

Hitachi Single-chip Microcomputer
H8/500 Series
Programming Manual



ADE-602-021A

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Preface

The H8/500 Family of Hitachi-original microcontrollers is built around a 16-bit CPU core that offers enhanced speed and a large address space. The CPU has a highly orthogonal general-register architecture and an optimized instruction set that efficiently executes programs coded in C language.

This manual describes the H8/500 instructions in detail, and is written for use with all chips in the H8/500 Family. For information on assembly-language coding, see the *H8/500 Series Cross Assembler User's Manual*.

For details on chip hardware, see the hardware manual for the particular chip.

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Section 1 CPU

1.1 Overview

The H8/500 CPU is a high-speed central processing unit designed for realtime control. It can be used as a CPU core in application-specific integrated circuits. It features eight 16-bit general registers, internal 16-bit data paths, and an optimized instruction set.

Section 1 summarizes the CPU architecture and instruction set.

1.1.1 Features

The main features of the H8/500 CPU are listed below.

- General-register machine
 - Eight 16-bit general registers
 - Seven control registers (two 16-bit registers, five 8-bit registers)
 - High speed: maximum 10MHz
 - At 10MHz a register-register add operation takes only 200ns.
 - Address space managed in 64K-byte pages, expandable to 16M bytes*
 - Simultaneous control is provided of four pages: a code page, stack page, data page, and extended page. Two address-space modes can be selected:
 - Minimum mode: Maximum 64K-byte address space
 - Maximum mode: Maximum 16M-byte address space*
 - Highly orthogonal instruction set
 - Addressing modes and data sizes can be specified independently within each instruction.
 - Optimized for efficient programming in C language
 - In addition to the general registers and orthogonal instruction set, the H8/500 CPU has short two-byte formats for frequently-used instructions and addressing modes.
- * The CPU architecture supports up to 16M bytes, but for specific chips the maximum address space is restricted by the number of external address lines (example: maximum 1M byte for the H8/532).

1.1.2 Data Structures

The H8/500 can process 1-bit data, 4-bit BCD data, 8-bit (byte) data, 16-bit (word) data, and 32-bit (longword) data.

Bit manipulation instructions operate on 1-bit data. Decimal arithmetic instructions operate on 4-bit BCD data. Almost all data transfer, shift, arithmetic, and logical operation instructions operate on byte and word data. Multiply and divide instructions operate on longword data.

Table 1-1 lists the data formats used in general registers. Table 1-2 lists the data formats used in memory.

(1) General Register Data Formats

Table 1-1 General Register Data Formats

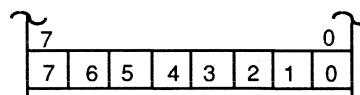
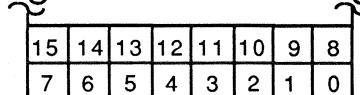
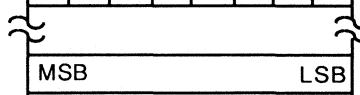
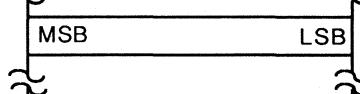
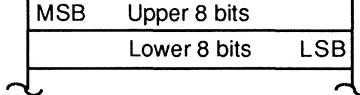
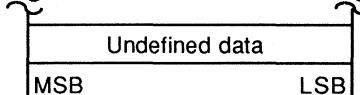
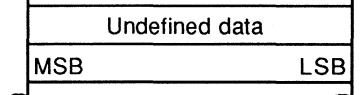
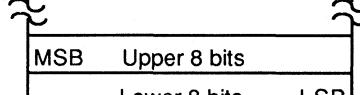
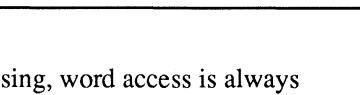
Data type	Register No.	Data structure														
1-Bit	Rn	15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0														
4-Bit BCD	Rn	15 8 7 4 3 0 Don't care Upper digit Lower digit														
Byte	Rn	15 8 7 0 Don't care MSB LSB														
Word	Rn	15 0 MSB LSB														
Longword	Rn* Rn+1*	31 16 MSB Upper word 15 0 Lower word LSB														

* For longword data n must be even (0, 2, 4, or 6).

(2) Data Formats in Memory

Access to word data in memory must always begin at an even address. Access to word data starting at an odd address causes an address error.

Table 1-2 Data Formats in Memory

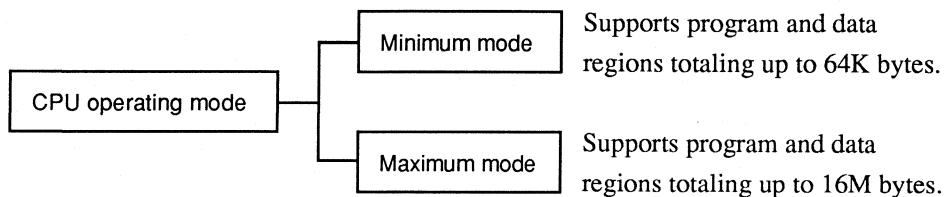
Data type	Data format
1-Bit (in byte operand)	Address n 
1-Bit (in word operand)	Even address  Odd address 
Byte	Address n 
Word	Even address  Odd address 
Byte in stack	Even address  Odd address 
Word in stack	Even address  Odd address 

Note: When the stack is accessed in exception processing, word access is always performed, regardless of the actual data size. Similarly, when the stack is accessed by an instruction using the @-R7 or @R7+ addressing mode, word access is performed regardless of the operand size specified in the instruction. An address error will therefore occur if the stack pointer indicates an odd address. Programs should be constructed so that the stack pointer always indicates an even address.

1.1.3 Address Space

The CPU has two modes: a minimum mode which supports an address space of up to 64K bytes, and a maximum mode which supports an address space of up to 16M bytes.

The mode is selected by input to the chip's mode pins. For details, see the *H8 Hardware Manual*.



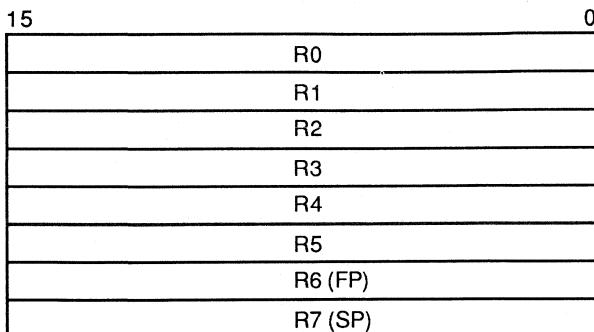
(1) Minimum Mode: Supports a maximum 64K-byte address space. The page register is ignored. Branching instructions that cross page boundaries (PJMP, PJSR, PRTS, and PRTD) are invalid.

(2) Maximum Mode: The page register is valid, supporting an address space of up to 16M bytes. The address space is not continuous, but is divided into 64K-byte pages. When a program crosses a page boundary, it must therefore use a page-crossing branching instruction or an interrupt. (It is recommended for a program to be contained in a single page.) When data access crosses a page boundary, the program must rewrite the page register before accessing the data.

1.1.4 Register Configuration

Figure 1-2 shows the register structure of the CPU. There are two groups of registers: the general registers (Rn) and the control registers (CR).

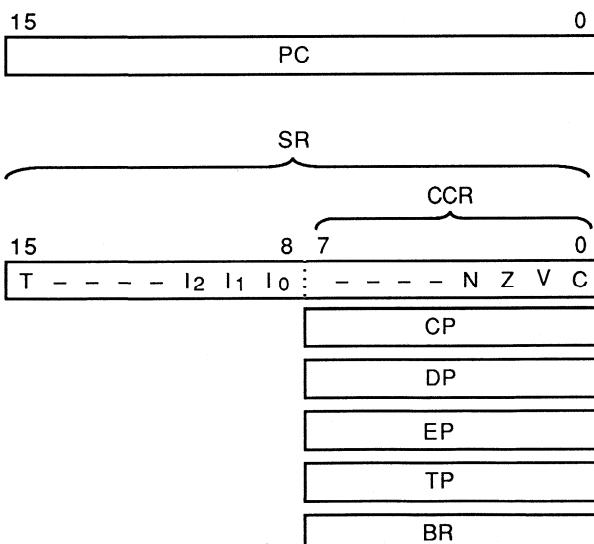
General registers (Rn)



FP: Frame Pointer

SP: Stack Pointer

Control registers (CR)



{ SR: Status Register
CCR: Condition Code Register

CP: Code Page register

DP: Data Page register

EP: Extended Page register

TP: Stack Page register

BR: Base Register

Figure 1-1 Registers in the CPU

1.2 Register Descriptions

1.2.1 General Registers

All eight of the 16-bit general registers are functionally alike; there is no distinction between data registers and address registers. When these registers are accessed as data registers, either byte or word size can be selected. R6 and R7, in addition to functioning as general registers, have special assignments.

R7 is the stack pointer, used implicitly in exception handling and subroutine calls. It is also used implicitly by the LDM and STM instructions, which load and store multiple registers from/to the stack and pre-decrement or post-increment R7 accordingly.

R6 functions as a frame pointer. High-level language compilers use R6 when they use instructions such as LINK and UNLK to reserve or release a stack frame.

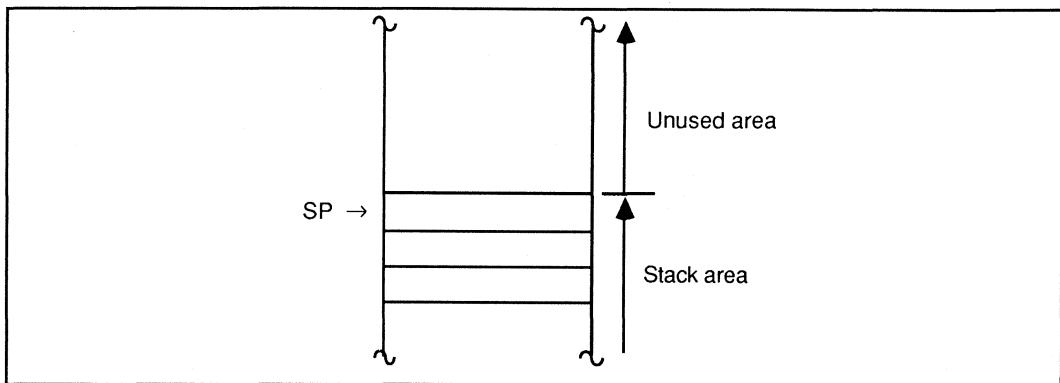


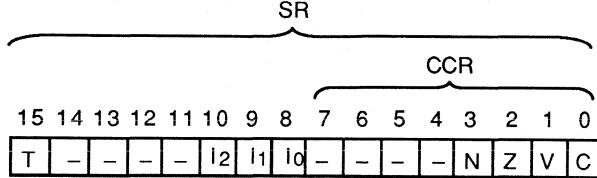
Figure 1-2 Stack Pointer (SP)

1.2.2 Control Registers

The control registers (CR) include a 16-bit program counter (PC), a 16-bit status register (SR) containing an 8-bit condition code register (CCR), four 8-bit page registers, and one 8-bit base register (BR).

The page registers are used only in the maximum mode. They are ignored in the minimum mode.

- (1) Program Counter (PC):** This 16-bit register indicates the address of the next instruction the CPU will execute.
- (2) Status Register/Condition Code Register (SR/CCR):** This 16-bit register indicates the internal state of the CPU. The lower half of the status register is referred to as the condition code register (CCR): its 8 bits can be accessed as a 1-byte condition code.



Bit 15—Trace (T): When this bit is set to "1," the CPU operates in trace mode and generates a trace exception after every instruction. When this bit is cleared to "0" instructions are executed in normal continuous sequence. This bit is cleared to "0" at a reset.

Bits 14 to 11—Reserved: These bits cannot be written, and when read, are always read as "0."

Bits 10 to 8—Interrupt mask (I₂ to I₀): These bits indicate the interrupt request mask level (0 to 7). As shown in 3, an interrupt request is not accepted unless it has a higher level than the value of the mask. A nonmaskable interrupt (NMI), which has level 8, is always accepted, regardless of the mask level.

4 indicates the values of the I bits after an interrupt is accepted. When an interrupt is accepted, the value of bits I₂ to I₀ is raised to the same level as the interrupt, to prevent a further interrupt from being accepted unless its level is higher.

A reset sets all three of bits (I₂, I₁, and I₀) to "1."

Table 1-3 Interrupt Mask Levels

Priority	Level	Interrupt mask			Interrupts accepted
		I ₂	I ₁	I ₀	
High	7	1	1	1	NMI
	6	1	1	0	Level 7 and NMI
	5	1	0	1	Levels 6 to 7 and NMI
	4	1	0	0	Levels 5 to 7 and NMI
	3	0	1	1	Levels 4 to 7 and NMI
	2	0	1	0	Levels 3 to 7 and NMI
	1	0	0	1	Levels 2 to 7 and NMI
	0	0	0	0	Levels 1 to 7 and NMI

Table 1-4 Interrupt Mask Bits after an Interrupt is Accepted

Level of interrupt accepted	I ₂	I ₁	I ₀
NMI (8)	1	1	1
7	1	1	1
6	1	1	0
5	1	0	1
4	1	0	0
3	0	1	1
2	0	1	0
1	0	0	1

Bits 7 to 4—Reserved: These bits cannot be written, and when read, are always read as "0."

Bit 3—Negative (N): This bit indicates the most significant bit (sign bit) of the result of an instruction.

Bit 2—Zero (Z): This bit is set to "1" to indicate a zero result and cleared to "0" to indicate a nonzero result.

Bit 1—Overflow (V): This bit is set to "1" when an arithmetic overflow occurs, and cleared to "0" at other times.

Bit 0—Carry (C): This bit is set to "1" when a carry or borrow occurs at the most significant bit, and is cleared to "0" (or left unchanged) at other times.

The specific changes that occur in the condition code bits when each instruction is executed are detailed in the instruction descriptions in Section 2.2.1 and listed in Tables 2-7 (1) to (4) in Section 2.5, "Condition Code Changes."

(3) Code Page Register (CP): The code page register and the program counter combine to generate a 24-bit program code address, thereby expanding the program area. The code page register contains the upper 8 bits of the 24-bit address.

In the maximum mode, both the code page register and program counter are saved and restored in exception handling, and a new code page value is loaded from the exception vector table.

(4) Data Page Register (DP): The data page register combines with general registers R0 to R3 to generate a 24-bit effective address, thereby expanding the data area. The data page register contains the upper 8 bits of the 24-bit effective address. The data page register is used to calculate effective addresses in the register indirect addressing mode using R0 to R3, and in the 16-bit absolute addressing mode (@aa:16).

(5) Extended Page Register (EP): The extended page register combines with general register R4 or R5 to generate a 24-bit effective address, thereby expanding the data area. The extended page register contains the upper 8 bits of the 24-bit address. It is used to calculate effective addresses in the register indirect addressing mode using R4 or R5.

(6) Stack Page Register (TP): The stack page register combines with R6 (Frame pointer) or R7 (Stack pointer) to generate a 24-bit stack address, thereby expanding the stack area. The stack page register contains the upper 8 bits of the 24-bit stack address. It is used to calculate effective addresses in the register indirect addressing mode using R6 or R7.

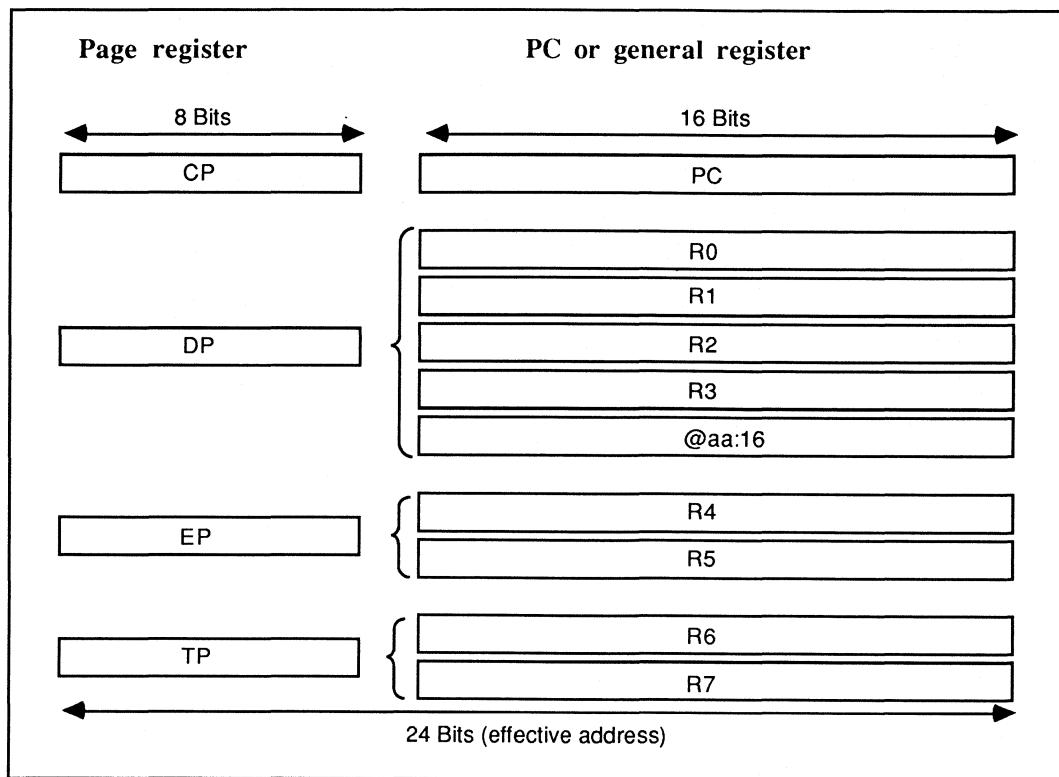


Figure 1-3 Combinations of Page Registers and PC or General Registers

(7) **Base Register (BR):** This register stores the base address used in the short absolute addressing mode (@aa:8). In the short absolute addressing mode a 16-bit operand address is generated by using the contents of the base register as the upper 8 bits and the address given in the instruction code as the lower 8 bits. The page is always page 0 in the short absolute addressing mode.

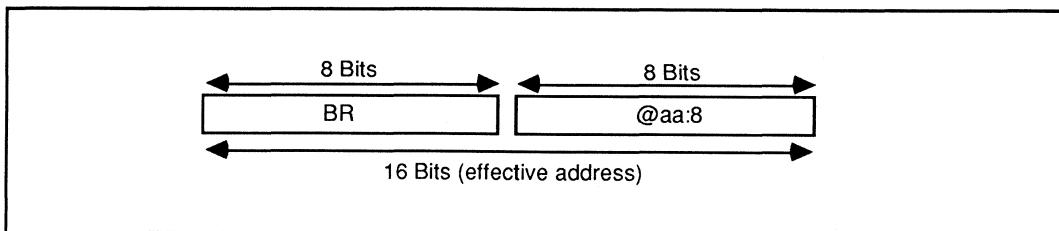


Figure 1-4 Base Register

1.2.3 Initial Register Values

When the CPU is reset, its internal registers are initialized as shown in Table 1-5.

Table 1-5 Initial Values of CPU Registers

Register	Initial value	
	Minimum mode	Maximum mode
General registers		
15 R0 – R7	0 Undetermined	Undetermined
Control registers		
15 PC	0 Loaded from vector table	Loaded from vector table
SR		
15 T - - - I ₂ I ₁ I ₀ : - - - N Z V C	H'070 * (N, Z,V and C are undetermined)	H'070 * (N, Z,V and C are undetermined)
7 CP	0 Undetermined	Loaded from vector table
7 DP	0 Undetermined	Undetermined
7 EP	0 Undetermined	Undetermined
7 TP	0 Undetermined	Undetermined
7 BR	0 Undetermined	Undetermined

1.3 Instruction Set

The main features of the CPU instruction set are:

- A general-register architecture.
- Orthogonality. Addressing modes and data sizes can be specified independently in each instruction.
- 1.5-type addressing (register-register and register-memory operations)
- Affinity for high-level languages, particularly C.
- Short formats for frequently-used instructions and addressing modes.

1.3.1 Types of Instructions

The CPU instruction set includes 63 types of instructions, listed by function in Table 1-6. Detailed descriptions are given starting in Section 2.2.1.

Table 1-6 Instruction Classification

Function	Instructions	Types
Data transfer	MOV, LDM, STM, XCH, SWAP, MOVTPE, MOVFPE	7
Arithmetic operations	ADD, SUB, ADDS, SUBS, ADDX, SUBX, DADD, DSUB, MULXU, DIVXU, CMP, EXTS, EXTU, TST, NEG, CLR, TAS	17
Logic operations	AND, OR, XOR, NOT	4
Shift	SHAL, SHAR, SHLL, SHLR, ROTL, ROTR, ROTXL, ROTXR	8
Bit manipulation	BSET, BCLR, BTST, BNOT	4
Branch	Bcc*, JMP, PJMP, BSR, JSR, PJSR, RTS, PRTS, RTD, PRTD, SCB (/F, /NE, /EQ)	11
System control	TRAPA, TRAP/VIS, RTE, SLEEP, LDC, STC, ANDC, ORC, XORC, NOP, LINK, UNLK	12
	Total	63

*: Bcc is the generic name of the conditional branch instructions.

1.3.2 Instructions Listed by Function

Tables 1-7 (1) to (6) give a concise summary of the instructions in each functional category. The notation used in these tables is listed below.

Operation Notation

Rd	General register (destination)
Rs	General register (source)
Rn	General register
(EAd)	Destination operand
(EAs)	Source operand
CCR	Condition code register
N	N (negative) bit of CCR
Z	Z (zero) bit of CCR
V	V (overflow) bit of CCR
C	C (carry) bit of CCR
CR	Control register
PC	Program counter
CP	Code page register
SP	Stack pointer
FP	Frame pointer
#IMM	Immediate data
disp	Displacement
+	Addition
-	Subtraction
×	Multiplication
÷	Division
^	AND logical
∨	OR logical
⊕	Exclusive OR logical
→	Move
↔	Exchange
¬	Not

Table 1-7 Instructions Listed by Function (1)

Instruction	Size^{*2}	Function
Data transfer	MOV MOV : G B/W MOV : E B MOV : I W MOV : F B/W MOV : L B/W MOV : S B/W	(EAs) → (EAd), #IMM → (EAd) Moves data between two general registers, or between a general register and memory, or moves immediate to a general register or memory.
	LDM W	Stack → Rn (register list) Pops data from the stack to one or more registers.
	STM W	Rn (register list) → stack Pushes data from one or more registers onto the stack.
	XCH W	Rs ↔ Rd Exchanges data between two general registers.
	SWAP B	Rd (upper byte) ↔ Rd (lower byte) Exchanges the upper and lower bytes in a general register.
	MOVTPPE ^{*1} B	Rn → (EAd) Transfers data from a general register to memory in synchronization with the E clock.
	MOVFPE ^{*1} B	(EAs) → Rd Transfers data from memory to a general register in synchronization with the E clock.

Notes:

*1 Do not use the MOVTPPE and MOVFPE instructions with the H8/520, which has no E-clock output pin.

*2 B: byte

W: word

Table 1-7 Instructions Listed by Function (2)

Instruction	Size	Function
Arithmetic operations	ADD	$Rd \pm (EAs) \rightarrow Rd, (EAd) \pm \#IMM \rightarrow (EAd)$
	ADD : G B/W	Performs addition or subtraction on data in two general registers or a general register and memory, or on immediate data and data in a general register or memory.
	ADD : Q B/W	
	SUB B/W	
	ADDS B/W	
	SUBS B/W	
	ADDX B/W	$Rd \pm (EAs) \pm C \rightarrow Rd$
	SUBX B/W	Performs addition or subtraction with carry or borrow on data in two general registers or a general register and memory, or on immediate data and data in a general register .
	DADD B	$(Rd)_{10} \pm (Rs)_{10} \pm C \rightarrow (Rd)_{10}$
	DSUB B	Performs decimal addition or subtraction on data in two general registers.
MULXU	B/W	$Rd \times (EAs) \rightarrow Rd$ Performs 8-bit \times 8-bit or 16-bit \times 16-bit unsigned multiplication on data in a general register and data in another general register or memory, or on data in a general register and immediate data.
DIVXU	B/W	$Rd \div (EAs) \rightarrow Rd$ Performs 16-bit \div 8-bit or 32-bit \div 16-bit unsigned division on data in a general register and data in another general register or memory, or on data in a general register and immediate data.
CMP		$Rd - (EAs), (EAd) - \#IMM$
	CMP : G B/W	Compares data in a general register with data in another general register or memory, or with immediate data, or compares immediate data with data in memory.
	CMP : E B	
	CMP : I W	
EXTS	B	$(\text{<bit 7> of } <Rd>) \rightarrow (\text{<bits 15 to 8> of } <Rd>)$ Converts byte data in a general register to word data by extending the sign bit.

Table 1-7 Instructions Listed by Function (3)

Instruction	Size	Function
Arithmetic operations	EXTU	B $0 \rightarrow (\text{bits } 15 \text{ to } 8 \text{ of } \langle Rd \rangle)$ Converts byte data in a general register to word data by padding with zero bits.
	TST	B/W $(EAd) - 0$ Compares general register or memory contents with 0.
	NEG	B/W $0 - (EAd) \rightarrow (EAd)$ Obtains the two's complement of general register or memory contents.
	CLR	B/W $0 \rightarrow (EAd)$ Clears general register or memory contents to 0.
	TAS	B $(EAd) - 0, (1)_2 \rightarrow (\text{bit } 7 \text{ of } \langle EAd \rangle)$ Tests general register or memory contents, then sets the most significant bit (bit 7) to "1."
Logical operations	AND	B/W $Rd \wedge (EAs) \rightarrow Rd$ Performs a logical AND operation on a general register and another general register, memory, or immediate data.
	OR	B/W $Rd \vee (EAs) \rightarrow Rd$ Performs a logical OR operation on a general register and another general register, memory, or immediate data.
	XOR	B/W $Rd \oplus (EAs) \rightarrow Rd$ Performs a logical exclusive OR operation on a general register and another general register, memory, or immediate data.
	NOT	B/W $\neg(EAd) \rightarrow (EAd)$ Obtains the one's complement of general register or memory contents.

Table 1-7 Instructions Listed by Function (4)

Instruction	Size	Function
Shift operations	SHAL SHAR	B/W (EAd) shift → (EAd) Performs an arithmetic shift operation on general register or memory contents.
	SHLL SHLR	B/W (EAd) shift → (EAd) Performs a logical shift operation on general register or memory contents.
	ROTL ROTR	B/W (EAd) rotate → (EAd) Rotates general register or memory contents.
	ROTXL ROTXR	B/W (EAd) rotate with carry → (EAd) Rotates general register or memory contents through the C (carry) bit.
Bit manipulations	BSET BCLR BNOT BTST	B/W ¬(<bit-No.> of <EAd>) → Z, 1 → (<bit-No.> of <EAd> Tests a specified bit in a general register or memory, then sets the bit to "1." The bit is specified by a bit-number given in immediate data or a general register. ¬(<bit-No.> of <EAd>) → Z, 0 → (<bit-No.> of <EAd> Tests a specified bit in a general register or memory, then clears the bit to "0." The bit is specified by a bit-number given in immediate data or a general register. ¬(<bit-No.> of <EAd>) → Z, → (<bit-No.> of <EAd> Tests a specified bit in a general register or memory, then inverts the bit. The bit is specified by a bit-number given in immediate data or a general register. ¬(<bit-No.> of <EAd>) → Z, Tests a specified bit in a general register or memory. The bit is specified by a bit-number given in immediate data or a general register.

Table 1-7 Instructions Listed by Function (5)

Instruction	Size	Function																																																						
Branch	BCC	— Branches if condition is true.																																																						
		<table> <thead> <tr> <th>Mnemonic</th><th>Description</th><th>Condition</th></tr> </thead> <tbody> <tr> <td>BRA (BT)</td><td>Always (true)</td><td>True</td></tr> <tr> <td>BRN (BF)</td><td>Never (false)</td><td>False</td></tr> <tr> <td>BHI</td><td>High</td><td>$C \vee Z = 0$</td></tr> <tr> <td>BLS</td><td>Low or Same</td><td>$C \vee Z = 1$</td></tr> <tr> <td>BCC (BHS)</td><td>Carry Clear</td><td>$C = 0$</td></tr> <tr> <td></td><td></td><td>(High or Same)</td></tr> <tr> <td>BCS (BLO)</td><td>Carry Set (Low)</td><td>$C = 1$</td></tr> <tr> <td>BNE</td><td>Not Equal</td><td>$Z = 0$</td></tr> <tr> <td>BEQ</td><td>Equal</td><td>$Z = 1$</td></tr> <tr> <td>BVC</td><td>Overflow Clear</td><td>$V = 0$</td></tr> <tr> <td>BVS</td><td>Overflow Set</td><td>$V = 1$</td></tr> <tr> <td>BPL</td><td>Plus</td><td>$N = 0$</td></tr> <tr> <td>BMI</td><td>Minus</td><td>$N = 1$</td></tr> <tr> <td>BGE</td><td>Greater or Equal</td><td>$N \oplus V = 0$</td></tr> <tr> <td>BLT</td><td>Less Than</td><td>$N \oplus V = 1$</td></tr> <tr> <td>BGT</td><td>Greater Than</td><td>$Z \vee (N \oplus V) = 0$</td></tr> <tr> <td>BLE</td><td>Less or Equal</td><td>$Z \vee (N \oplus V) = 1$</td></tr> </tbody> </table>	Mnemonic	Description	Condition	BRA (BT)	Always (true)	True	BRN (BF)	Never (false)	False	BHI	High	$C \vee Z = 0$	BLS	Low or Same	$C \vee Z = 1$	BCC (BHS)	Carry Clear	$C = 0$			(High or Same)	BCS (BLO)	Carry Set (Low)	$C = 1$	BNE	Not Equal	$Z = 0$	BEQ	Equal	$Z = 1$	BVC	Overflow Clear	$V = 0$	BVS	Overflow Set	$V = 1$	BPL	Plus	$N = 0$	BMI	Minus	$N = 1$	BGE	Greater or Equal	$N \oplus V = 0$	BLT	Less Than	$N \oplus V = 1$	BGT	Greater Than	$Z \vee (N \oplus V) = 0$	BLE	Less or Equal	$Z \vee (N \oplus V) = 1$
Mnemonic	Description	Condition																																																						
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		(High or Same)																																																						
BCS (BLO)	Carry Set (Low)	$C = 1$																																																						
BNE	Not Equal	$Z = 0$																																																						
BEQ	Equal	$Z = 1$																																																						
BVC	Overflow Clear	$V = 0$																																																						
BVS	Overflow Set	$V = 1$																																																						
BPL	Plus	$N = 0$																																																						
BMI	Minus	$N = 1$																																																						
BGE	Greater or Equal	$N \oplus V = 0$																																																						
BLT	Less Than	$N \oplus V = 1$																																																						
BGT	Greater Than	$Z \vee (N \oplus V) = 0$																																																						
BLE	Less or Equal	$Z \vee (N \oplus V) = 1$																																																						
		(\vee = Logic OR)																																																						
JMP	—	Branches unconditionally to a specified address in the same page.																																																						
PJMP	—	Branches unconditionally to a specified address in a specified page.																																																						
BSR	—	Branches to a subroutine at a specified address in the same page.																																																						
JSR	—	Branches to a subroutine at a specified address in the same page.																																																						
PJSR	—	Branches to a subroutine at a specified address in a specified page.																																																						
RTS	—	Returns from a subroutine in the same page.																																																						

Table 1-7 Instructions Listed by Function (6)

Instruction	Size	Function
Branch	PRTS	— Returns from a subroutine in a different page.
	RTD	— Returns from a subroutine in the same page and adjusts the stack pointer.
	PRTD	— Returns from a subroutine in a different page and adjusts the stack pointer.
	SCB/F	— Controls a loop using a loop counter and/or a specified.
	SCB/NE	— CCR termination condition.
	SCB/EQ	—
System control	TRAPA	— Generates a trap exception with a specified vector number.
	TRAP/V\$	— Generates a trap exception if the V bit is set when the instruction is executed.
	RTE	— Returns from an exception-handling routine.
	LINK	— $FP \rightarrow @-SP; SP \rightarrow FP; SP + \#IMM \rightarrow SP$ Creates a stack frame.
	UNLK	— $FP \rightarrow SP; @SP+ \rightarrow FP$ Deallocates a stack frame created by the LINK instruction.
	SLEEP	— Causes a transition to the power-down state.
	LDC	B/W* (EAs) → CR Moves immediate data or general register or memory contents to a specified control register.
	STC	B/W* CR → (EAd) Moves control register data to a specified general register or memory location.
	ANDC	B/W* CR \wedge #IMM → CR Logically ANDs a control register with immediate data.
	ORC	B/W* CR \vee #IMM → CR Logically ORs a control register with immediate data.
	XORC	B/W* CR \oplus #IMM → CR Logically exclusive-ORs a control register with immediate data.
	NOP	— PC + 1 → PC No operation. Only increments the program counter.

* The size depends on the control register.

1.3.3 Short Format Instructions

The ADD, CMP, and MOV instructions have special short formats. Table 1-8 lists these short formats together with the equivalent general formats.

The short formats are a byte shorter than the corresponding general formats, and most of them execute one state faster.

Table 1-8 Short-Format Instructions and Equivalent General Formats

Short-format instruction	Length	Execution states *2	Equivalent general-format instruction	Length	Execution states *2
ADD:Q #xx,Rd *1	2	2	ADD:G #xx:8,Rd	3	3
CMP:E #xx:8,Rd	2	2	CMP:G.B #xx:8,Rd	3	3
CMP:I #xx:16,Rd	3	3	CMP:G.W #xx:16,Rd	4	4
MOV:E #xx:8,Rd	2	2	MOV:G.B #xx:8,Rd	3	3
MOV:I #xx:16,Rd	3	3	MOV:G.W #xx:16,Rd	4	4
MOV:L @aa:8,Rd	2	5	MOV:G @aa:8,Rd	3	5
MOV:S Rs,@aa:8	2	5	MOV:G Rs,@aa:8	3	5
MOV:F @ (d:8,R6),Rd	2	5	MOV:G @ (d:8,R6),Rd	3	5
MOV:F Rs,@ (d:8,R6)	2	5	MOV:G Rs,@ (d:8,R6)	3	5

Notes:

*1 The ADD:Q instruction accepts other destination operands in addition to a general register, but the immediate data value (#xx) is limited to ± 1 or ± 2 .

*2 Number of execution states for access to on-chip memory. For the H8/510, the number of execution states for general register access.

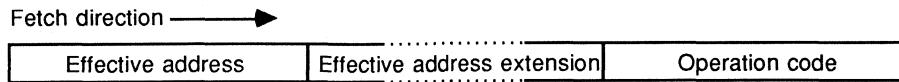
1.3.4 Basic Instruction Formats

There are two basic CPU instruction formats: the general format and the special format.

(1) General format: This format consists of an effective address (EA) field, an effective address extension field, and an operation code (OP) field. It is used in arithmetic instructions and other general instructions.

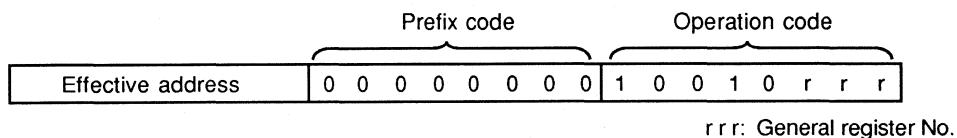
- Effective address field: One byte containing information used to calculate the effective address of an operand.

- Effective address extension: Zero to two bytes containing a displacement value, immediate data, or an absolute address.
- Operation code: Defines the operation to be carried out on the operand located at the address calculated from the effective address information. Each instruction has a unique operation code.



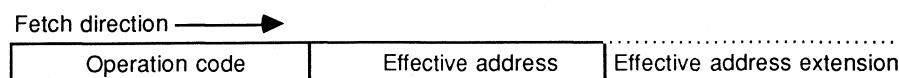
Note: Some instructions (DADD, DSUB, MOVFPE, MOVTPE) have an extended format in which the operand code is preceded by a one-byte prefix code.

(Example: MOVTPE instruction)



(2) Special format: In this format the operation code comes first, followed by the effective address field and effective address extension. This format is used in branching instructions, system control instructions, and other instructions that can be executed faster if the operation to be performed on the operand is specified first.

- Operation code: One or two bytes defining the operation to be performed by the instruction.
- Effective address field and effective address extension: Zero to three bytes containing information used to calculate the effective address of an operand.



1.3.5 Addressing Modes and Effective Address Calculation

The CPU supports the seven addressing modes listed in Table 1-9 below. Due to the highly orthogonal nature of the instruction set, most instructions having operands can use any applicable addressing mode from 1 through 6. Mode 7 is used by branching instructions.

Table 1-9 explains how the effective address (EA) is calculated in each addressing mode.

Table 1-9 Addressing Modes

No.	Addressing mode	Mnemonic	Effective Address and Extension	Bytes
1	Register direct	Rn	1010 Sz rrr *1, *2	1
2	Register indirect	@Rn	1101 Sz rrr	1
3	Register indirect with displacement	@(d:8,Rn) @(d:16,Rn)	1110 Sz rrr disp 1111 Sz rrr disp (H) disp (L)	2 3
4	Register indirect with pre-decrement Register indirect with post-increment	@-Rn @Rn+	1011 Sz rrr	1
5	Absolute address *3	@aa:8 @aa:16	0000 Sz 101 addr (L) 0001 Sz 101 addr (H) addr (L)	2 3
6	Immediate	#xx:8 #xx:16	00000 100 data 00001 100 data (H) data (L)	2 3
7	PC-relative	disp	Effective address information is specified in the operation code.	1 or 2

Notes:

*1 Sz: Operand size

Sz = 0: byte operand

Sz = 1: word operand

*2 rrr (register number field): General register number

000: R0 001: R1 010: R2 011: R3

100: R4 101: R5 110: R6 111: R7

*3 The @aa:8 addressing mode may be referred to as the short absolute addressing mode.

Table 1-10 Effective Address Calculation (1)

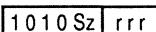
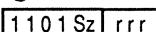
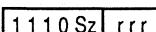
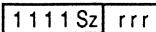
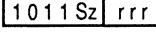
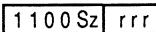
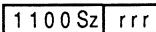
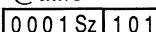
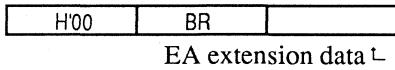
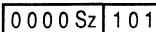
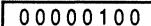
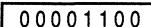
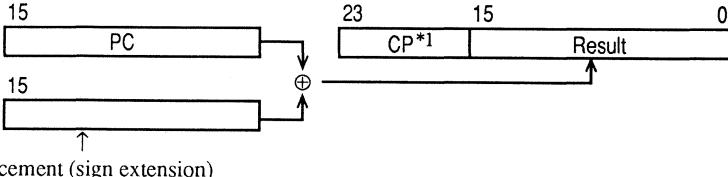
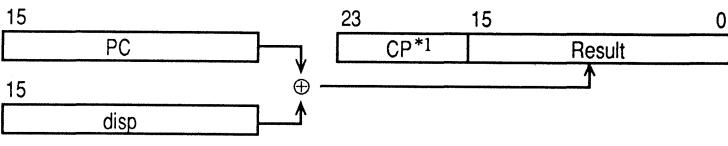
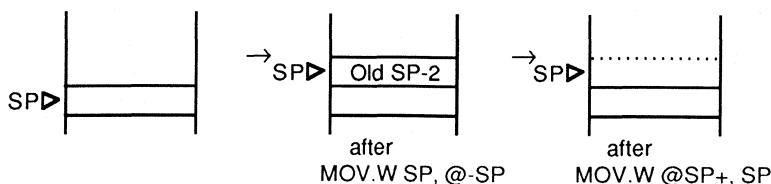
No.	Addressing mode	Effective address calculation	Effective address
1	Register direct Rn	None	Operand is contents of Rn. 
2	Register indirect @Rn	None	 23 15 0 DP/TP/EP *1 Rn *2
3	Register indirect with displacement @(d:8,Rn)	8 bit  15 Rn contents 15 + disp (sign extention) Result	 15 Rn contents 15 + disp Result
4	① Register indirect with pre-decrement @-Rn	15 Rn contents 15 - 1 or 2 Result Rn is decremented by -1 or -2 before instruction execution.*3, *4, *5	 23 15 0 DP/TP/EP *1 Rn *2
	② Register indirect with post-increment @Rn+	None  Rn is incremented by +1 or +2 after instruction execution.*3, *4, *5	 23 15 0 DP/TP/EP *1 Rn *2
5	Absolute address @aa:8	None 	 23 15 0 H'00 BR EA extension data
	@aa:16	None 	 23 15 0 DP*1 EA extension data

Table 1-10 Effective Address Calculation (2)

No.	Addressing mode	Effective address calculation	Effective address
6	Immediate #xx:8	None	Operand is 1-byte EA extension data. 
	#xx:16	None	Operand is 2-byte EA extension data 
7	PC-relative d:8	8 Bits	
	d:16	16 Bits	

Notes:

1. The page register is ignored in the minimum mode.
2. In addressing modes No. 2, 3, and 4, the page register is as follows:
 DP for register-indirect addressing with R0, R1, R2, or R3.
 EP for register-indirect addressing with R4 or R5.
 TP for register indirect addressing with R6 or R7.
3. Increment (Decrement) by 1 for a byte operand, and by 2 for a word operand.
4. In addressing mode No. 4 (register indirect with pre-decrement or post-increment), when register R7 is specified the increment or decrement is always ± 2 , even when operand size is 1 byte.
5. If SP is saved by @-SP addressing mode and popped by @SP+, the result will be as follows.



1.3.6 Register Specification

(1) General Register Specification: General registers are specified by a three-bit register number contained in the instruction code. Another bit may be used to indicate whether a register operand is a byte or word operand. See Table 1-11.

Table 1-11 General Register Specification

EA field	OP field	
* * * * Sz	ri ri ri	* * * * * rj rj rj

EA: Effective address
 OP: Operation code
 Sz: Size (byte/word)
 ri ri ri / rj rj rj: General register number

ri ri ri / rj rj rj	Sz = 0 (Byte)	Sz = 1 (Word)			
0 0 0	15 8 7 0 <table border="1" style="display: inline-table; vertical-align: top;"> <tr><td>Not used</td><td>R0</td></tr> </table>	Not used	R0	15 0 <table border="1" style="display: inline-table; vertical-align: top;"> <tr><td>R0</td></tr> </table>	R0
Not used	R0				
R0					
0 0 1	Not used R1	R1			
0 1 0	Not used R2	R2			
0 1 1	Not used R3	R3			
1 0 0	Not used R4	R4			
1 0 1	Not used R5	R5			
1 1 0	Not used R6	R6			
1 1 1	Not used R7	R7			

(2) **Control Register Specification:** Control registers are specified by a control register number embedded in the operation code byte. See Table 1-12.

Table 1-12 Control Register Specification

EA field	OP field	c c c: Control register number field	
		Sz = 0 (Byte)	Sz = 1 (Word)
Effective address	* * * * * ccc	0 0 0 7 0 0 0 1 0 1 0 0 1 1 1 0 0 1 0 1 1 1 0 1 1 1	(Not allowed*) CCR (Not allowed) BR EP DP (Not allowed) TP 15 0 SR (Not allowed) (Not allowed) (Not allowed) (Not allowed) (Not allowed) (Not allowed) (Not allowed)

* Control register numbers indicated as "(Not allowed)" should not be used, because they may cause the CPU to malfunction.

Section 2 Instruction Set: Detailed Descriptions

2.1 Table Format and Notation

Each instruction is described in a table with the following format:

Name	Mnemonic
<Operation>	<Condition Code>
<hr/> <Assembly-Language Format> <hr/>	
<hr/> <Operand Size> <hr/>	
<hr/> <Description> <hr/>	
<hr/> <Instruction Format> <hr/>	
<hr/> <Addressing Modes> <hr/>	

Name: A name indicating the function of the instruction.

Mnemonic: The assembly-language mnemonic of the instruction.

Operation: A concise, symbolic indication of the operation performed by the instruction. The notation used is listed on the next page.

Operation notation

Rd	General register (destination)
Rs	General register (source)
Rn	General register
(EAd)	Destination operand
(EAs)	Source operand
CCR	Condition code register
N	N (negative) bit of CCR
Z	Z (zero) bit of CCR
V	V (overflow) bit of CCR
C	C (carry) bit of CCR
CR	Control register
PC	Program counter
CP	Code page register
SP	Stack pointer

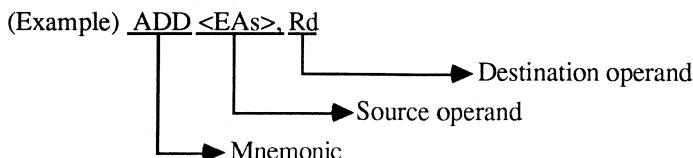
FP	Frame pointer
#IMM	Immediate data
disp	Displacement
+	Addition
-	Subtraction
×	Multiplication
÷	Division
^	AND logical
∨	OR logical
⊕	Exclusive OR logical
→	Move
↔	Exchange
¬	Not

Condition code: Changes in the condition code (N, Z, V, C) after instruction execution are indicated by the following symbols:

- : Not changed.
- *: Undetermined
- †: Changed according to the result of the instruction.
- 0: Always cleared to "0."
- 1: Always set to "1."
- Δ: Handling depends on the operand.

Section 2.5, "Condition Code Changes," lists these changes with explicit formulas showing how the bit values are derived.

Assembly-language format: The assembly-language coding of the instruction is indicated as below.

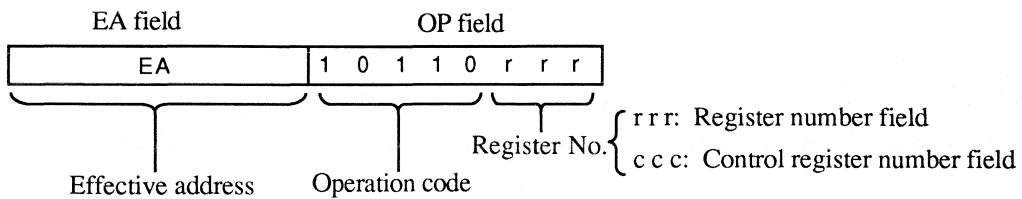


For details on assembly-language notation, see the *H8/500 Series Cross Assembler Manual*.

Operand size: The available operand sizes are indicated.

Description: A detailed description of the instruction.

Instruction format: The machine-language instruction format, including the effective address, is indicated as shown below.



No.	Addressing mode	Mnemonic	Effective address and extension	Bytes
1	Register direct	Rn	1010Szrrrr	1
2	Register indirect	@Rn	1101Szrrrr	1
3	Register indirect with displacement	@(d:8,Rn) @(d:16,Rn)	1110Szrrrr disp 1111Szrrrr disp (H) disp (L)	2 3
4	Register indirect with pre-decrement Register indirect with post-increment	@-Rn @Rn+	1011Szrrrr 1100Szrrrr	1 1
5	Absolute address*	@aa:8 @aa:16	0000Sz101 addr (L) 0001Sz101 addr (H) addr (L)	2 3
6	Immediate	#xx:8 #xx:16	00000100 data 00001100 data (H) data (L)	2 3
7	PC-relative	disp	Effective address information is specified in the operation code.	1 or 2

* The @aa:8 addressing mode may be referred to as the short absolute addressing mode.

Addressing modes: The addressing modes that can be specified for the source and destination operands are indicated in a table like the one below. "Yes" means that the mode can be used; "—" means that it cannot.

(Example: ADD instruction)

	Rn	@Rn	@(d:8,Rn)	@(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16
Source	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Destination	Yes	—	—	—	—	—	—	—	—	—

Symbol	Meaning
Rn	Register direct
@Rn	Register indirect
@(d:8,Rn)	Register indirect with 8-bit displacement
@(d:16,Rn)	Register indirect with 16-bit displacement
@-Rn	Register indirect with pre-decrement
@Rn+	Register indirect with post-increment
@aa:8	Short absolute address (8 bits)
@aa:16	Absolute address (16 bits)
#xx:8	Immediate (8 bits)
#xx:16	Immediate (16 bits)

2.2 Instruction Descriptions

The individual instructions are described starting in Section 2.2.1.

2.2.1 ADD

(1) ADD:G (ADD, General format)

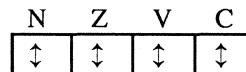
ADD Binary

<Operation>

Rd + (EAs) → Rd

ADD:G

<Condition Code>



<Assembly-Language Format>

ADD:G <EAs>, Rd

(Example)

- (1) ADD:G.B R0, R1
- (2) ADD.B R0, R1*

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Set to "1" if an overflow occurs;
otherwise cleared to "0."

C: Set to "1" if a carry occurs; otherwise
cleared to "0."

<Operand Size>

Byte

Word

<Description>

This instruction adds the source operand to the contents of general register Rd (destination operand) and places the result in general register Rd.

When the source operand is the immediate data ± 1 or ± 2 , the ADD:Q instruction in Section 2.2.1 (2) can be used. The ADD:Q instruction is shorter and executes more quickly.

<Instruction Format>

EA	0 0 1 0 0 r r r
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.1 (2) ADD:Q (ADD Quick, short format)

ADD Quick

<Operation>

(EAd) + #IMM → (EAd)

<Assembly-Language Format>

ADD:Q #xx, <EAd>

(Example)

(1) ADD:Q.W #1, @R0

(2) ADD.W #1, @R0*

<Operand Size>

Byte

Word

ADD:Q

<Condition Code>

N	Z	V	C
↑	↑	↑	↑

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Set to "1" if an overflow occurs;
otherwise cleared to "0."

C: Set to "1" if a carry occurs; otherwise
cleared to "0."

<Description>

This instruction adds immediate data to the destination operand and places the result in the destination operand.

The values ±1 and ±2 can be specified as immediate data.

<Instruction Format>

ADD:Q #1, <EAd>	EA	0 0 0 0 1 0 0 0
ADD:Q #2, <EAd>	EA	0 0 0 0 1 0 0 1
ADD:Q #-1, <EAd>	EA	0 0 0 0 1 1 0 0
ADD:Q #-2, <EAd>	EA	0 0 0 0 1 1 0 1

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

- * In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.2 ADDS (ADD with Sign extension)

ADD with Sign extension

<Operation>

Rd + (EAs) → Rd

ADDS

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

ADDS <EAs>, Rd

(Example)

ADDS.W #H'10, R3

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction adds the source operand to the contents of general register Rd (destination operand) and places the result in general register Rd.

Differing from the ADD instruction, this instruction does not alter the condition code.

If byte size is specified, the sign bit of the source operand is extended. The addition is performed using the resulting word data. General register Rd is always accessed as a word-size operand.

<Instruction Format>

EA	0 0 1 0 1 r r r
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
--------	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

Destination	Yes	—	—	—	—	—	—	—	—	—
-------------	-----	---	---	---	---	---	---	---	---	---

2.2.3 ADDX (ADD with eXtend carry)

ADD with eXtend carry

<Operation>

$Rd + (EAs) + C \rightarrow Rd$

<Assembly-Language Format>

ADDX <EAs>, Rd

(Example)

ADDX.B @ (H'20, R4), R0

ADDX

<Condition Code>

N	Z	V	C
↑	↑	↑	↑

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" if the previous Z bit value
was "1" and the result of the
instruction is zero; otherwise cleared
to "0."

V: Set to "1" if an overflow occurs;
otherwise cleared to "0."

C: Set to "1" if a carry occurs; otherwise
cleared to "0."

<Operand Size>

Byte

Word

<Description>

This instruction adds the source operand and the C bit to the contents of general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	1	0	1	0	0	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.4 AND (AND logical)

AND logical

AND

<Operation>

<Condition Code>

$Rd \wedge (EAs) \rightarrow Rd$

N	Z	V	C
↑	↑	0	—

<Assembly-Language Format>

AND <EAs>, Rd

N: Set to "1" when the MSB of the result is "1;" otherwise cleared to "0."

(Example)

Z: Set to "1" when the result is zero; otherwise cleared to "0."

AND .B @H'F8:8, R1

V: Always cleared to 0.

<Operand Size>

C: Previous value remains unchanged.

Byte

Word

<Description>

This instruction obtains the logical AND of the source operand and the contents of general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	0	1	0	1	0	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
--------	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

Destination	Yes	—	—	—	—	—	—	—	—	—
-------------	-----	---	---	---	---	---	---	---	---	---

2.2.5 ANDC (AND Control register)

AND Control register

<Operation>

$CR \wedge \#IMM \rightarrow CR$

<Assembly-Language Format>

ANDC #xx, CR

(Example)

ANDC.B #H'FE, CCR

<Operand Size>

Byte

Word

(Depends on the control register)

ANDC

<Condition Code>

N	Z	V	C
Δ	Δ	Δ	Δ

- (1) When CR is the status register (SR or CCR), the N, Z, V, and C bits are set according to the result of the operation.
 - (2) When CR is not the status register (EP, TP, DP, or BR), the bits are set as below.
- N: Set to "1" when the MSB of the result is "1;" otherwise cleared to "0."
- Z: Set to "1" when the result is zero; otherwise cleared to "0."
- V: Always cleared to 0.
- C: Previous value remains unchanged.

<Description>

This instruction ANDs the contents of a control register (CR) with immediate data and places the result in the control register.

The operand size specified in the instruction depends on the control register as indicated in Table 1-12 in Section 1.3.6, "Register Specification."

Interrupts are not accepted and trace exception processing is not performed immediately after the end of this instruction.

<Instruction Format>

ANDC #xx:8, CR	0 0 0 0 1 0 0	data	0 1 0 1 1 ccc
----------------	---------------	------	---------------

ANDC #xx:16, CR	0 0 0 0 1 1 0 0	data (H)	data (L)	0 1 0 1 1 ccc
-----------------	-----------------	----------	----------	---------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	—	—	—	—	—	—	Yes	Yes
--------	---	---	---	---	---	---	-----	-----

2.2.6 Bcc (Branch conditionally)

Branch conditionally

<Operation>

If condition is true then PC + disp → PC
else next;

Bcc

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

Bcc disp

The mnemonic varies depending on the specified condition. See <Mnemonic and Condition Field> below.

(Example)

BEQ LABEL

<Operand Size>

<Description>

If the condition specified in the condition field (cc) is true, the displacement (disp) is added to the program counter and execution branches to the resulting address. If the condition is not true, the next instruction is executed.

The displacement can be an 8- or 16-bit value. The corresponding relative branching distances are -128 to +127 bytes and -32768 to +32767 bytes. However, it is not possible to branch across a page boundary.

The PC value used in the address calculation is the address of the instruction immediately following this instruction.

<Instruction Format>

0	0	1	0	c	c	disp	
0	0	1	0	c	c	disp (H)	disp (L)

cc: Condition field

Branch conditionally**Bcc****<Mnemonic and Condition Field>**

Mnemonic	cc field	Description	Condition
BRA (BT)	0 0 0 0	Always (True)	True
BRN (BF)	0 0 0 1	Never (False)	False
BHI	0 0 1 0	High	$C \vee Z = 0$
BLS	0 0 1 1	Low or Same	$C \vee Z = 1$
BCC (BHS)	0 1 0 0	Carry Clear (High or Same)	$C = 0$
BCS (BLO)	0 1 0 1	Carry Set (Low)	$C = 1$
BNE	0 1 1 0	Not Equal	$Z = 0$
BEQ	0 1 1 1	Equal	$Z = 1$
BVC	1 0 0 0	Overflow Clear	$V = 0$
BVS	1 0 0 1	Overflow Set	$V = 1$
BPL	1 0 1 0	Plus	$N = 0$
BMI	1 0 1 1	Minus	$N = 1$
BGE	1 1 0 0	Greater or Equal	$N \oplus V = 0$
BLT	1 1 0 1	Less Than	$N \oplus V = 1$
BGT	1 1 1 0	Greater Than	$Z \vee (N \oplus V) = 0$
BLE	1 1 1 1	Less or Equal	$Z \vee (N \oplus V) = 1$

2.2.7 BCLR (Bit test and CLeaR)

Bit test and CLeaR

<Operation>

$\neg(\text{bit No. of } \langle EAd \rangle) \rightarrow Z$
 $0 \rightarrow (\text{bit No. of } \langle EAd \rangle)$

BCLR

<Condition Code>

N	Z	V	C
—	↑	—	—

<Assembly-Language Format>

BCLR #xx, <EAd>

BCLR Rs, <EAd>

(Example)

BCLR.B #7, @H'FF00

- N: Previous value remains unchanged.
Z: Set to "1" if the value of the bit tested was zero. Otherwise cleared to "0."
V: Previous value remains unchanged.
C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction tests a specified bit in the destination operand, sets or clears the Z bit according to the result, then clears the specified bit to "0."

The bit number (0 to 15) can be specified directly using immediate data, or can be placed in a specified general register. If a general register is used, the lower 4 bits of the register specify the bit number and the upper 12 bits are ignored.

<Instruction Format>

BCLR #xx, <EAd>	EA	1 1 0 1	:	Data
BCLR Rs, <EAd>	EA	0 1 0 1	1 r r r	

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.8 BNOT (Bit test and NOT)

Bit test and NOT

<Operation>

$\neg(\text{bit No. of } <\text{EAd}>) \rightarrow Z$
 $\rightarrow (\text{bit No. of } <\text{EAd}>)$

BNOT

<Condition Code>

N	Z	V	C
—	↑	—	—

<Assembly-Language Format>

BNOT #xx, <EAd>
BNOT Rs, <EAd>
(Example)
BNOT.W R0, R1

N: Previous value remains unchanged.
Z: Set to "1" if the value of the bit tested was zero. Otherwise cleared to "0."
V: Previous value remains unchanged.
C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction tests a specified bit in the destination operand, sets or clears the Z bit according to the result, then inverts the specified bit.

The bit number (0 to 15) can be specified directly using immediate data, or can be placed in a specified general register. If a general register is used, the lower 4 bits of the register specify the bit number and the upper 12 bits are ignored.

<Instruction Format>

BNOT #xx,<EAd>	EA	1 1 1 0	:	Data
BNOT Rs,<EAd>	EA	0 1 1 0	1 r r r	

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—							
-------------	-----	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.9 BSET (Bit test and SET)

Bit test and SET

<Operation>

$\neg(\text{bit No.} \text{ of } \text{EAd}) \rightarrow Z$
 $1 \rightarrow (\text{bit No.} \text{ of } \text{EAd})$

BSET

<Condition Code>

N	Z	V	C
—	↑	—	—

<Assembly-Language Format>

BSET #xx, <EAd>
BSET Rs, <EAd>
(Example)
BSET.B #0, @R1+

- N: Previous value remains unchanged.
Z: Set to "1" if the value of the bit tested was zero. Otherwise cleared to "0."
V: Previous value remains unchanged.
C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction tests a specified bit in the destination operand, sets or clears the Z bit according to the result, then sets the specified bit to "1."

The bit number (0 to 15) can be specified directly using immediate data, or can be placed in a specified general register. If a general register is used, the lower 4 bits of the register specify the bit number and the upper 12 bits are ignored.

<Instruction Format>

BSET #xx,<EAd>	EA	1 1 0 0	:	Data
BSET Rs,<EAd>	EA	0 1 0 0	1 r r r	

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.10 BSR (Branch to SubRoutine)

Branch to SubRoutine

<Operation>

PC → @-SP

PC + disp → PC

BSR

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

BSR disp

(Example)

BSR LABEL

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction branches to a subroutine at a specified address.

It saves the program counter contents to the stack area, then adds a displacement to the program counter and jumps to the resulting address.

The displacement can be an 8-bit value from -128 to +127 bytes or 16-bit value from -32768 to +32767 bytes. However, it is not possible to branch across a page boundary.

This instruction is paired with the RTS instruction to execute a subroutine call. The PC value saved to the stack and used in the address calculation is the address of the instruction immediately following this instruction.

<Instruction Format>

BSR d:8	0 0 0 0 1 1 1 0	disp
---------	-----------------	------

BSR d:16	0 0 0 1 1 1 1 0	disp (H)	disp (L)
----------	-----------------	----------	----------

2.2.11 BTST (Bit TeST)

Bit TeST

<Operation>

$\neg(\text{bit No.} \text{ of } \text{EAd}) \rightarrow Z$

BTST

<Condition Code>

N	Z	V	C
—	↑	—	—

<Assembly-Language Format>

BTST #xx, <EAd>

BTST Rs, <EAd>

(Example)

BTST.B R0, @H'F0:8

N: Previous value remains unchanged.

Z: Set to "1" if the value of the bit tested was zero. Otherwise cleared to "0."

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction tests a specified bit in the destination operand and sets or clears the Z bit according to the result.

The bit number (0 to 15) can be specified directly using immediate data, or can be placed in a specified general register. If a general register is used, the lower 4 bits of the register specify the bit number and the upper 12 bits are ignored.

<Instruction Format>

BTST #xx, <EAd>	EA	1 1 1 1	:	Data
BTST Rs, <EAd>	EA	0 1 1 1 1	r r r	

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.12 CLR (CLeAР)

CLeAР	CLR								
<Operation>	<Condition Code>								
$0 \rightarrow (\text{EAd})$	<table border="1"><tr><td>N</td><td>Z</td><td>V</td><td>C</td></tr><tr><td>0</td><td>1</td><td>0</td><td>0</td></tr></table>	N	Z	V	C	0	1	0	0
N	Z	V	C						
0	1	0	0						
<Assembly-Language Format>									
CLR <EAd>	N: Always cleared to 0.								
(Example)	Z: Always set to 1.								
CLR.W @ (H'1000, R5)	V: Always cleared to 0.								
	C: Always cleared to 0.								
<Operand Size>									
Byte									
Word									
<Description>									
This instruction clears the destination operand (general register Rn or an operand in memory) to zero.									
<Instruction Format>									
<table border="1"><tr><td>EA</td><td>0 0 0 1 0 0 1 1</td></tr></table>	EA	0 0 0 1 0 0 1 1							
EA	0 0 0 1 0 0 1 1								
<Addressing Modes>									
Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16									
Destination	Yes Yes Yes Yes Yes Yes Yes Yes — —								

2.2.13 CMP

(1) CMP:G (CoMPare, General format)

CoMPare	CMP:G
<Operation>	<Condition Code>
Set CCR according to result of (EAd) – #IMM	N Z V C ↑ ↓ ↓ ↓
Set CCR according to result of Rd – (EAs)	
<Assembly-Language Format>	N: Set to "1" when the result is negative; otherwise cleared to "0." Z: Set to "1" when the result is zero; otherwise cleared to "0." V: Set to "1" if an overflow occurs; otherwise cleared to "0." C: Set to "1" if a borrow occurs; otherwise cleared to "0."
<Operand Size>	
Byte	
Word	

<Description>

This instruction subtracts the source operand from the destination operand and sets or clears the condition code (CCR) according to the result. It does not alter the destination operand.

The CMP instruction also has short formats (CMP:E and CMP:I) that can be used to compare a general register with immediate data.

<Instruction Format>

CMP #xx, <EAd>	EA	0 0 0 0 0 1 0 0	data*
	EA	0 0 0 0 0 1 0 1	data (H)*
CMP <EAs>, Rd	EA 0 1 1 1 0 r r r		

* The length of the immediate data depends on the size (Sz) specified for the first operation code: one byte when Sz = 0; one word when Sz = 1.

* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

<Addressing Modes>

CMP #xx,<EA_d>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	—	—	—	—	—	—	—	Yes	Yes
Destination	—	Yes	—						

CMP <EA_s>, Rd

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes								
Destination	Yes	—	—	—	—	—	—	—	—

2.2.13 (2) CMP:E (CoMPare:E, short format)

CoMPare immediate bytE	CMP:E
<Operation>	<Condition Code>
Set CCR according to result of Rd – #IMM	N Z V C ↑ ↑ ↑ ↑
<Assembly-Language Format>	
CMP : E #xx:8, Rd	N: Set to "1" when the result is negative; otherwise cleared to "0."
(Example)	Z: Set to "1" when the result is zero; otherwise cleared to "0."
(1) CMP : E #H'00, R0	V: Set to "1" if an overflow occurs; otherwise cleared to "0."
(2) CMP .B #H'00, R0*	C: Set to "1" if a borrow occurs; otherwise cleared to "0."
<Operand Size>	
Byte	
<Description>	
This instruction subtracts one byte of immediate data from general register Rd and sets or clears the condition code (CCR) according to the result. It does not alter the contents of general register Rd.	
This instruction is a short form of the CMP instruction. Compared with CMP:G #xx:8, Rd, its object code is one byte shorter and it executes one state faster.	
<Instruction Format>	
0 1 0 0 0 r r r data	
<Addressing Modes>	
Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16	
Source — — — — — — — — Yes —	
Destination Yes — — — — — — — — — —	

* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.13 (3) CMP:I (CoMPare:I, short format)

CoMPare Immediate word	CMP:I								
<Operation>	<Condition Code>								
Set CCR according to result of Rd – #IMM	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>N</td> <td>Z</td> <td>V</td> <td>C</td> </tr> <tr> <td>↑</td> <td>↑</td> <td>↑</td> <td>↑</td> </tr> </table>	N	Z	V	C	↑	↑	↑	↑
N	Z	V	C						
↑	↑	↑	↑						
<Assembly-Language Format>									
CMP :I #xx:16, Rd (Example) (1) CMP :I #H'FFFF, R1 (2) CMP .W #H'FFFF, R1*	<p>N: Set to "1" when the result is negative; otherwise cleared to "0."</p> <p>Z: Set to "1" when the result is zero; otherwise cleared to "0."</p> <p>V: Set to "1" if an overflow occurs; otherwise cleared to "0."</p> <p>C: Set to "1" if a borrow occurs; otherwise cleared to "0."</p>								
<Operand Size>									
Word									
<Description>									
<p>This instruction subtracts one word of immediate data from general register Rd and sets or clears the condition code (CCR) according to the result. It does not alter the contents of general register Rd.</p> <p>This instruction is a short form of the CMP instruction. Compared with CMP:G #xx:16, Rd, its object code is one byte shorter and it executes one state faster.</p>									
<Instruction Format>									
<table border="1" style="width: 100%; text-align: center;"> <tr> <td>0 1 0 0 1 r r r</td> <td>data (H)</td> <td>data (L)</td> </tr> </table>	0 1 0 0 1 r r r	data (H)	data (L)						
0 1 0 0 1 r r r	data (H)	data (L)							
<Addressing Modes>									
<table border="1" style="width: 100%; text-align: center;"> <tr> <td>Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16</td> </tr> </table>		Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16							
Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16									
Source	— — — — — — — — — Yes								
Destination	Yes — — — — — — — — — — —								

- * In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.14 DADD (Decimal ADD with extend carry)

Decimal ADD with extend carry

<Operation>

$(Rd)_{10} + (Rs)_{10} + C \rightarrow (Rd)_{10}$

<Assembly-Language Format>

DADD Rs, Rd

(Example)

DADD R0, R1

<Operand Size>

Byte

<Description>

This instruction adds the contents of a general register (source operand) and the C bit to the contents of a general register (destination operand) as decimal numbers and places the result in the destination register.

Correct results are not assured if word size is specified.

<Instruction Format>

1	0	1	0	0	r _s	r _s	r _s	0	0	0	0	0	0	0	1	0	1	0	0	r _d	r _d	r _d
---	---	---	---	---	----------------	----------------	----------------	---	---	---	---	---	---	---	---	---	---	---	---	----------------	----------------	----------------

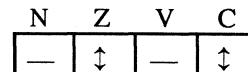
<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
Destination	Yes	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—

DADD

<Condition Code>



N: Previous value remains unchanged.

Z: Set to "1" if the previous Z bit value was "1" and the result of the instruction is zero; otherwise cleared to "0."

V: Previous value remains unchanged.

C: Set to "1" if a decimal carry occurs; otherwise cleared to "0."

2.2.15 DIVXU (DIVide eXtend as Unsigned)

DIVide eXtend as Unsigned

<Operation>

$Rd \div (EAs) \rightarrow Rd$

<Assembly-Language Format>

DIVXU <EAs>, Rd

(Example)

DIVXU.W @R3, R0

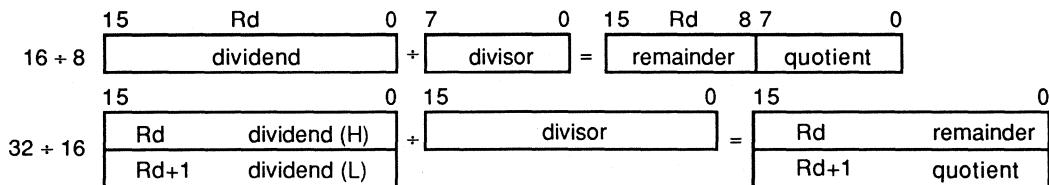
<Operand Size>

Byte

Word

<Description>

When byte size is specified for the source operand, the 16-bit value in Rd is divided by the 8-bit source operand, yielding an 8-bit quotient which is placed in the lower byte of Rd and 8-bit remainder which is placed in the upper byte of Rd. When word size is specified for the source operand, the 32-bit value in Rd and Rd+1 is divided by the 16-bit source operand, yielding a 16-bit quotient which is placed in Rd+1 and a 16-bit remainder which is placed in Rd.



When the dividend is a 32-bit value located in Rd and Rd+1, d must be even (0, 2, 4, or 6). Correct results are not assured if an odd register number is specified. Also:

- (1) Attempted division by 0 causes a zero-divide exception. The N, V and C bits are cleared to 0 and the Z bit is set to 1.
- (2) When an overflow is detected, the V bit is set to 1 and the division is not performed. The N, Z and C bits are cleared to 0. The contents of general register Rd are not updated.

<Instruction Format>

EA*	1	0	1	1	1	r	r	r
-----	---	---	---	---	---	---	---	---

* When Sz = 0: 16 bits ÷ 8 bits.

When Sz = 1: 32 bits ÷ 16 bits

where Sz is the size bit in the EA code

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16											
Source	Yes										
Destination	Yes	—	—	—	—	—	—	—	—	—	—

<Note>

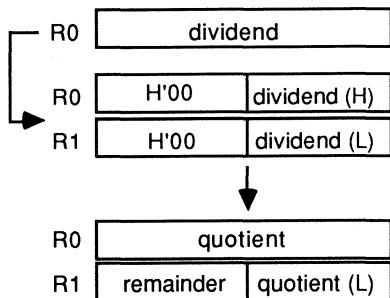
An overflow can occur in both cases of the DIVXU instruction:

- ① 16 bits ÷ 8 bits → 8-bit quotient, 8-bit remainder
- ② 32 bits ÷ 16 bits → 16-bit quotient, 16-bit remainder

Consider H'FFFF ÷ H'1 → H'FFFF in case ①, for example. An overflow occurs because the quotient is longer than 8 bits. Overflow can be avoided by using work registers as in the programs shown below.

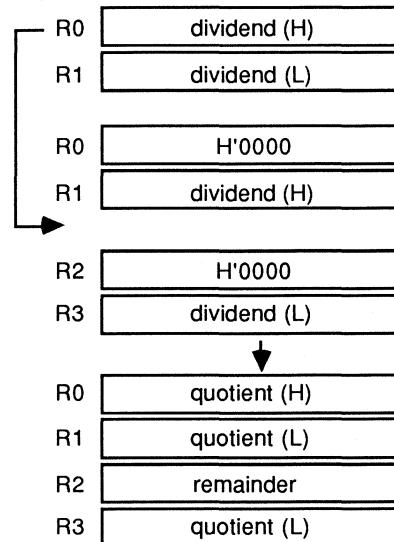
① 16 bits ÷ 8 bits

DIVXU.B <EA>,R0



② 32 bits ÷ 16 bits

DIVXU.W <EA>,R0



MOV.B	R0, R1	MOV.W	R1, R3
SWAP	R0	MOV.W	R0, R1
AND.W	#H'00FF 16,R0	CLR.W	R0
DIVXU.B	<EA>,R0	DIVXU.W	<EA>,R0
SWAP	R0	MOV.W	R0, R2
SWAP	R1	MOV.W	R1, R0
MOV.B	R0, R1	DIVXU.W	<EA>, R2
SWAP	R1	MOV.W	R3, R1
DIVXU.B	<EA>, R1		
MOV.B	R1, R0		

2.2.16 DSUB (Decimal SUBtract with extend carry)

Decimal SUBtract with extend carry

DSUB

<Operation>

$(Rd)_{10} - (Rs)_{10} - C \rightarrow (Rd)_{10}$

<Condition Code>

N	Z	V	C
—	↑	—	↑

<Assembly-Language Format>

DSUB Rs, Rd

(Example)

DSUB R2, R3

N: Previous value remains unchanged.

Z: Set to "1" if the previous Z bit value was "1" and the result of the instruction is zero; otherwise cleared to "0."

V: Previous value remains unchanged.

C: Set to "1" if a decimal borrow occurs; otherwise cleared to "0."

<Operand Size>

Byte

<Description>

This instruction subtracts the contents of general register Rs (source operand) and the C bit from the contents of general register Rd (destination operand) as decimal numbers and places the result in general register Rd.

Correct results are not assured if word size is specified for the operand size.

<Instruction Format>

1	0	1	0	0	r _s	r _s	r _s	0	0	0	0	0	0	0	1	0	1	1	0	r _d	r _d	r _d
---	---	---	---	---	----------------	----------------	----------------	---	---	---	---	---	---	---	---	---	---	---	---	----------------	----------------	----------------

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
Destination	Yes	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—	—

2.2.17 EXTS (EXTend as Signed)

EXTend as Signed

<Operation>

(<bit 7> of <Rd>) → (<bits 15 to 8> of <Rd>)

Sign extension

EXTS

<Condition Code>

N	Z	V	C
↓	↓	0	0

<Assembly-Language Format>

EXTS Rd

(Example)

EXTS R0

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Always cleared to 0.

<Operand Size>

Byte

<Description>

This instruction converts byte data in general register Rd (destination operand) to word data by propagating the sign bit. It copies bit 7 of Rd into bits 8 through 15.

<Instruction Format>

1	0	1	0	0	r	r	r	0	0	0	1	0	0	0	1
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination Yes — — — — — — — — — — — —

2.2.18 EXTU (EXTend as Unsigned)

EXTend as Unsigned

<Operation>

0 → (<bits 15 to 8> of <Rd>)

Zero extension

EXTU

<Condition Code>

N	Z	V	C
0	↑	0	0

<Assembly-Language Format>

EXTU Rd

(Example)

EXTU R1

N: Always cleared to 0.

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Always cleared to 0.

<Operand Size>

Byte

<Description>

This instruction converts byte data in general register Rd (destination register) to word data by filling bits 8 to 15 of Rd with zeros.

<Instruction Format>

1	0	1	0	0	r	r	r	0	0	0	1	0	0	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination Yes

— — — — — — — — — —

2.2.19 JMP (JuMP)

JuMP	JMP
<Operation>	<Condition Code>
Effective address → PC	N Z V C — — — —
<Assembly-Language Format>	
JMP <EA>	N: Previous value remains unchanged.
(Example)	Z: Previous value remains unchanged.
JMP @ (#H'10, R4)	V: Previous value remains unchanged.
	C: Previous value remains unchanged.
<Operand Size>	
<Description>	
This instruction branches unconditionally to a specified address in the same page. It cannot branch across a page boundary.	
<Instruction Format>	
JMP @Rn	0 0 0 1 0 0 0 1 1 1 0 1 0 r r r
JMP @ (d:8, Rn)	0 0 0 1 0 0 0 1 1 1 1 0 0 r r r disp
JMP @ (d:16, Rn)	0 0 0 1 0 0 0 1 1 1 1 1 0 r r r disp (H) disp (L)
JMP @aa:16	0 0 0 1 0 0 0 0 address (H) address (L)
<Addressing Modes>	
Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16	
Destination — Yes Yes Yes — — — Yes — —	

2.2.20 JSR (Jump to SubRoutine)

Jump to SubRoutine

<Operation>

PC → @SP

Effective address → PC

JSR

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

JSR <EA>

(Example)

JSR @ (H'0FFF, R3)

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction pushes the program counter contents onto the stack, then branches to a specified address in the same page. The address pushed on the stack is the address of the instruction immediately following this instruction.

This instruction cannot branch across a page boundary.

<Instruction Format>

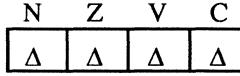
JSR @Rn	0 0 0 1 0 0 0 1 1 1 0 1 1 r r r
JSR @ (d:8, Rn)	0 0 0 1 0 0 0 1 1 1 1 0 1 r r r disp
JSR @ (d:16, Rn)	0 0 0 1 0 0 0 1 1 1 1 1 1 r r r disp (H) disp (L)
JSR @aa:16	0 0 0 1 1 0 0 0 address (H) address (L)

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	—	Yes	Yes	Yes	—	—	—	Yes	—	—
-------------	---	-----	-----	-----	---	---	---	-----	---	---

2.2.21 LDC (LoaD to Control register)

LoaD to Control register	LDC		
<Operation>	<Condition Code>		
(EAs) → CR			
<Assembly-Language Format>			
LDC <EAs>, CR (Example) LDC.B #H'01, DP	<p>(1) When CR is the status register (SR or CCR), the N, Z, V, and C bits are set according to the result of the operation.</p> <p>(2) When CR is not the status register (EP, TP, DP, or BR), the previous value remains unchanged.</p>		
<Operand Size>			
Byte Word (Depends on the control register)			
<Description>	<p>This instruction loads the source operand (immediate data, or general register or memory contents) into a specified control register (CR).</p> <p>The operand size specified in the instruction depends on the control register as indicated in Table 1-12 in Section 1.3.6, "Register Specification."</p> <p>Interrupts are not accepted and trace exception processing is not performed immediately after the end of this instruction.</p>		
<Instruction Format>	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>EA</td> <td>1 0 0 0 1 c c c</td> </tr> </table>	EA	1 0 0 0 1 c c c
EA	1 0 0 0 1 c c c		
<Addressing Modes>	Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16		
Source	Yes		

2.2.22 LDM (LoaD to Multiple registers)

LoaD to Multiple registers

LDM

<Operation>

@SP+ (stack) → Rd (register group)

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

LDM @SP+, <register list>

(Example)

LDM @SP+, (R0, R2-R4)

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Word

<Description>

This instruction restores data saved on the stack to a specified list of general registers. In the instruction code, the register list is encoded as one byte in which bits set to "1" indicate registers that receive data. The first word of data is restored to the lowest-numbered register in the list, the next word to the next-lowest-numbered register, and so on.

At the end of this instruction, general register R7 (the stack pointer) is updated to the value: (contents of R7 before this instruction) + 2 × (number of registers restored).

<Instruction Format>

0	0	0	0	0	0	1	0	register list
---	---	---	---	---	---	---	---	---------------

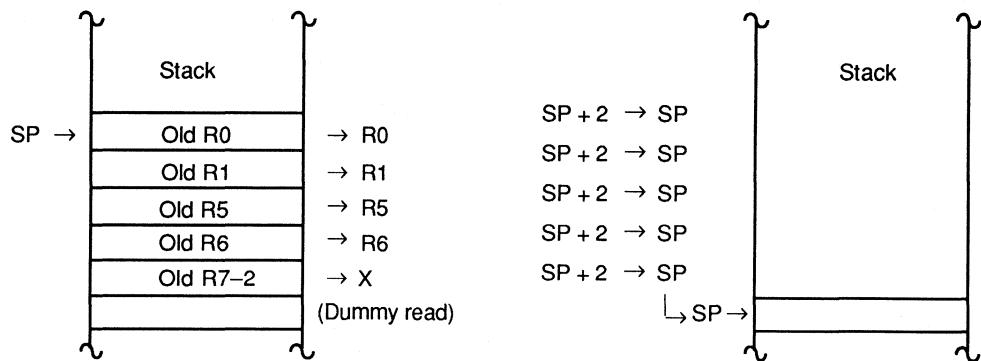
Register list

7	6	5	4	3	2	1	0
R7	R6	R5	R4	R3	R2	R1	R0

<Note>

The LDM instruction can be used to restore a group of registers from the stack on return from a subroutine call. When there are many registers to restore, the LDM instruction is faster than the MOV instruction.

The status of the stack before and after an LDM instruction is shown below.

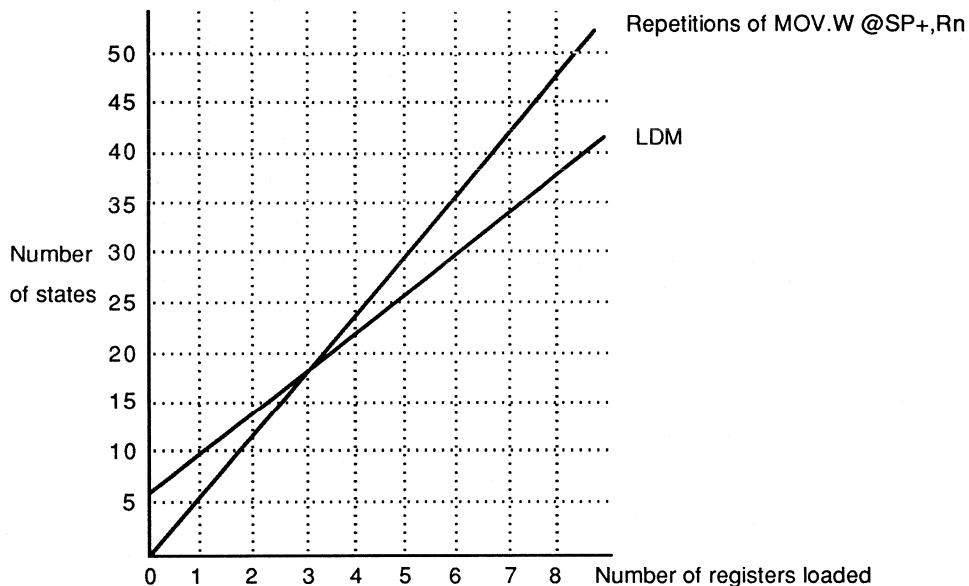


Execution of LDM @SP+, (R0,R1,R5-R7)

If R7 (the stack pointer) is included in the register list, a dummy read of the stack is performed. Accordingly, the instruction will execute faster if R7 is not specified. The value of R7 after execution of the instruction is: (contents of R7 before the instruction) + 2 × (number of registers restored).

<Note (Continued)>

The following graph compares the number of machine states required for execution of LDM and execution of the same process using the MOV instruction.



Note: This graph is for the case in which instruction fetches and stack access are both to on-chip memory.

The LDM instruction is faster when the number of registers is four or more. The MOV instruction is faster when there are only one or two registers to restore. When the instruction fetches are to off-chip memory, the LDM instruction is faster when there are two registers or more.

2.2.23 LINK (LINK)

LINK stack

<Operation>

FP (R6) → @-SP

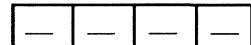
SP → FP (R6)

SP+#IMM → SP

LINK

<Condition Code>

N Z V C



<Assembly-Language Format>

LINK FP, #xx

(Example)

LINK FP, #-4

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction saves the frame pointer (FP = R6) to the stack, copies the stack pointer (SP = R7) contents to the frame pointer, then adds a specified immediate value to the stack pointer to allocate a new frame in the stack area.

The immediate data can be an 8-bit value from -128 to +127 or a 16-bit value from -32768 to +32767. Note that the LINK instruction allows negative immediate data.

The frame allocated with the LINK instruction can be deallocated with the UNLK instruction.

Note: When the stack is accessed an address error will occur if the stack pointer indicates an odd address. The immediate data should be an even number so that the stack pointer indicates an even address after execution of the LINK instruction.

<Instruction Format>

LINK FP, #xx:8

0	0	0	1	0	1	1	1	data
---	---	---	---	---	---	---	---	------

LINK FP, #xx:16

0	0	0	1	1	1	1	1	data (H)	data (L)
---	---	---	---	---	---	---	---	----------	----------

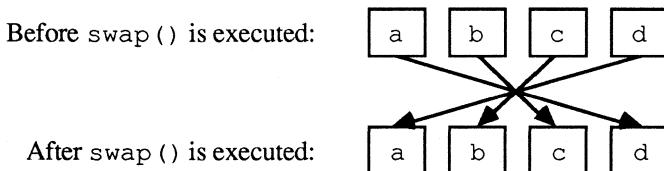
<Note>

The LINK and UNLK instructions provide an efficient way to allocate and deallocate areas for local variables used in subroutine and function calls in high-level languages. Local variables are accessed relative to R6 (the frame pointer).

The LINK and UNLK instructions can be broken down into the following groups of more general instructions:

LINK FP, #-n	⇒	MOV.W FP, @-SP MOV.W SP, FP ADDS.W #-n, SP (providing an n-byte local variable area)
UNLK FP	⇒	MOV.W FP, SP MOV.W @SP+, FP

An example of the usage of these instructions in a C-language program is shown below. The program contains a function swap that uses two work variables temp1 and temp2 to exchange the contents of four variables a, b, c, and d.



The coding in C language is:

```

int a, b, c, d;      — Global variables a, b, c, d
swap()
{
    int temp1, temp2; — Local variables temp1, temp2
    temp1 = a;          — Usable only in the swap () function.
    temp2 = b;          — Present in memory only when the swap () function is called.
    a = d;
    b = c;
    c = temp2;
    d = temp1;
}

```

<Note (Continued)>

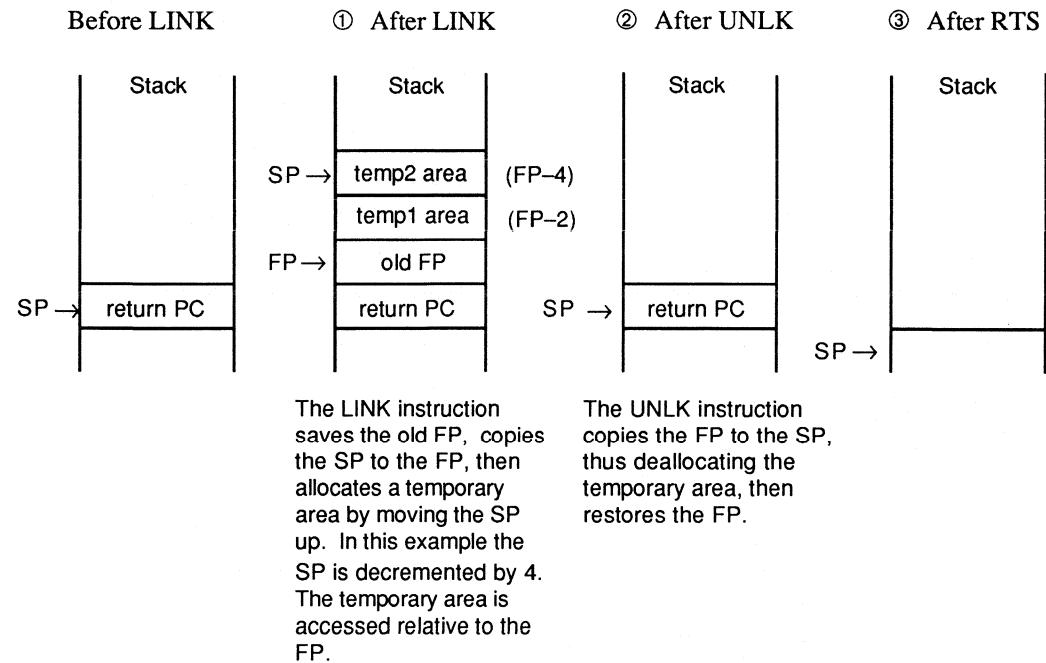
An assembly-language coding of the swap function is:

Swap:	LINK	FP, #-4	→ See ① on next page.
	MOV	@a, R0	→ temp1 = a;
	MOV:F	R0, @(-2, FP)	
	MOV	@b, R0	→ temp2 = b;
	MOV:F	R0, @(-4, FP)	
	MOV	@d, R0	→ a = d;
	MOV	R0, @a	
	MOV	@c, R0	→ b = c;
	MOV	R0, @b	
	MOV:F	@(-4, FP), R0	→ c = temp2;
	MOV	R0, @c	
	MOV:F	@(-2, FP), R0	→ d = temp1;
	MOV	R0, @d	
	UNLK	FP	→ See ② on next page.
	RTS		→ See ③ on next page.

LINK stack**LINK**

<Note (Continued)>

A map of the stack area in memory at various stages in this routine is shown below.



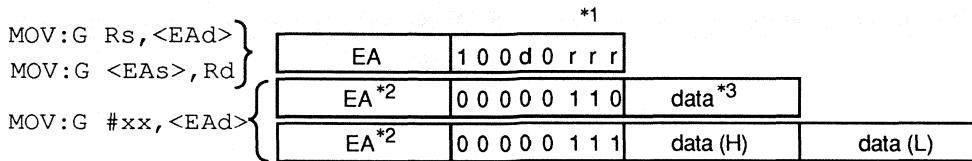
2.2.24 MOV

(1) MOV:G (MOVE data from source to destination, General format)

MOVE data from source to destination	MOV:G								
<Operation>	<Condition Code>								
(EAs) → (EAd)	<table border="1"><tr><td>N</td><td>Z</td><td>V</td><td>C</td></tr><tr><td>↓</td><td>↓</td><td>0</td><td>—</td></tr></table>	N	Z	V	C	↓	↓	0	—
N	Z	V	C						
↓	↓	0	—						
<Assembly-Language Format>									
MOV:G Rs, <EAd>	N: Set to "1" when the value moved is negative; otherwise cleared to "0."								
MOV:G #xx, <EAd>	Z: Set to "1" when the value moved is zero; otherwise cleared to "0."								
MOV:G <EAs>, Rd	V: Always cleared to 0.								
(Example)	C: Previous value remains unchanged.								
(1) MOV:G.W R0, @R1									
(2) MOV.W R0, @R1*									
<Operand Size>									
Byte									
Word									
<Description>									
This instruction copies source operand data to a destination, and sets or clears the N and Z bits according to the data value.									
Alternative short formats can be used for the R6 indirect with displacement addressing mode (MOV:F), the short (@aa:8) absolute addressing mode (MOV:L and MOV:S), and the immediate addressing modes (MOV:E for #xx:8 and MOV:I for #xx:16).									
* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.									

MOVE data from source to destination MOV:G

<Instruction Format>



Notes:

*1 The d bit indicates the direction of the transfer: load if d = 0; store if d = 1.

When d = 1, the <EA> field cannot contain immediate data or specify a register.

*2 The <EA> field cannot contain immediate data or specify a register.

*3 If the immediate data length is 8 bits but word size is specified in the <EA> field, the sign bit of the immediate data is extended and 16 bits of data are transferred.

<Addressing Modes>

MOV:G Rs, <EAd>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes	—	—	—	—	—	—	—	—	—	—
Destination	—	Yes	—	—	—						

MOV:G #xx, <EAd>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	—	—	—	—	—	—	—	—	Yes	Yes
Destination	—	Yes	—	—						

MOV:G <EAs>, Rd

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.24 (2) MOV:E (MOVE data:E, short format)

MOVE immEdiate byte

<Operation>

#IMM → Rd

MOV:E

<Condition Code>

N	Z	V	C
↓	↓	0	—

<Assembly-Language Format>

MOV:E #xx:8, Rd

(Example)

- (1) MOV:E #H'55, R0
- (2) MOV.B #H'55, R0*

N: Set to "1" when the value moved is negative; otherwise cleared to "0."

Z: Set to "1" when the value moved is zero; otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

<Description>

This instruction moves one byte of immediate data to a general register, and sets or clears the N and Z bits according to the data value.

This instruction is a short form of the MOV instruction. Compared with the general form MOV:G #xx:8, Rd, its object code is one byte shorter and it executes one state faster.

<Instruction Format>

0	1	0	1	0	r	r	r	data
---	---	---	---	---	---	---	---	------

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16

Source — — — — — — — — Yes —

Destination Yes — — — — — — — — —

* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.24 (3) MOV:F (MOVE data:F, short format)

MOVE stack Frame data

<Operation>

(EAs) → Rd

Rs → EAd

MOV:F

<Condition Code>

N	Z	V	C
↓	↓	0	—

<Assembly-Language Format>

MOV:F @ (d:8, R6), Rd

MOV:F Rs, @ (d:8, R6)

(Example)

(1) MOV:F.B @ (4, R6), R0

(2) MOV.B @ (4, R6), R0*

N: Set to "1" when the value moved is negative; otherwise cleared to "0."

Z: Set to "1" when the value moved is zero; otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction moves data between a stack frame and a general register, and sets or clears the N and Z bits according to the data value.

This instruction is a short form of the MOV instruction. Compared with the general form MOV:G @ (d:8, R6), Rd or MOV:G Rs, @ (d:8, R6), its object code is one byte shorter.

<Instruction Format>

MOV:F @ (d:8, R6), Rd	1 0 0 0 S _z r r r	disp
MOV:F Rs, @ (d:8, R6)	1 0 0 1 S _z r r r	disp

-
- * In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

MOVE stack Frame data**MOV:F****<Addressing Modes>**

MOV:F @ (d:8, R6), Rd

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source — — Yes*

Destination Yes — —

MOV:F Rs, @ (d:8, R6)

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source Yes — —

Destination — — Yes*

* This instruction can specify R6 (FP) only.

2.2.24 (4) MOV:I (MOVe data:I, short format)

MOVE Immediate word

<Operation>

#IMM → Rd

MOV:I

<Condition Code>

N	Z	V	C
↑	↑	0	—

<Assembly-Language Format>

MOV:I #xx:16, Rd

(Example)

- (1) MOV:I #H'FF00, R5
- (2) MOV.W #H'FF00, R5*

N: Set to "1" when the value moved is negative; otherwise cleared to "0."

Z: Set to "1" when the value moved is zero; otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Word

<Description>

This instruction moves one word of immediate data to a general register, and sets or clears the N and Z bits according to the data value.

This instruction is a short form of the MOV instruction. Compared with the general form MOV:G #xx:16, Rd, its object code is one byte shorter.

<Instruction Format>

0	1	0	1	1	r	r	r	data (H)	data (L)
---	---	---	---	---	---	---	---	----------	----------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source — — — — — — — — — Yes

Destination Yes — — — — — — — — — —

* In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.24 (5) MOV:L (MOVE data:L, short format)

MOVE data (Load register)

<Operation>

(EAs) → Rd

<Assembly-Language Format>

MOV:L @aa:8, Rd

(Example)

- (1) MOV:L.B @H'A0:8, R0
- (2) MOV.B @H'A0:8, R0*

<Operand Size>

Byte

Word

<Description>

This instruction copies source operand data to a general register, and sets or clears the N and Z bits according to the data value.

This instruction is a short form of the MOV instruction. Compared with the general form
MOV:G @aa:8, Rd, its object code is one byte shorter.

<Instruction Format>

0	1	1	0	S _z	r	r	r	address (L)
---	---	---	---	----------------	---	---	---	-------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	—	—	—	—	—	—	Yes	—	—	—
--------	---	---	---	---	---	---	-----	---	---	---

Destination	Yes	—	—	—	—	—	—	—	—	—
-------------	-----	---	---	---	---	---	---	---	---	---

- * In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

MOV:L

<Condition Code>

N	Z	V	C
↑	↑	0	—

N: Set to "1" when the value moved is negative; otherwise cleared to "0."

Z: Set to "1" when the value moved is zero; otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

2.2.24 (6) MOV:S (MOVe data:S, short format)

MOVE data (Store register)

<Operation>

$Rs \rightarrow (EAd)$

MOV:S

<Condition Code>

N	Z	V	C
↓	↓	0	—

<Assembly-Language Format>

MOV:S Rs, @aa:8

(Example)

- (1) MOV:S.W R0, @H'A0:8
- (2) MOV.W R0, @H'A0:8*

N: Set to "1" when the value moved is negative; otherwise cleared to "0."

Z: Set to "1" when the value moved is zero; otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction stores general register data to a destination, and sets or clears the N and Z bits according to the data value.

This instruction is a short form of the MOV instruction. Compared with the general form MOV:G Rs, @aa:8, its object code is one byte shorter.

<Instruction Format>

0	1	1	1	S _z	r	r	r	address (L)
---	---	---	---	----------------	---	---	---	-------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes	—	—	—	—	—	—	—	—
--------	-----	---	---	---	---	---	---	---	---

Destination	—	—	—	—	—	—	Yes	—	—
-------------	---	---	---	---	---	---	-----	---	---

- * In assembly-language coding it is usually not necessary to specify the general or special format (by coding :G etc.). If the format specification is omitted, the assembler automatically generates the optimum object code. If a format is specified, the assembler follows the format specification.

2.2.25 MOVFPE (MOVE From Peripheral with E clock)

MOVE From Peripheral with E clock	MOVFPE				
<Operation>	<Condition Code>				
(EAs) → Rd	N Z V C				
Synchronized with E clock	<table border="1" style="margin-left: auto; margin-right: auto;"><tr><td>—</td><td>—</td><td>—</td><td>—</td></tr></table>	—	—	—	—
—	—	—	—		
<Assembly-Language Format>	N: Previous value remains unchanged. Z: Previous value remains unchanged. V: Previous value remains unchanged. C: Previous value remains unchanged.				
MOVFPE <EAs>, Rd					
(Example)					
MOVFPE @H'F000, R0					
<Operand Size>					
Byte					
<Description>					
This instruction transfers data from a source operand to a general register in synchronization with the E clock.					
The operand must be byte size. Correct results are not guaranteed if word size is specified.					
Note: This instruction should not be used with chips that do not have an E clock output pin. (Example: the H8/520)					
<Instruction Format>					
EA	<table border="1" style="margin-left: auto; margin-right: auto;"><tr><td>0 0 0 0 0 0 0 0 1 0 0 0 0 r r r</td></tr></table>	0 0 0 0 0 0 0 0 1 0 0 0 0 r r r			
0 0 0 0 0 0 0 0 1 0 0 0 0 r r r					
<Addressing Modes>					
Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16					
Source — Yes Yes Yes Yes Yes Yes Yes — —					
Destination Yes — — — — — — — — — —					

2.2.26 MOVTPE (MOVE To Peripheral with E clock)

MOVE To Peripheral with E clock

MOVTPE

<Operation>

Rs → (EAd)

Synchronized with E clock

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

MOVTPE Rs, <EAd>

(Example)

MOVTPE R0, @R1

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Byte

<Description>

This instruction transfers data from a general register to a destination in synchronization with the E clock.

The operand must be byte size. Correct results are not guaranteed if word size is specified.

Note: This instruction should not be used with chips that do not have an E clock output pin.

(Example: the H8/520)

<Instruction Format>

EA	0 0 0 0 0 0 0 0	1 0 0 1 0 r r r
----	-----------------	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes	—	—	—	—	—	—	—	—	—
Destination	—	Yes	—	—						

2.2.27 MULXU (MULTIPLY eXTEND as Unsigned)

MULTIPLY eXTEND as Unsigned

<Operation>

$Rd \times (EAs) \rightarrow Rd$

MULXU

<Condition Code>

N	Z	V	C
↑	↑	0	0

<Assembly-Language Format>

MULXU <EAs>, Rd

(Example)

MULXU.B R0, R1

<Operand Size>

Byte

Word

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

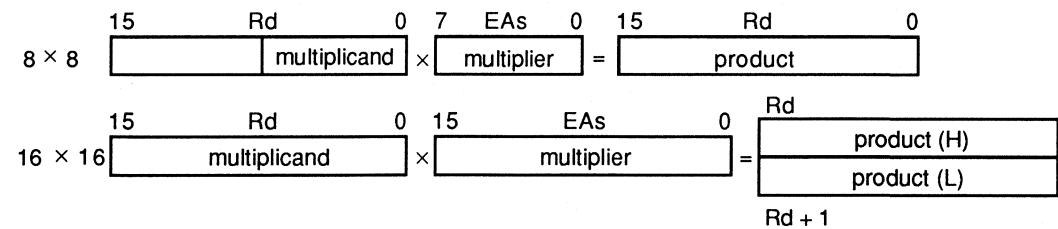
V: Always cleared to 0.

C: Always cleared to 0.

<Description>

This instruction multiplies the contents of general register Rd (destination operand) by a source operand and places the result in general register Rd.

When byte size is specified for the source operand, the 8-bit value in the lower byte of Rd is multiplied by the 8-bit source operand, yielding a 16-bit result. When word size is specified for the source operand, the 16-bit value in Rd is multiplied by the 16-bit source operand, yielding a 32-bit result which is placed in Rd and Rd+1.



When word size is specified and the 32-bit product is placed in Rd and Rd+1, d must be even (0, 2, 4, or 6). Correct results are not assured if an odd register number is specified.

MULtiply eXtend as Unsigned**MULXU****<Instruction Format>**

EA*	1	0	1	0	1	r	r	r
-----	---	---	---	---	---	---	---	---

- * When Sz = 0: 8 bits \times 8 bits = 16 bits
- When Sz = 1: 16 bits \times 16 bits = 32 bits
- where Sz is the size bit in the EA code

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.28 NEG (NEGate)

NEGATE	NEG								
<Operation>	<Condition Code>								
$0 - (\text{EAd}) \rightarrow (\text{EAd})$	<table border="1"><tr><td>N</td><td>Z</td><td>V</td><td>C</td></tr><tr><td>↓</td><td>↓</td><td>↓</td><td>↑</td></tr></table>	N	Z	V	C	↓	↓	↓	↑
N	Z	V	C						
↓	↓	↓	↑						
<Assembly-Language Format>	N: Set to "1" when the result is negative; otherwise cleared to "0." Z: Set to "1" when the result is zero; otherwise cleared to "0." V: Set to "1" if an overflow occurs; otherwise cleared to "0." C: Set to "1" if a borrow occurs; otherwise cleared to "0."								
<Operand Size>									
Byte									
Word									
<Description>									
This instruction replaces the destination operand (general register Rd or memory contents) with its two's complement. It subtracts the destination operand from zero and places the result in the destination.									
<Instruction Format>									
<table border="1"><tr><td>EA</td><td>0 0 0 1 0 1 0 0</td></tr></table>	EA	0 0 0 1 0 1 0 0							
EA	0 0 0 1 0 1 0 0								
<Addressing Modes>									
Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16									
Destination	Yes Yes Yes Yes Yes Yes Yes Yes — —								

2.2.29 NOP (No OPeration)

No OPeration

<Operation>

$PC + 1 \rightarrow PC$

NOP

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

NOP

(Example)

NOP

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction only increments the program counter.

<Instruction Format>

0	0	0	0	0	0	0	0
---	---	---	---	---	---	---	---

2.2.30 NOT (NOT = logical complement)

Logical complement	NOT								
<Operation>	<Condition Code>								
$\neg(EAd) \rightarrow (EAd)$	<table border="1"><tr><td>N</td><td>Z</td><td>V</td><td>C</td></tr><tr><td>↓</td><td>↓</td><td>0</td><td>—</td></tr></table>	N	Z	V	C	↓	↓	0	—
N	Z	V	C						
↓	↓	0	—						
<Assembly-Language Format>									
NOT <EAd>	N: Set to "1" when the result is negative; otherwise cleared to "0."								
(Example)	Z: Set to "1" when the result is zero; otherwise cleared to "0."								
NOT.B @ (H'10, R2)	V: Always cleared to 0.								
	C: Previous value remains unchanged.								
<Operand Size>									
Byte									
Word									
<Description>									
This instruction replaces the destination operand (general register Rd or memory contents) with its one's complement.									
<Instruction Format>									
EA	0 0 0 1 0 1 0 1								
<Addressing Modes>									
Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16									
Destination	Yes Yes Yes Yes Yes Yes Yes Yes — —								

2.2.31 OR (inclusive OR logical)

Inclusive logical OR

<Operation>

Rd \vee (EAs) \rightarrow Rd

OR

<Condition Code>

N	Z	V	C
↓	↓	0	—

<Assembly-Language Format>

OR <EAs>, Rd

(Example)

OR.B @H'F0:8, R1

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction obtains the logical OR of the source operand and general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	0	1	0	0	0	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.32 ORC (OR Control register)

OR Control register	ORC								
<Operation>	<Condition Code>								
$CR \vee \#IMM \rightarrow CR$	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>N</td> <td>Z</td> <td>V</td> <td>C</td> </tr> <tr> <td>Δ</td> <td>Δ</td> <td>Δ</td> <td>Δ</td> </tr> </table>	N	Z	V	C	Δ	Δ	Δ	Δ
N	Z	V	C						
Δ	Δ	Δ	Δ						
<Assembly-Language Format>									
ORC #xx, CR (Example) ORC.W #H'0700, SR	<p>(1) When CR is the status register (SR or CCR), the N, Z, V, and C bits are set according to the result of the operation.</p> <p>(2) When CR is not the status register (EP, TP, DP, or BR), the bits are set as below.</p> <p>N: Set to "1" when the MSB of the result is "1;" otherwise cleared to "0."</p> <p>Z: Set to "1" when the result is zero; otherwise cleared to "0."</p> <p>V: Always cleared to 0.</p> <p>C: Previous value remains unchanged.</p>								
<Operand Size>									
Byte Word (Depends on the control register)									

<Description>

This instruction ORs the contents of a control register (CR) with immediate data and places the result in the control register.

The operand size specified in the instruction depends on the control register as explained in Table 1-12 in Section 1.3.6, "Register Specification."

Interrupts are not accepted and trace exception processing is not performed immediately after the end of this instruction.

<Instruction Format>

ORC #xx:8, CR	0 0 0 0 0 1 0 0	data	0 1 0 0 1 c c c
ORC #xx:16, CR	0 0 0 0 1 1 0 0	data (H)	data (L) 0 1 0 0 1 c c c

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16

Source	—	—	—	—	—	—	—	Yes	Yes
--------	---	---	---	---	---	---	---	-----	-----

2.2.33 PJMP (Page JuMP)

Page JuMP

<Operation>

Effective address → CP, PC

PJMP

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

PJMP @aa:24

PJMP @Rn

(Example)

PJMP @R4

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction branches unconditionally to a specified address in a specified page, updating the code page (CP) register. If register indirect (@Rn) addressing is used, the lower byte of general register Rn is copied to the code page register, and the contents of general register Rn+1 are copied to the program counter (PC). The register number n must be even (n = 0, 2, 4, or 6). Correct results are not assured if n is odd.

This instruction is invalid when the CPU is operating in minimum mode.

<Instruction Format>

PJMP @aa:24	0 0 0 1 0 0 1 1	page	address (H)	address (L)
PJMP @Rn	0 0 0 1 0 0 0 1	1 1 0 0 0 r r r		

2.2.34 PJSR (Page Jump to SubRoutine)

Page Jump to SubRoutine	PJSL				
<Operation>	<Condition Code>				
PC → @-SP	N Z V C				
CP → @-SP	<table border="1" style="display: inline-table;"><tr><td>—</td><td>—</td><td>—</td><td>—</td></tr></table>	—	—	—	—
—	—	—	—		
Effective address → CP, PC					
<hr/>					
<Assembly-Language Formats>					
PJSR @aa:24	N: Previous value remains unchanged.				
PJSR @Rn	Z: Previous value remains unchanged.				
(Example)	V: Previous value remains unchanged.				
PJSR @H'010000	C: Previous value remains unchanged.				
<hr/>					
<Operand Size>					
<hr/>					
<Description>					
This instruction pushes the program counter (PC) and code page registers (CP) onto the stack, then branches to a specified address in a specified page. The PC and CP values pushed on the stack are the address of the instruction immediately following the PJSL instruction.					
If register indirect (@Rn) addressing is used, the lower byte of general register Rn is copied to the code page register, and the contents of general register Rn+1 are copied to the program counter. The register number n must be even (n = 0, 2, 4, or 6). Correct results are not assured if n is odd.					
This instruction is invalid when the CPU is operating in minimum mode.					
The status of the stack after execution of this instruction is shown below.					

<Instruction Format>				
PJSR @aa:24 <table border="1" style="display: inline-table;"><tr><td>0 0 0 0 0 1 1</td><td>page</td><td>address (H)</td><td>address (L)</td></tr></table>	0 0 0 0 0 1 1	page	address (H)	address (L)
0 0 0 0 0 1 1	page	address (H)	address (L)	
PJSR @Rn <table border="1" style="display: inline-table;"><tr><td>0 0 0 1 0 0 0 1</td><td>1 1 0 0 1 r r r</td></tr></table>	0 0 0 1 0 0 0 1	1 1 0 0 1 r r r		
0 0 0 1 0 0 0 1	1 1 0 0 1 r r r			

2.2.35 PRTD (Page ReTurn and DeAllocate)

Page ReTurn and DeAllocate

<Operation>

@SP+ → CP
@SP+ → PC
SP + #IMM → SP

PRTD

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

PRTD #xx
(Example)
PRTD #8

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction is used to return from a subroutine in a different page and deallocate the stack area used by the subroutine. It pops the code page register (CP) and program counter (PC) from the stack, then adjusts the stack pointer by adding immediate data specified in the instruction. The immediate data value can be an 8-bit value from -128 to +127, or a 16-bit value from -32768 to +32767.

This instruction can be used to restore the previous stack when returning from a subroutine called by the PJSR instruction.

This instruction is invalid when the CPU is operating in minimum mode.

Note: When the stack is accessed an address error will occur if the stack pointer indicates an odd address. The immediate data should be an even number so that the stack pointer indicates an even address after execution of the PRTD instruction.

<Instruction Format>

PRTD #xx:8	0 0 0 1 0 0 0 1 0 0 0 1 0 1 0 0	data
PRTD #xx:16	0 0 0 1 0 0 0 1 0 0 0 1 1 1 0 0	data (H) data (L)

2.2.36 PRTS (Page ReTurn from Subroutine)

Page ReTurn from SubRoutine	PRTS				
<Operation>	<Condition Code>				
@SP+ → CP	N Z V C				
@SP+ → PC	<table border="1"><tr><td>—</td><td>—</td><td>—</td><td>—</td></tr></table>	—	—	—	—
—	—	—	—		
<Assembly-Language Format>	N: Previous value remains unchanged. Z: Previous value remains unchanged. V: Previous value remains unchanged. C: Previous value remains unchanged.				
(Example)					
PRTS					
<Operand Size>					
<Description>	<p>This instruction is used to return from a subroutine in a different page. It pops the code page register (CP) and program counter (PC) from the stack. Execution continues from the popped address.</p> <p>This instruction is used to return from a subroutine called by PJSR instruction.</p> <p>This instruction is invalid when the CPU is operating in minimum mode.</p>				
<Instruction Formats>	<table border="1"><tr><td>0 0 0 1 0 0 0 1</td><td>0 0 0 1 1 0 0 1</td></tr></table>	0 0 0 1 0 0 0 1	0 0 0 1 1 0 0 1		
0 0 0 1 0 0 0 1	0 0 0 1 1 0 0 1				

2.2.37 ROTL (ROTate Left)

ROTRate Left

<Operation>

(EAd) rotated left → (EAd)

<Assembly-Language Format>

ROTL <EAd>

(Example)

ROTL.W R0

<Operand Size>

Byte

Word

ROTL

<Condition Code>

N	Z	V	C
↓	↓	0	↑

N: Set to "1" when the result is negative;
otherwise cleared to "0."

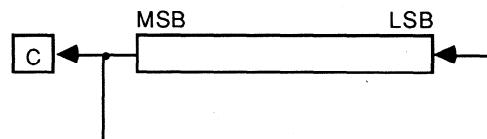
Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Set to the value shifted out from the
most significant bit.

<Description>

This instruction rotates the destination operand (general register Rd or memory contents) left, and sets the C bit to the value rotated out from the most significant bit.



<Instruction Format>

EA	0 0 0 1 1 1 0 0
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.38 ROTR (ROTate Right)

ROTR

<Operation>

(EAd) rotated right → (EAd)

ROTR

<Condition Code>

N	Z	V	C
↑	↑	0	↑

<Assembly-Language Format>

ROTR <EAd>

(Example)

ROTR.B @R1

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Set to the value shifted out from the
least significant bit.

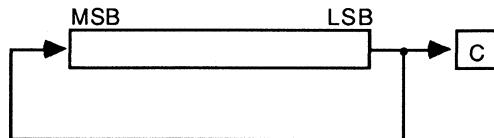
<Operand Size>

Byte

Word

<Description>

This instruction rotates the destination operand (general register Rd or memory contents) right, and sets the C bit to the value rotated out from the least significant bit.



<Instruction Format>

EA	0 0 0 1 1 1 0 1
----	-----------------

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination Yes Yes Yes Yes Yes Yes Yes Yes — —

2.2.39 ROTXL (ROTRate with eXtend carry Left)

ROTRate with eXtend carry Left

<Operation>

(EAd) rotated left through C bit → (EAd)

ROTRXL

<Condition Code>

N	Z	V	C
↓	↓	0	↓

<Assembly-Language Format>

ROTRXL <EAd>

(Example)

ROTRXL.W @ (H'02, R1)

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Receives the value shifted out from
the most significant bit.

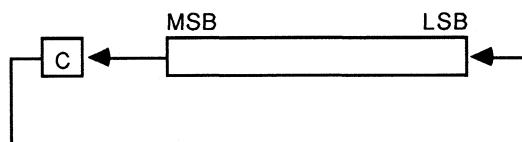
<Operand Size>

Byte

Word

<Description>

This instruction rotates the destination operand (general register Rd or memory contents) left through the C bit. The least significant bit of the destination operand receives the old value of the C bit. The most significant bit is rotated to become the new value of the C bit.



<Instruction Format>

EA	0 0 0 1 1 1 1 0
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination Yes Yes Yes Yes Yes Yes Yes Yes — —

2.2.40 ROTXR (ROTRate with eXtend carry Right)

ROTRate with eXtend carry Right

<Operation>

(EAd) rotated right through C bit → (EAd)

ROTXR

<Condition Code>

N	Z	V	C
↑	↑	0	↑

<Assembly-Language Format>

ROTXR <EAd>

(Example)

ROTXR.B @H'FA:8

<Operand Size>

Byte

Word

N: Set to "1" when the result is negative;
otherwise cleared to "0."

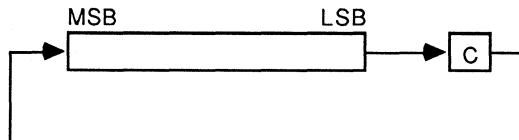
Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Receives the value shifted out from
the least significant bit.

<Description>

This instruction rotates the destination operand (general register Rd or memory contents) right through the C bit. The most significant bit of the destination operand receives the old value of the C bit. The least significant bit is rotated to become the new value of the C bit.



<Instruction Format>

EA	0 0 0 1 1 1 1 1
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.41 RTD (ReTurn and DeAllocate)

ReTurn and DeAllocate

<Operation>

$\text{@SP+} \rightarrow \text{PC}$
 $\text{SP + #IMM} \rightarrow \text{SP}$

RTD

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

RTD #xx
(Example)
RTD #4

- N: Previous value remains unchanged.
Z: Previous value remains unchanged.
V: Previous value remains unchanged.
C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction is used to return from a subroutine in the same page and deallocate the stack area used by the subroutine. It pops the program counter (PC) from the stack, then adjusts the stack pointer by adding immediate data specified in the instruction.

The immediate data value can be an 8-bit value from -128 to +127, or a 16-bit value from -32768 to +32767.

Note: When the stack is accessed an address error will occur if the stack pointer indicates an odd address. The immediate data should be an even number so that the stack pointer indicates an even address after execution of the RTD instruction.

<Instruction Format>

RTD #xx:8

0	0	0	1	0	1	0	0	data
---	---	---	---	---	---	---	---	------

RTD #xx:16

0	0	0	1	1	1	0	0	data (H)	data (L)
---	---	---	---	---	---	---	---	----------	----------

<Note>

The RTD instruction works efficiently with programs coded in high-level languages that use function routines. Besides returning from a function call, it can deallocate an argument area used by the function.

The RTD instruction can be broken down into more general instructions as follows.

```
RTD      #n    ⇨      RTS
        ADDS.W #n, SP
        (where n is the size of the argument area)
```

The usage of the RTD instruction in a program coded in C language is illustrated below.

Sample program

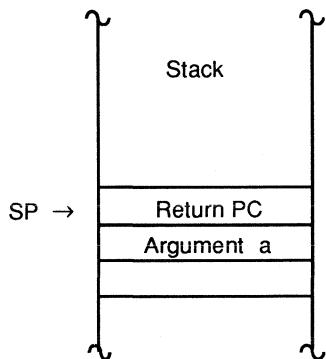
```
main () {
{
int a, b;
a = 10;
b = func(a); —— Function call with argument a.
}
func(x)
int x;
{
    function processing
}
```

In assembly language this program could be coded as follows.

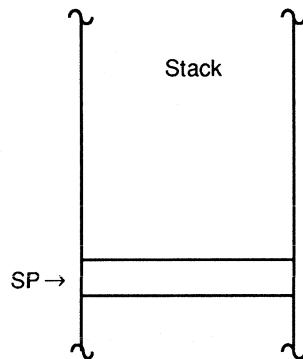
```
main:   MOV:I   #10,R0      — Pass argument to function via stack.
        MOV     R0,@-SP      —
        JSR     func
func:   MOV     @ (2,SP),R0 — Get argument a.
        function processing
RTD      #2           — Return and deallocate argument area.
```

<Note (Continued)>

The stack area during and after the function call is shown below.



During func() call.



After RTD

The PC is popped as in RTS,
then the stack pointer is
moved downward to
deallocate the argument a. In
this example the stack pointer
is incremented by 2.

2.2.42 RTE (ReTurn from Exception)

ReTurn from Exception	RTE				
<Operation>	<Condition Code>				
@SP+ → SR (if maximum mode then @SP+ → CP)	N Z V C <table border="1"><tr><td>↑</td><td>↑</td><td>↑</td><td>↑</td></tr></table>	↑	↑	↑	↑
↑	↑	↑	↑		
@SP+ → PC					
	N: Popped from stack. Z: Popped from stack. V: Popped from stack. C: Popped from stack.				
<Assembly-Language Format>					
RTE (Example) RTE					
<Operand Size>					
<Description>					
This instruction returns from an exception-handling routine. It pops the program counter (PC) and status register (SR) from the stack. In the maximum mode it also pops the code page register (CP).*					
Execution continues from the new address in the program counter (and code page register in maximum mode).					
Interrupts are not accepted and trace exception processing is not performed immediately after the end of this instruction.					
* The code page (CP) register is one byte in length. A full word is popped from the stack and the lower 8 bits are placed in the CP.					
<Instruction Format>					
0 0 0 0 1 0 1 0					

2.2.43 RTS (ReTurn from Subroutine)

ReTurn from Subroutine

<Operation>

@SP+ → PC

RTS

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

RTS

(Example)

RTS

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction is used to return from a subroutine in the same page. It pops the program counter (PC) from the stack. Execution continues from the new PC address.

This instruction can be used to return from a subroutine called by the BSR or JSR instruction.

<Instruction Format>

0	0	0	1	1	0	0	1
---	---	---	---	---	---	---	---

2.2.44 SCB (Subtract, Compare and Branch conditionally)

Subtract, Compare and Branch conditionally SCB

<Operation>

If condition is true then next;

else $R_n - 1 \rightarrow R_n$;

If $R_n = -1$ then next

else $PC + disp \rightarrow PC$;

<Condition Code>

N	Z	V	C
—	—	—	—

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Assembly-Language Format>

SCB/cc Rn,disp

Note: F (False), NE (Not Equal), or EQ (EQUAL) can be specified in the condition code field (cc). There are accordingly three mnemonics:

SCB/F, SCB/NE, and SCB/EQ

(Example)

SCB/EQ R4, LABEL

<Operand Size>

<Description>

This instruction is used for loop control. The condition code (cc) field can be set to create a pure counted loop (SCB/F), or a do-while or do-until (SCB/NE or SCB/EQ) loop with a limiting count.

If the specified condition (cc) is true, this instruction exits the loop by proceeding to the next instruction. Otherwise, it decrements the counter register (Rc) and exits the loop if the result is -1. When it does not exit the loop, this instruction branches to a relative address given by an 8-bit displacement value from -128 to +127.

The loop counter register (Rc) is decremented as a word register. The program counter (PC) value used in address calculation is the address of the instruction immediately following the SCB instruction.

Mnemonic	Description	Condition
SCB/F		False
SCB/NE	Not Equal	$Z = 0$
SCB/EQ	Equal	$Z = 1$

Subtract, Compare and Branch conditionally SCB

<Instruction Format>

SCB/F	0 0 0 0 0 0 0 1	1 0 1 1 1 r r r	disp
SCB/NE	0 0 0 0 0 1 1 0	1 0 1 1 1 r r r	disp
SCB/EQ	0 0 0 0 0 1 1 1	1 0 1 1 1 r r r	disp

Subtract, Compare and Branch conditionally SCB

<Note>

The general SCB instruction controls a loop with a counter register and the CCR bits as termination conditions. The H8/500 provides three SCB instructions: SCB/F, SCB/NE, and SCB/EQ.

- ① The SCB/F instruction can be broken down into the following more general instructions:

SCB/F Rn, LOOP	⇒	SUB.W #1,Rn
		CMP.W #-1,Rn
		BNE LOOP

If a loop count is set in Rn, this produces a simple counted loop. In the following example the loop is executed $9 + 1 = 10$ times. The final value left in R1 is 10.

MOV.W #9,R0	
CLR.W R1	
LO: ADD.W #1,R1	Start loop
SCB/F R0, LO	End loop

- ② The SCB/NE instruction can be broken down into the following more general instructions:

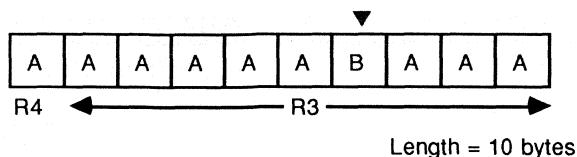
SCB/NE Rn, LOOP	⇒	BNE NEXT
		SUB.W #1,Rn
		CMP.W #-1,Rn
		BNE LOOP

NEXT:

In the following example a search for a value other than "A" is made in a block of the length indicated by general register R3 beginning at the address indicated by R4.

Subtract, Compare and Branch conditionally SCB

<Note (Continued)>



```

MOV.W      #9, R3
LO:   CMP.B      #'A', @R4+  Start loop
      SCB/NE    R3, LO      End loop
  
```

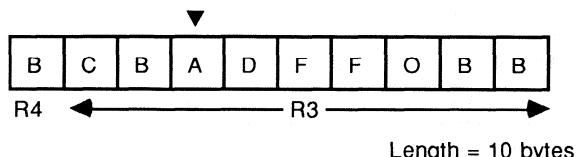
With the data shown, the loop executes 7 times and ends with the Z bit cleared to 0 and the value 3 in R3. The position of the first non-"A" data can be calculated as R4 + (10 – R3). If all the data were "A," the loop would end with the Z bit set to 1 and R3 = -1.

③ The SCB/EQ instruction can be broken down into the following more general instructions:

```

SCB/EQ Rn, LOOP ⇔          BEQ      NEXT
                           SUB.W    #1, Rn
                           CMP.W    #-1, Rn
                           BNE      LOOP
NEXT:
  
```

In the following example a search for the value "A" is made in a block of the length indicated by general register R3 beginning at the address indicated by R4.



```

MOV.W      #9, R3
LO:   CMP.B      #'A', @R4+  Start loop
      SCB/EQ    R3, LO      End loop
  
```

With the data shown, the loop executes 4 times and ends with the Z bit set to 1 and the value 6 in R3. The position of the first "A" can be calculated as R4 + (10 – R3). If there was no "A," the loop would end with the Z bit cleared to 0 and R3 = -1.

2.2.45 SHAL (SHift Arithmetic Left)

SHift Arithmetic Left

<Operation>

(EAd) shifted arithmetic left → (EAd)

SHAL

<Condition Code>

N	Z	V	C
↑	↑	↑	↑

<Assembly-Language Format>

SHAL <EAd>

(Example)

SHAL.B @R2+

<Operand Size>

Byte

Word

N: Set to "1" when the result is negative;
otherwise cleared to "0."

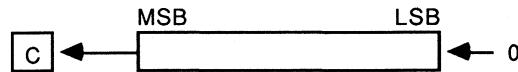
Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Set to "1" when the shift changes the
value of the most significant bit;
otherwise cleared to "0."

C: Set to the value shifted out from the
most significant bit.

<Description>

This instruction shifts the destination operand (general register Rd or memory contents) left, and sets the C bit to the value shifted out from the most significant bit. The least significant bit is cleared to "0."



<Instruction Format>

EA	0 0 0 1 1 0 0 0
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—							
-------------	-----	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.46 SHAR (SHift Arithmetic Right)

SHift Arithmetic Right

<Operation>

(EAd) shifted arithmetic right → (EAd)

SHAR

<Condition Code>

N	Z	V	C
↑	↑	0	↑

<Assembly-Language Format>

SHAR <EAd>

(Example)

SHAR.W @H'FF00

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Set to the value shifted out from the
least significant bit.

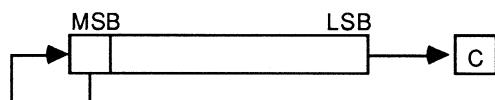
<Operand Size>

Byte

Word

<Description>

This instruction shifts the destination operand (general register Rd or memory contents) right, and sets the C bit to the value shifted out from the least significant bit. The most significant bit does not change, so the sign of the result remains the same.



<Instruction Format>

EA	0 0 0 1 1 0 0 1
----	-----------------

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.47 SHLL (SHift Logical Left)

SHift Logical Left

<Operation>

(EAd) shifted logical left → (EAd)

<Assembly-Language Format>

SHLL <EAd>

(Example)

SHLL.B R1

<Operand Size>

Byte

Word

SHLL

<Condition Code>

N	Z	V	C
↑	↑	0	↑

N: Set to "1" when the result is negative;
otherwise cleared to "0."

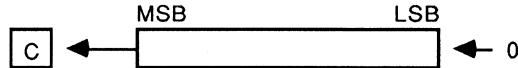
Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Set to the value shifted out from the
most significant bit.

<Description>

This instruction shifts the destination operand (general register Rd or memory contents) left, and sets the C bit to the value shifted out from the most significant bit. The least significant bit is cleared to 0. The only difference between this instruction and SHAL is that this instruction clears the V bit to "0."



<Instruction Format>

EA	0 0 0 1 1 0 1 0
----	-----------------

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.48 SHLR (SHift Logical Right)

SHift Logical Right

<Operation>

(EAd) shifted logical right → (EAd)

SHLR

<Condition Code>

N	Z	V	C
0	↑	0	↑

<Assembly-Language Format>

SHLR <EAd>

(Example)

SHLR.W @R1

N: Always cleared to 0.

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Set to the value shifted out from the
least significant bit.

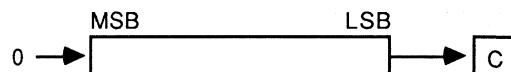
<Operand Size>

Byte

Word

<Description>

This instruction shifts the destination operand (general register Rd or memory contents) right, and sets the C bit to the value shifted out from the least significant bit. The most significant bit is cleared to 0.



<Instruction Format>

EA	0	0	0	1	1	0	1	1
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.49 SLEEP (SLEEP)

SLEEP

<Operation>

Normal operating mode → power-down mode

SLEEP

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

SLEEP

(Example)

SLEEP

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

When the SLEEP instruction is executed, the CPU enters the power-down mode. Its internal state remains unchanged, but the CPU stops executing instructions and waits for an exception handling request. When it receives such a request, the CPU exits the power-down mode and begins exception handling.

<Instruction Format>

0	0	0	1	1	0	1	0
---	---	---	---	---	---	---	---

2.2.50 STC (STore Control register)

STore Control register

<Operation>

CR → (EAd)

STC

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

STC CR, <EAd>

(Example)

STC.B BR, R0

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

(Depends on the control register)

<Description>

This instruction stores the contents of a control register (CR) to a general register or memory location (destination operand).

The operand size specified in the instruction depends on the control register as indicated in Table 1-12 in Section 1.3.6, "Register Specification."

<Instruction Format>

EA	1 0 0 1 1 c c c
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.51 STM (STore Multiple registers)

STore Multiple registers

<Operation>

Rs (register group) → @-SP (stack)

STM

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

STM <register list>, @-SP
(Example)

STM (R0-R3), @-SP

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Word

<Description>

This instruction pushes data from a specified list of general registers onto the stack. In the instruction code, the register list is encoded as one byte in which bits set to "1" indicate registers to be pushed. The highest-numbered register in the list is pushed first, the next-highest-numbered register second, and so on.

At the end of this instruction, general register R7 (the stack pointer) is updated to the value: (contents of R7 before this instruction) – 2 × (number of registers pushed). If the register list includes R7, the value pushed is (contents of R7 before this instruction) – 2.

<Instruction Format>

0	0	0	1	0	0	1	0	register list
---	---	---	---	---	---	---	---	---------------

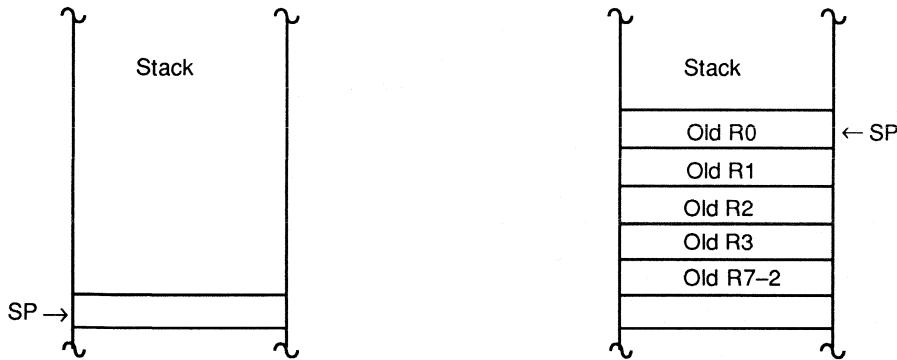
Register list

7	6	5	4	3	2	1	0
R7	R6	R5	R4	R3	R2	R1	R0

<Note>

The STM instruction can be used to save a group of registers to the stack at the beginning of exception handling routine or a subroutine. When there are many registers to save, the STM instruction is faster than the MOV instruction.

The status of the stack before and after an STM instruction is shown below.

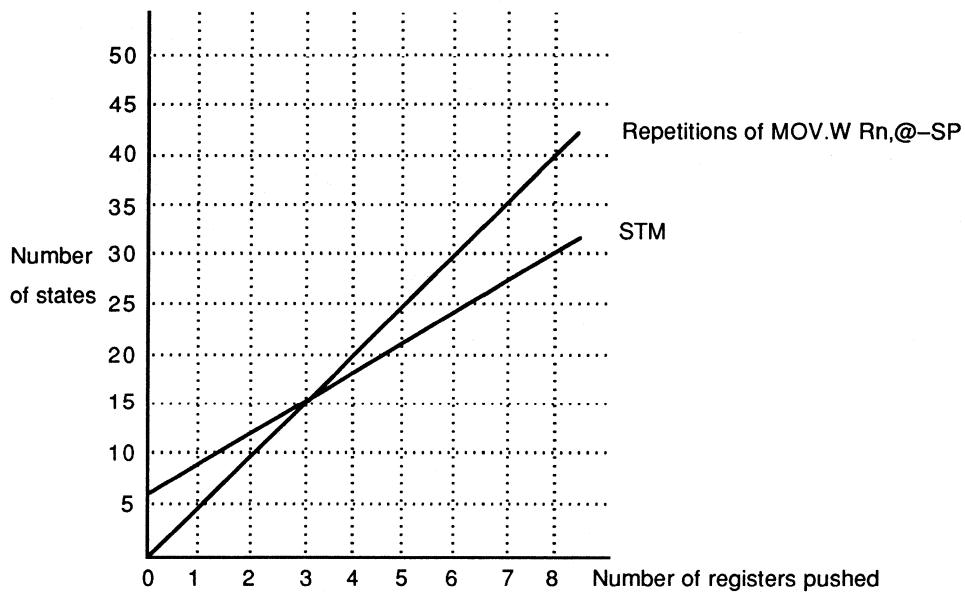
**Execution of STM (R0-R3, R7), @-SP**

If R7 (the stack pointer) is included in the register list, the value of R7 pushed on the stack is: (contents of R7 before the instruction) – 2. The value of R7 after execution of the instruction is: (contents of R7 before the instruction) – 2 × (number of registers restored).

Normally the STM instruction is paired with an LDM instruction which restores the registers. LDM does not, however, restore R7; it performs a dummy read instead. Accordingly, the program will execute faster if R7 is not specified in the register list.

<Note (Continued)>

The following graph compares the number of machine states required for execution of STM and execution of the same process using the MOV instruction.



Note: This graph is for the case in which instruction fetches and stack access are both to on-chip memory.

The STM instruction is faster when the number of registers is four or more. The MOV instruction is faster when there are only one or two registers to save. If the instruction fetches are to off-chip memory, the STM instruction is faster when there are two registers or more.

2.2.52 SUB (SUBtract binary)

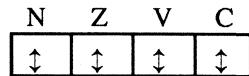
SUBtract binary

<Operation>

Rd - (EAs) → Rd

SUB

<Condition Code>



<Assembly-Language Format>

SUB <EAs>, Rd

(Example)

SUB.W @R1, R0

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Set to "1" if an overflow occurs;
otherwise cleared to "0."

C: Set to "1" if a borrow occurs;
otherwise cleared to "0."

<Operand Size>

Byte

Word

<Description>

This instruction subtracts a source operand from general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	0 0 1 1 0 r r r
----	-----------------

<Addressing Modes>

Rn @Rn @ (d:8,Rn) @ (d:16,Rn) @ -Rn @ Rn+ @ aa:8 @ aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.53 SUBS (SUBtract with Sign extension)

SUBtract with Sign extension

<Operation>

$Rd - (EAs) \rightarrow Rd$

<Assembly-Language Format>

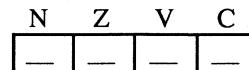
SUBS <EAs>, Rd

(Example)

SUBS.W #2, R2

SUBS

<Condition Code>



N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction subtracts the source operand from the contents of general register Rd (destination operand) and places the result in general register Rd.

Differing from the SUB instruction, this instruction does not alter the condition code.

If byte size is specified, the sign bit of the source operand is extended. The subtraction is performed using the resulting word data. General register Rd is always accessed as a word-size operand.

<Instruction Format>

EA	0	0	1	1	1	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.54 SUBX (SUBtract with eXtend carry)

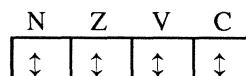
SUBtract with eXtend carry

<Operation>

Rd - (EAs) - C → Rd

SUBX

<Condition Code>



<Assembly-Language Format>

SUBX <EAs>, Rd

(Example)

SUBX.W @R2+, R0

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Set to "1" if an overflow occurs;
otherwise cleared to "0."

C: Set to "1" if a borrow occurs;
otherwise cleared to "0."

<Operand Size>

Byte

Word

<Description>

This instruction subtracts the source operand contents and the C bit from general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	1	0	1	1	0	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.55 SWAP (SWAP register halves)

SWAP register halves

<Operation>

Rd (upper byte) \leftrightarrow Rd (lower byte)

SWAP

<Condition Code>

N	Z	V	C
↑	↑	0	—

<Assembly-Language Format>

SWAP Rd

(Example)

SWAP R0

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

<Description>

This instruction interchanges the upper eight bits of general register Rd (destination register) with the lower eight bits.

<Instruction Format>

1	0	1	0	0	r	r	r	0	0	0	1	0	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

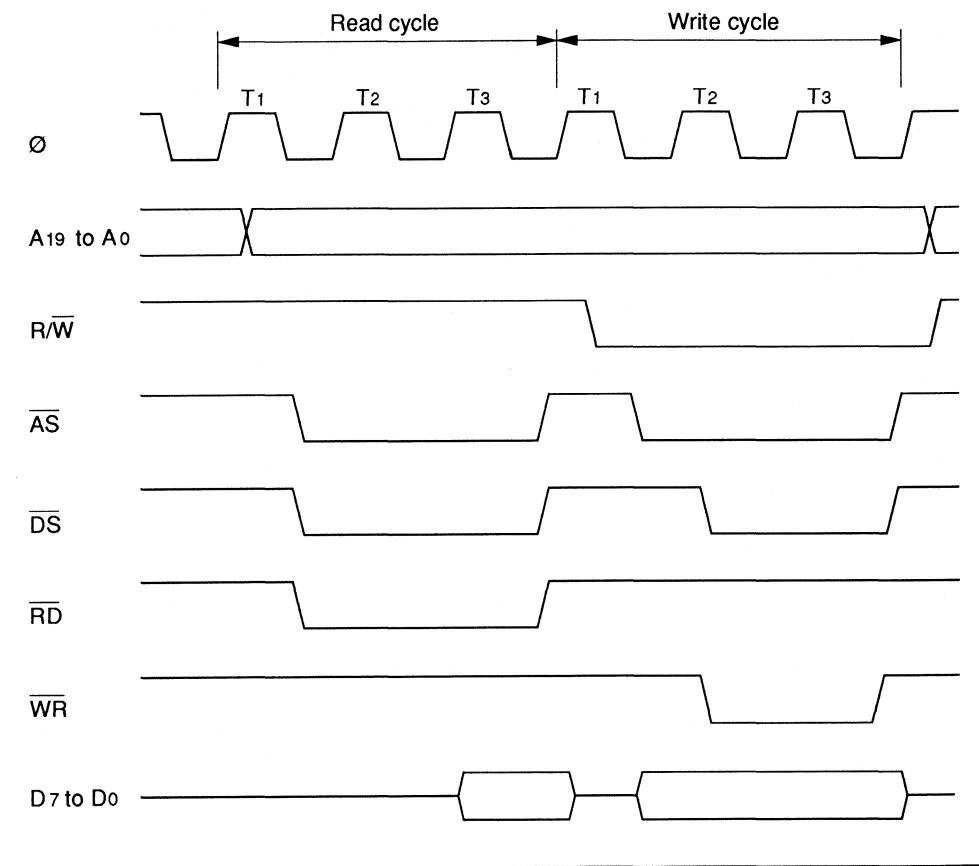
2.2.56 TAS (Test And Set)

Test And Set	TAS								
<Operation>	<Condition Code>								
Set CCR according to result of (EAd) – 0 (1) ₂ → (<bit 7> of <EAd>)	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>N</td> <td>Z</td> <td>V</td> <td>C</td> </tr> <tr> <td>↑</td> <td>↑</td> <td>0</td> <td>0</td> </tr> </table>	N	Z	V	C	↑	↑	0	0
N	Z	V	C						
↑	↑	0	0						
<Assembly-Language Format>	N: Set to "1" when the result is negative; otherwise cleared to "0." Z: Set to "1" when the result is zero; otherwise cleared to "0." V: Always cleared to 0. C: Always cleared to 0.								
TAS <EAd> (Example) TAS @H'F000									
<Operand Size>	Byte								
<Description>	This instruction tests a destination operand (general register Rd or memory contents) by comparing it with 0, sets the condition code register according to the result, then sets the most significant bit of the operand to "1."								
<Instruction Format>	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>EA</td> <td>0 0 0 1 0 1 1 1</td> </tr> </table>	EA	0 0 0 1 0 1 1 1						
EA	0 0 0 1 0 1 1 1								
<Addressing Modes>	Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16								
Destination	Yes Yes Yes Yes Yes Yes Yes Yes — —								

<Note>

Execution of the TAS instruction causes the CPU to perform the read-modify-write cycle shown below. No signal is output to indicate this cycle, but at the point between the read and write cycles the CPU will not accept interrupts and will not relinquish the bus. If an address error or other exception condition occurs during the read cycle, it is not handled until the write cycle has been executed.

The timing chart below is for access to off-chip memory by the H8/532.



2.2.57 TRAPA (TRAP Always)

TRAP Always

<Operation>

PC → @-SP

(If maximum mode then CP → @-SP)

SR → @-SP

(If maximum mode then <vector> → CP)

<vector> → PC

<Assembly-Language Format>

TRAPA #xx

(Example)

TRAPA #4

<Operand Size>

<Description>

This instruction generates a trap exception with a specified vector number.

When a TRAPA instruction is executed, the CPU initiates exception handling according to its current operating mode. In the minimum mode, it pushes the program counter (PC) and status register (SR) onto the stack, then indexes the vector table by the vector number specified in the instruction and copies the vector at that location to the program counter. In the maximum mode, it pushes the code page register* (CP), PC, and SR onto the stack and copies the vector to CP and PC.

* The code page register is byte size, but the stack and vector table are always accessed as word data. The lower eight bits are used.

TRAPA

<Condition Code>

N	Z	V	C
—	—	—	—

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

TRAP Always**TRAPA****<Instruction Format>**

0	0	0	0	1	0	0	0	1	:	#VEC
---	---	---	---	---	---	---	---	---	---	------

#VEC: A 4-bit number from 0 to 15 specifying an exception vector number according to the table below.

#VEC	Vector address		#VEC	Vector address	
	Minimum mode	Maximum mode		Minimum mode	Maximum mode
0	H'0020 – H'0021	H'0040 – H'0043	8	H'0030 – H'0031	H'0060 – H'0063
1	H'0022 – H'0023	H'0044 – H'0047	9	H'0032 – H'0033	H'0064 – H'0067
2	H'0024 – H'0025	H'0048 – H'004B	10	H'0034 – H'0035	H'0068 – H'006B
3	H'0026 – H'0027	H'004C – H'004F	11	H'0036 – H'0037	H'006C – H'006F
4	H'0028 – H'0029	H'0050 – H'0053	12	H'0038 – H'0039	H'0070 – H'0073
5	H'002A – H'002B	H'0054 – H'0057	13	H'003A – H'003B	H'0074 – H'0077
6	H'002C – H'002D	H'0058 – H'005B	14	H'003C – H'003D	H'0078 – H'007B
7	H'002E – H'002F	H'005C – H'005F	15	H'003E – H'003F	H'007C – H'007F

2.2.58 TRAP/V_S (TRAP if oVerflow)

TRAP if oVerflow bit is Set

<Operation>

If V bit is set then TRAP
else next;

TRAP/V_S

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

TRAP/V_S
(Example)
TRAP/V_S

N: Previous value remains unchanged.

Z: Previous value remains unchanged.

V: Previous value remains unchanged.

C: Previous value remains unchanged.

<Operand Size>

<Description>

When this instruction is executed, the CPU checks the CCR (condition code register) and initiates exception handling if the V bit is set to "1". If the V bit is cleared, execution proceeds to the next instruction without an exception.

The vector address of the exception generated by a TRAP/V_S instruction is shown below.

Minimum mode	Maximum mode
H'0008 – H'0009	H'0010 – H'0013

<Instruction Format>

0	0	0	0	1	0	0	1
---	---	---	---	---	---	---	---

2.2.59 TST (TeST)

TeST

<Operation>

Set CCR according to result of (EAd) – 0

TST

<Condition Code>

N	Z	V	C
↑	↑	0	0

<Assembly-Language Format>

TST <EAd>

(Example)

TST @ (H'1000, R1)

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Always cleared to 0.

<Operand Size>

Byte

Word

<Description>

This instruction compares the destination operand (general register Rd or memory contents) with 0 and sets the condition code register according to the result. It does not modify the destination operand.

<Instruction Format>

EA	0 0 0 1 0 1 1 0
----	-----------------

<Addressing Modes>

Rn @Rn@(d:8,Rn)@(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Destination	Yes	—	—						
-------------	-----	-----	-----	-----	-----	-----	-----	---	---

2.2.60 UNLK (UNLinK)

UNLinK

<Operation>

FP (R6) → SP
@SP+ → FP (R6)

UNLK

<Condition Code>

N	Z	V	C
—	—	—	—

<Assembly-Language Format>

UNLK FP
(Example)
UNLK FP

- N: Previous value remains unchanged.
Z: Previous value remains unchanged.
V: Previous value remains unchanged.
C: Previous value remains unchanged.

<Operand Size>

<Description>

This instruction deallocates a stack frame created by a LINK instruction.

It copies the frame pointer (FP = R6) contents to the stack pointer (SP = R7), then pops the top word in the new stack area (the FP saved by the LINK instruction) to the frame pointer.

<Instruction Format>

0	0	0	0	1	1	1	1
---	---	---	---	---	---	---	---

2.2.61 XCH (eXCHange registers)

eXCHange register	XCH				
<Operation>	<Condition Code>				
Rs ↔ Rd	N Z V C <table border="1"><tr><td>—</td><td>—</td><td>—</td><td>—</td></tr></table>	—	—	—	—
—	—	—	—		
<Assembly-Language Format>					
XCH Rs, Rd	N: Previous value remains unchanged.				
(Example)	Z: Previous value remains unchanged.				
XCH R0, R1	V: Previous value remains unchanged.				
	C: Previous value remains unchanged.				
<Operand Size>					
Word					
<Description>	This instruction interchanges the contents of two general registers.				
<Instruction Format>					
1 0 1 0 1 r _s r _s r _s 1 0 0 1 0 r _d r _d r _d					
<Addressing Modes>	Rn @Rn @(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16				
Source Yes	— — — — — — — — — —				
Destination Yes	— — — — — — — — — —				

2.2.62 XOR (eXclusive OR logical)

eXclusive OR logical

<Operation>

Rd \oplus (EAs) \rightarrow Rd

XOR

<Condition Code>

N	Z	V	C
↓	↓	0	—

<Assembly-Language Format>

XOR <EAs>, Rd

(Example)

XOR.B @H'A0:8, R0

N: Set to "1" when the result is negative;
otherwise cleared to "0."

Z: Set to "1" when the result is zero;
otherwise cleared to "0."

V: Always cleared to 0.

C: Previous value remains unchanged.

<Operand Size>

Byte

Word

<Description>

This instruction obtains the logical exclusive OR of the source operand and the contents of general register Rd (destination operand) and places the result in general register Rd.

<Instruction Format>

EA	0	1	1	0	0	r	r	r
----	---	---	---	---	---	---	---	---

<Addressing Modes>

Rn @Rn@(d:8,Rn) @(d:16,Rn)@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16

Source	Yes									
Destination	Yes	—	—	—	—	—	—	—	—	—

2.2.63 XORC (eXclusive OR Control register)

eXclusive OR Control register	XORC								
<Operation>	<Condition Code>								
$CR \oplus \#IMM \rightarrow CR$	<table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td>N</td><td>Z</td><td>V</td><td>C</td></tr> <tr> <td>Δ</td><td>Δ</td><td>Δ</td><td>Δ</td></tr> </table>	N	Z	V	C	Δ	Δ	Δ	Δ
N	Z	V	C						
Δ	Δ	Δ	Δ						
<Assembly-Language Format>									
XORC #xx, CR (Example) XORC.B #H'01, CCR	<p>(1) When CR is the status register (SR or CCR), the N, Z, V, and C bits are set according to the result of the operation.</p> <p>(2) When CR is not the status register (EP, TP, DP, or BR), the bits are set as below.</p> <p>N: Set to "1" when the MSB of the result is "1;" otherwise cleared to "0."</p> <p>Z: Set to "1" when the result is zero; otherwise cleared to "0."</p> <p>V: Always cleared to 0.</p> <p>C: Previous value remains unchanged.</p>								
<Operand Size>									
Byte Word (Depends on the control register)									
<Description>	<p>This instruction exclusive-ORs the contents of a control register (CR) with immediate data and places the result in the control register.</p> <p>The operand size specified in the instruction depends on the control register as indicated in Table 1-12 in Section 1.3.6, "Register Specification."</p> <p>Interrupts are not accepted and trace exception processing is not performed immediately after the end of this instruction.</p>								
<Instruction Formats>									
XORC #xx:8, CR XORC #xx:16, CR	<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 30%;">0 0 0 0 0 1 0 0</td> <td style="width: 20%;">data</td> <td style="width: 50%;">0 1 1 0 1 c c c</td> </tr> <tr> <td>0 0 0 0 1 1 0 0</td> <td>data (H)</td> <td>data (L) 0 1 1 0 1 c c c</td> </tr> </table>	0 0 0 0 0 1 0 0	data	0 1 1 0 1 c c c	0 0 0 0 1 1 0 0	data (H)	data (L) 0 1 1 0 1 c c c		
0 0 0 0 0 1 0 0	data	0 1 1 0 1 c c c							
0 0 0 0 1 1 0 0	data (H)	data (L) 0 1 1 0 1 c c c							
<Addressing Modes>	Rn @Rn @((d:8,Rn)) @((d:16,Rn))@-Rn @Rn+ @aa:8 @aa:16 #xx:8 #xx:16								
Source	— — — — — — — Yes Yes								

2.3 Instruction Codes

Table 2-1 shows the machine-language coding of each instruction.

- **How to read Table 2-1 (a) to (d).**

The general operand format consists of an effective address (EA) field and operation-code (OP) field specified in the following order:



Bytes 2, 3, 5, 6 are not present in all instructions.

Instruction		Addressing mode												Operation code (EA)			Operation code (OP)		
		1			2			3			4			5			6		
instruction	MOV:G.B <EAs>,Rd	Rn	1 0 1 0	Sz r r r										1 0 0 0 0	r _d	r _d	r _d		
	MOV:G.W <EAs>,Rd	@Rn	1 1 0 1	Sz r r r										1 0 0 0 0	r _d	r _d	r _d		
	MOV:G.B Rs,<EAd>	(@d:8,Rn)	1 1 1 0	Sz r r r	disp									1 0 0 1 0	r _s	r _s	r _s		
	MOV:G.W Rs,<EAd>	1 0 1 1	Sz r r r	disp (H)										1 0 0 1 0	r _s	r _s	r _s		
Byte length of instruction														Shading indicates addressing modes not available for this instruction.					

Some instructions have a special format in which the operation code comes first.

The following notation is used in the tables.

- Sz: Operand size (byte or word)
 - Byte: Sz = 0
 - Word: Sz = 1

- **r r r:** General register number field

r r r	Sz = 0 (Byte)	Sz = 1 (Word)
0 0 0	15 8 7 0 Not used R0	15 0 R0
0 0 1	Not used R1	R1
0 1 0	Not used R2	R2
0 1 1	Not used R3	R3
1 0 0	Not used R4	R4
1 0 1	Not used R5	R5
1 1 0	Not used R6	R6
1 1 1	Not used R7	R7

- **c c c:** Control register number field

c c c	Sz = 0 (Byte)	Sz = 1 (Word)
0 0 0	(Not allowed*) 7 0	15 0 SR
0 0 1	CCR	(Not allowed)
0 1 0	(Not allowed)	(Not allowed)
0 1 1	BR	(Not allowed)
1 0 0	EP	(Not allowed)
1 0 1	DP	(Not allowed)
1 1 0	(Not allowed)	(Not allowed)
1 1 1	TP	(Not allowed)

- * "Disallowed" means that this combination of bits must not be specified. Specifying a disallowed combination may cause abnormal results.

- register list: A byte in which bits indicate general registers as follows

Bit:	7	6	5	4	3	2	1	0
	R7	R6	R5	R4	R3	R2	R1	R0

- #VEC: Four bits designating a vector number from 0 to 15. The vector numbers correspond to addresses of entries in the exception vector table as follows:

#VEC	Vector address		#VEC	Vector address	
	Minimum mode	Maximum mode		Minimum mode	Maximum mode
0	H'0020 – H'0021	H'0040 – H'0043	8	H'0030 – H'0031	H'0060 – H'0063
1	H'0022 – H'0023	H'0044 – H'0047	9	H'0032 – H'0033	H'0064 – H'0067
2	H'0024 – H'0025	H'0048 – H'004B	10	H'0034 – H'0035	H'0068 – H'006B
3	H'0026 – H'0027	H'004C – H'004F	11	H'0036 – H'0037	H'006C – H'006F
4	H'0028 – H'0029	H'0050 – H'0053	12	H'0038 – H'0039	H'0070 – H'0073
5	H'002A – H'002B	H'0054 – H'0057	13	H'003A – H'003B	H'0074 – H'0077
6	H'002C – H'002D	H'0058 – H'005B	14	H'003C – H'003D	H'0078 – H'007B
7	H'002E – H'002F	H'005C – H'005F	15	H'003E – H'003F	H'007C – H'007F

- Examples of machine-language coding

Example 1: ADD:G.B @R0,R1

	EA field	OP field
Table 2.1 (a)	1 1 0 1 S z r r r	0 0 1 0 0 r d r d r d
Machine code	1 1 0 1 0 0 0 0	0 0 1 0 0 0 0 1
		H'D021

Example 2: ADD:G.W @H'11:8,R1

	EA field	OP field
Table 2.1 (a)	0 0 0 0 S z 1 0 1	0 0 0 1 0 0 0 1
Machine code	0 0 0 0 1 1 0 1	0 0 0 1 0 0 0 1
		H'0D1121

Table 2-1 (a) Machine Language Coding [General Format] (1)

Instruction		Operation code (EA)												Operation code (OP)					
		Addressing mode		1		2		3		4		5		6					
MOV:G.B <EA _s >,Rd	Rn	1 0 1 0 S _z r r r												1 0 0 0 0 r _d r _d r _d					
MOV:G.W <EA _s >,Rd	@Rn	1 1 0 1 S _z r r r												1 0 0 0 0 r _d r _d r _d					
MOV:G.B Rs,<EA _d >	(d:8,Rn)	1 1 1 0 S _z r r r	disp											1 0 0 1 0 r _s r _s r _s					
MOV:G.W Rs,<EA _d >	(d:16,Rn)	1 1 1 1 S _z r r r	disp (H)											1 0 0 1 0 r _s r _s r _s					
MOV:G.B #xx:8,<EA _d >	(d:8)	1 0 1 1 S _z r r r												0 0 0 0 0 1 1 0					
MOV:G.W #xx:8,<EA _d >	(d:16)	1 1 0 0 S _z r r r												0 0 0 0 0 1 1 0					
MOV:G.W #xx:16,<EA _d >	#xx:16	0 0 0 0 S _z 1 0 1	address											0 0 0 0 0 1 1 1					
LDM.W @SP+,<register list>														0 0 0 0 0 0 1 0					
STM.W <register list>,@-SP														0 0 0 0 0 0 1 0					
XCH.W Rs,Rd														1 0 0 1 0 r _d r _d r _d					
SWAP.B Rd														0 0 0 1 0 0 0					
MOVTP.E.B Rs,<EA _d > ^{*1}														0 0 0 0 0 0 0 0	1 0 0 1 0 r _s r _s r _s				
MOVTP.E.B <EA _s >,Rd ^{*1}														0 0 0 0 0 0 0 0	1 0 0 0 0 r _d r _d r _d				
ADD:G.B <EA _s >,Rd														0 0 1 0 0 r _d r _d r _d					
ADD:G.W <EA _s >,Rd														0 0 0 1 0 0 0 r _d r _d r _d					
ADD:Q.B #1,<EA _d > ^{*2}														0 0 0 0 1 0 0 0					
ADD:Q.W #1,<EA _d > ^{*2}														0 0 0 0 1 0 0 0					
ADD:Q.B #2,<EA _d > ^{*2}														0 0 0 0 1 0 0 1					
ADD:Q.W #2,<EA _d > ^{*2}														0 0 0 0 1 0 0 1					
ADD:Q.B #-1,<EA _d > ^{*2}														0 0 0 0 1 1 0 0					
ADD:Q.W #-1,<EA _d > ^{*2}														0 0 0 0 1 1 0 0					
ADD:Q.B #2,<EA _d > ^{*2}														0 0 0 0 1 1 0 1					
ADD:Q.W #2,<EA _d > ^{*2}														0 0 0 0 1 1 0 1					
ADDS.B <EA _s >,Rd														0 0 1 0 1 r _d r _d r _d					
ADDS.W <EA _s >,Rd														0 0 0 1 0 1 r _d r _d r _d					
ADDX.B <EA _s >,Rd														1 0 1 0 0 r _d r _d r _d					
ADDX.W <EA _s >,Rd														1 0 1 0 0 r _d r _d r _d					

Notes: 1. Not supported by the H8/520.

2. Short format instruction.

Table 2-1 (a) Machine Language Coding [General Format] (2)

Instruction	Addressing mode	Operation code (EA)						Operation code (OP)			
		1		2		3		4		5	
		Rn	1 0 1 0 S ₂ Z r r r	@Rn	1 1 0 1 S ₂ Z r r r	(d:8, Rn)	1 1 1 0 S ₂ Z r r r	disp	1 1 1 1 S ₂ Z r r r	disp (H)	1 0 1 1 0 r _d r _d r _d
Arithmetic operation instruction	(@:16, Rn)										
DADD.B Rs,Rd	3								0 0 0 0 0 0 0 0	1 0 1 0 0 r _d r _d r _d	
SUB.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	3 4	0 0 1 1 0 r _d r _d r _d		
SUB.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 1 1 0 r _d r _d r _d		
SUBS.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 1 1 1 r _d r _d r _d		
SUBS.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 1 1 1 r _d r _d r _d		
SUBX.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 1 0 r _d r _d r _d		
SUBX.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 1 0 r _d r _d r _d		
DSUB.B Rs,Rd	3								0 0 0 0 0 0 0 0	1 0 1 1 0 r _d r _d r _d	
MULXU.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 0 1 r _d r _d r _d		
MULXU.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 0 1 r _d r _d r _d		
DIVXU.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 1 1 r _d r _d r _d		
DIVXU.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	1 0 1 1 1 r _d r _d r _d		
CMP.G.B <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 1 1 1 0 r _d r _d r _d		
CMP.G.W <EA>,Rd	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 1 1 1 0 r _d r _d r _d		
CMP.G.B #xx,<EAd>	3 4 5 3 3 4	5 3 3 4	5						0 0 0 0 0 1 0 0	data	
CMP.G.W #xx,<EAd>	4 5 6 4 4 5	6 4 4 5	6						0 0 0 0 0 1 0 1	data (H)	data (L)
EXTS.B Rd	2									0 0 0 1 0 0 0 1	
EXTU.B Rd	2									0 0 0 1 0 0 1 0	
TST.B <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 1 1 0		
TST.W <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 1 1 0		
NEG.B <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 1 0 0		
NEG.W <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 1 0 0		
CLR.B <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 0 1 1		
CLR.W <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 0 1 1		
TAS.B <EAd>	2 2 3 4	2 2 3 4	2 2 3 4	2 2 3 4	3 4	3 4	3 4	3 4	0 0 0 1 0 1 1 1		

Table 2-1 (a) Machine Language Coding [General Format] (3)

Instruction		Addressing mode				Operation code (EA)				Operation code (OP)			
		1		2		3		4		5		6	
Shift instruction	SHAL.B <EAd>	2	2	3	4	2	2	3	4	00011000			
	SHAL.W <EAd>	2	2	3	4	2	2	3	4	00011000			
	SHAR.B <EAd>	2	2	3	4	2	2	3	4	00011001			
	SHAR.W <EAd>	2	2	3	4	2	2	3	4	00011001			
	SHLL.B <EAd>	2	2	3	4	2	2	3	4	00011010			
	SHLL.W <EAd>	2	2	3	4	2	2	3	4	00011010			
	SHLR.B <EAd>	2	2	3	4	2	2	3	4	00011011			
	SHLR.W <EAd>	2	2	3	4	2	2	3	4	00011011			
	ROTL.B <EAd>	2	2	3	4	2	2	3	4	00011100			
	ROTL.W <EAd>	2	2	3	4	2	2	3	4	00011100			
	ROTR.B <EAd>	2	2	3	4	2	2	3	4	00011101			
	ROTR.W <EAd>	2	2	3	4	2	2	3	4	00011101			
	ROTXL.B <EAd>	2	2	3	4	2	2	3	4	00011110			
	ROTXL.W <EAd>	2	2	3	4	2	2	3	4	00011110			
	ROTXR.B <EAd>	2	2	3	4	2	2	3	4	00011111			
	ROTXR.W <EAd>	2	2	3	4	2	2	3	4	00011111			
Logic operation instruction	AND.B <EAs>,Rd	2	2	3	4	2	2	3	4	3	01010 r dr dr d		
	AND.W <EAs>,Rd	2	2	3	4	2	2	3	4	4	01010 r dr dr d		
	OR.B <EAs>,Rd	2	2	3	4	2	2	3	4	3	01000 r dr dr d		
	OR.W <EAs>,Rd	2	2	3	4	2	2	3	4	4	01000 r dr dr d		
	XOR.B <EAs>,Rd	2	2	3	4	2	2	3	4	3	01100 r dr dr d		
	XOR.W <EAs>,Rd	2	2	3	4	2	2	3	4	4	01100 r dr dr d		
	NOT.B <EAd>	2	2	3	4	2	2	3	4		00010101		
	NOT.W <EAd>	2	2	3	4	2	2	3	4		00010101		

Table 2-1 (a) Machine Language Coding [General Format] (4)

Instruction		Addressing mode				Operation code (EA)				Operation code (OP)			
		1	2	3	4	5	6			4	5	6	
Bit manipulate instruction	BSET.B #xx,<EAd>	2	2	3	4	2	2	3	4	1100	data		
	BSET.W #xx,<EAd>	2	2	3	4	2	2	3	4	1100	data		
	BSET.B Rs,<EAd>	2	2	3	4	2	2	3	4	01001	rsrsrs		
	BSET.W Rs,<EAd>	2	2	3	4	2	2	3	4	01001	rsrsrs		
	BCLR.B #xx,<EAd>	2	2	3	4	2	2	3	4	1101	data		
	BCLR.W #xx,<EAd>	2	2	3	4	2	2	3	4	1101	data		
	BCLR.B Rs,<EAd>	2	2	3	4	2	2	3	4	01011	rsrsrs		
	BCLR.W Rs,<EAd>	2	2	3	4	2	2	3	4	01011	rsrsrs		
	BTST.B #xx,<EAd>	2	2	3	4	2	2	3	4	1111	data		
	BTST.W #xx,<EAd>	2	2	3	4	2	2	3	4	1111	data		
	BTST.B Rs,<EAd>	2	2	3	4	2	2	3	4	01111	rsrsrs		
	BTST.W Rs,<EAd>	2	2	3	4	2	2	3	4	01111	rsrsrs		
	BNOT.B #xx,<EAd>	2	2	3	4	2	2	3	4	1110	data		
	BNOT.W #xx,<EAd>	2	2	3	4	2	2	3	4	1110	data		
	BNOT.B Rs,<EAd>	2	2	3	4	2	2	3	4	01101	rsrsrs		
	BNOT.W Rs,<EAd>	2	2	3	4	2	2	3	4	01101	rsrsrs		
System control instruction	LDC.B <EAs>,CR	2	2	3	4	2	2	3	4	3	10001	cccc	
	LDC.W <EAs>,CR	2	2	3	4	2	2	3	4	4	10001	cccc	
	STC.B CR,<EAd>	2	2	3	4	2	2	3	4		10011	cccc	
	STC.W CR,<EAd>	2	2	3	4	2	2	3	4		10011	cccc	
	ANDC.B #xx:8, CR								3		01011	cccc	
	ANDC.W #xx:16, CR								4		01011	cccc	
	ORC.B #xx:8, CR								3		01001	cccc	
	ORC.W #xx:16, CR								4		01001	cccc	
XORC.B #xx:8, CR									3		01101	cccc	
									4		01101	cccc	

Table 2-1 (b) Machine Language Coding [Special Format: Short Format]

Instruction	Byte	Operation code			
		1	2	3	4
MOV:E.B #xx:8,Rd	2	0 1 0 1 0 r _d r _d r _d	data		
MOV:I.W #xx:16,Rd	3	0 1 0 1 1 r _d r _d r _d	data (H)	data (L)	
MOV:L.B @aa:8,Rd	2	0 1 1 0 0 r _d r _d r _d	address (L)		
MOV:L.W @aa:8,Rd	2	0 1 1 0 1 r _d r _d r _d	address (L)		
MOV:S.B Rs,@aa:8	2	0 1 1 1 0 r _s r _s r _s	address (L)		
MOV:S.W Rs,@aa:8	2	0 1 1 1 1 r _s r _s r _s	address (L)		
MOV:F.B @(d:8,R6),Rd	2	1 0 0 0 0 r _d r _d r _d	disp		
MOV:F.W @(d:8,R6),Rd	2	1 0 0 0 1 r _d r _d r _d	disp		
MOV:F.B Rs,@(d:8,R6)	2	1 0 0 1 0 r _s r _s r _s	disp		
MOV:F.W Rs,@(d:8,R6)	2	1 0 0 1 1 r _s r _s r _s	disp		
CMP:E.B #xx:8,Rd	2	0 1 0 0 0 r _d r _d r _d	data		
CMP:I.W #xx:16,Rd	3	0 1 0 0 1 r _d r _d r _d	data (H)	data (L)	

Table 2-1 (c) Machine Language Coding [Special Format: Branch Instructions] (1)

Instruction		Byte	Operation code			
			1	2	3	4
Bcc d:8	BRA (BT)	2	00100000	disp		
	BRN (BF)		00100001	disp		
	BHI		00100010	disp		
	BLS		00100011	disp		
	BCC (BHS)		00100100	disp		
	BCS (BLO)		00100101	disp		
	BNE		00100110	disp		
	BEQ		00100111	disp		
	BVC		00101000	disp		
	BVS		00101001	disp		
	BPL		00101010	disp		
	BMI		00101011	disp		
	BGE		00101100	disp		
	BLT		00101101	disp		
	BGT		00101110	disp		
	BLE		00101111	disp		
Bcc d:16	BRA (BT)	3	00110000	disp(H)	disp(L)	
	BRN (BF)		00110001	disp(H)	disp(L)	
	BHI		00110010	disp(H)	disp(L)	
	BLS		00110011	disp(H)	disp(L)	
	BCC (BHS)		00110100	disp(H)	disp(L)	
	BCS (BLO)		00110101	disp(H)	disp(L)	
	BNE		00110110	disp(H)	disp(L)	
	BEQ		00110111	disp(H)	disp(L)	
	BVC		00111000	disp(H)	disp(L)	
	BVS		00111001	disp(H)	disp(L)	
	BPL		00111010	disp(H)	disp(L)	
	BMI		00111011	disp(H)	disp(L)	
	BGE		00111100	disp(H)	disp(L)	
	BLT		00111101	disp(H)	disp(L)	
	BGT		00111110	disp(H)	disp(L)	
	BLE		00111111	disp(H)	disp(L)	
JMP @Rn		2	00010001	11010 r r r		
JMP @aa:16		3	00010000	address(H)	address(L)	

Table 2-1 (c) Machine Language Coding [Special Format: Branch Instructions] (2)

Instruction	Byte	Operation code			
		1	2	3	4
JMP @(d:8,Rn)	3	00010001	11100rrrr	disp	
JMP @(d:16,Rn)	4	00010001	11110rrrr	disp(H)	disp(L)
BSR d:8	2	00001110	disp		
BSR d:16	3	00011110	disp(H)	disp(L)	
JSR @Rn	2	00010001	11011rrrr		
JSR @aa:16	3	00011000	address(H)	address(L)	
JSR @(d:8,Rn)	3	00010001	11101rrrr	disp	
JSR @(d:16,Rn)	4	00010001	11111rrrr	disp(H)	disp(L)
RTS	1	00011001			
RTD #xx:8	2	00010100	data		
RTD #xx:16	3	00011100	data (H)	data (L)	
SCB/cc Rn, disp	SCB/F	00000001	10111rrrr	disp	
		00000110	10111rrrr	disp	
		00000111	10111rrrr	disp	
PJMP @aa:24	4	00010011	page	address(H)	address(L)
PJMP @Rn	2	00010001	11000rrrr		
PJSR @aa:24	4	00000011	page	address(H)	address(L)
PJSR @Rn	2	00010001	11001rrrr		
PRTS	2	00010001	00011001		
PRTD #xx:8	3	00010001	00010100	data	
PRTD #xx:16	4	00010001	00011100	data (H)	data (L)

Table 2-1 (d) Machine Language Coding [Special Format: System Control Instructions]

Instruction	Byte	Operation code			
		1	2	3	4
TRAPA #xx	2	00001000	0001#VEC		
TRAP/V\$	1	00001001			
RTE	1	00001010			
LINK FP,#xx:8	2	00010111	data		
LINK FP,#xx:16	3	00011111	data (H)	data (L)	
UNLK FP	1	00001111			
SLEEP	1	00011010			
NOP	1	00000000			

2.4 Operation Code Map

Tables 2-2 through 2-6 are a map of the operation codes. Table 2-2 shows the meaning of the first byte of the instruction code, indicating both operation codes and addressing modes. Tables 2-2 through 2-6 indicate the meanings of operation codes in the second and third bytes.

Table 2-2 Operation Codes in Byte 1

HI	LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	NOP	SCB/F See Tbl. 2-6	LDM	PJSR @aa:24	#xx:8 See Tbl. 2-5	#aa:8.B See Tbl. 2-4	SCB/N/E See Tbl. 2-6	SCB/EQ See Tbl. 2-6	TRAPA	TRAPNS	RTE			#xx:16 See Tbl. 2-5	@aa:8.W See Tbl. 2-4	BSR d:8	UNLK
1	JMP	See Tbl. 2-6	STM	PJMP @aa:24	RTD #xx:8 Tbl. 2-4	@aa:16.B See Tbl. 2-4	LINK #xx:8 Tbl. 2-4	JSR	RTS	SLEEP			RTD #xx:16 See Tbl. 2-4	@aa:16.W See Tbl. 2-4	BSR d:16	LINK #xx:16	
2	BRA	BRN	BHI	BLS	Bcc	BCS	BNE	BEQ	BVC	BVS	BPL	BMI	BGE	BLT	BGT	BLE	
3	BRA d:16	BRN	BHI	BLS	Bcc	BCS	BNE	BEQ	BVC	BVS	BPL	BMI	BGE	BLT	BGT	BLE	
4	R0	R1	R2	R3	R4	R5	R6	R7	R0	R1	R2	R3	R4	R5	R6	R7	
5		MOVE #xx:8, Rn								MOVE:I #xx:16, Rn							
6		MOV:L.B @aa:8, Rn								MOV:L.W @aa:8, Rn							
7		MOV:S.B Rn, @aa:8								MOV:S.W Rn, @aa:8							
8		MOV:F.B @ (d8, R6), Rn								MOV:F.W @ (d8, R6), Rn							
9		MOV:F.B Rn, @ (d8, R6)								MOV:F.W Rn, @ (d8, R6)							
A		Rn		(Byte)		See Table 2-3			Rn		(Word)					See Table 2-3	
B		@-Rn		(Byte)		See Table 2-4			@-Rn		(Word)					See Table 2-4	
C		@Rn+		(Byte)		See Table 2-4			@Rn+		(Word)					See Table 2-4	
D		@Rn		(Bye)		See Table 2-4			@Rn		(Word)					See Table 2-4	
E		@(d8,Rn)		(Bye)		See Table 2-4			@(d8,Rn)		(Word)					See Table 2-4	
F		@(d16,Rn)		(Bye)		See Table 2-4			@(d16,Rn)		(Word)					See Table 2-4	

Notes:

References to Tables 2-3 through 2-6 indicate that the instruction code has one or more additional bytes, described in those tables.

- * H'11 is the first operation code byte of the following instructions:
- JMP, JSR, PJSR (register indirect addressing mode)
- JMP, JSR (register indirect addressing mode with displacement)
- PRTS, PRTD (all addressing modes)

Table 2-3 Operation Codes in Byte 2 (Axx)

HI	LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	See Tbl. 2-6*																
1	SWAP	EXTS	EXTU	CLR	NEG	NOT	TST	TAS	SHAL	SHAR	SHLL	SHLR	ROTL	ROTR	ROTXL	ROTXR	
2	R0	R1	R2	R3	R4	R5	R6	R7	R0	R1	R2	R3	R4	R5	R6	R7	
3		SUB							SUBS								
4		OR								BSET (Register indirect specification of bit number)							
5		AND								BCLR (Register indirect specification of bit number)							
6		XOR								BNOT (Register indirect specification of bit number)							
7		CMP								BTST (Register indirect specification of bit number)							
8		MOV								LDC							
9		XCH								STC							
A		ADDX								MULXU							
B		SUBX								DIVXU							
C	b0	b1	b2	b3	b4	b5	b6	b7	b8	b9	b10	b11	b12	b13	b14	b15	
D									BCLR (Immediate specification of bit number)								
E									BNOT (Immediate specification of bit number)								
F									BTST (Immediate specification of bit number)								

Note: * The operation code is in byte 3, given in Table 2-6.

Table 2-4 Operation Codes in Byte 2 (05xx, 15xx, 0Dxx, 1Dxx, Bxxx, Cxxx, Dxxx, Exxx, Fxxx)

HI	LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	
0	See Tbl. 2-6*					CMP #xx:8	CMP #xx:16	MOV #xx:8	MOV #xx:16	ADD:Q #1	ADD:Q #2			ADD:Q #1	ADD:Q #2			
1						CLR	NEG	NOT	TST	TAS	SHAL	SHAR	SHLL	SHLR	ROTL	ROTR	ROTXL	ROTXR
2						ADD												
3						SUB							SUB\$					
4						OR								BSET	(Register indirect specification of bit number)			
5						AND								BCLR	(Register indirect specification of bit number)			
6						XOR								BNOT	(Register indirect specification of bit number)			
7						CMP								BTST	(Register indirect specification of bit number)			
8						MOV (load)								LDC				
9						MOV (store)								STC				
A						ADDX								MULXU				
B						SUBX								DIVXU				
C														BSET	(Immediate specification of bit number)			
D														BCLR	(Immediate specification of bit number)			
E														BNOT	(Immediate specification of bit number)			
F														BTST	(Immediate specification of bit number)			

Note: * The operation code is in byte 3, given in Table 2-6.

Table 2-5 Operation Codes in Byte 2 (04xx, 0Cx_x)

HI 0	LO 0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
1																
2																
3																
4																
5																
6																
7																
8																
9																
A																
B																
C																
D																
E																
F																

Table 2-6 Operation Codes in Bytes 2 and 3 (11xx, 01xx, 06xx, 07xx, xx00xx)

	LO	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																	
1					PRTD #xx:8					PRTS			PRTD #xx:16				
2																	
3																	
4																	
5																	
6																	
7																	
8	R0	1	R1	1	R2	1	R3	1	R4	1	R5	1	R6	1	R7		
9							MOVTP										
A							DADD										
B							DSUB						SCB				
C							PJMP @Rn						R0	1	R1	1	R7
D							JMP @Rn						PJSR @Rn				
E							JMP @(d:8,Rn)						JSR @Rn				
F							JMP @(d:16,Rn)						JSR @(d:8,Rn)				

2.5 Condition Code Changes

The changes in the condition code bits occurring after the execution of each CPU instruction are summarized in Tables 2-7 (1) to (4). The following notation is used.

Sm: Most significant bit of source operand

Dm: Most significant bit of destination
operand

Rm: Most significant bit of result

Dn: Bit n of destination operand

—: Not changed.

↑: Changed according to the result of the
instruction.

0: Always cleared to "0."

1: Always set to "1."

Δ: Handling depends on the operand.

Instruction	N	Z	V	C	Definitions
ADD	↑	↑	↑	↑	
ADDS	—	—	—	—	
ADDX	↑	↑	↑	↑	N = ~ Z = ~ V = ~ C = ~

Table 2-7 Condition Code Changes (1)

Instruction	N	Z	V	C	Definitions
ADD	↑	↑	↑	↑	$N = R_m$ $Z = \overline{R_m} \cdot \overline{R_{m-1}} \dots \overline{R_0}$ $V = S_m \cdot D_m \cdot \overline{R_m} + \overline{S_m} \cdot \overline{D_m} \cdot R_m$ $C = S_m \cdot D_m + D_m \cdot \overline{R_m} + S_m \cdot \overline{R_m}$
ADDS	—	—	—	—	
ADDX	↑	↑	↑	↑	$N = R_m$ $Z = Z' \cdot \overline{R_m} \dots \overline{R_0}^*$ $V = S_m \cdot D_m \cdot \overline{R_m} + \overline{S_m} \cdot \overline{D_m} \cdot R_m$ $C = S_m \cdot D_m + D_m \cdot \overline{R_m} + S_m \cdot \overline{R_m}$
AND	↑	↑	0	—	$N = R_m$ $Z = \overline{R_m} \cdot \overline{R_{m-1}} \dots \overline{R_0}$
ANDC	Δ	Δ	Δ	Δ	If CR = SR (CCR): N, Z, V, and C are ANDed with source operand bits 3 to 0. If CR ≠ SR (CCR): N = Rm $Z = R_m \cdot R_{m-1} \dots R_0$ $V = 0$ $C = \text{remains unchanged.}$
BCC	—	—	—	—	
BCLR	—	↑	—	—	$Z = \overline{D_n}$
BNOT	—	↑	—	—	$Z = \overline{D_n}$
BSET	—	↑	—	—	$Z = \overline{D_n}$
BSR	—	—	—	—	
BTST	—	↑	—	—	$Z = \overline{D_n}$
CLR	0	1	0	0	
CMP	↑	↑	↑	↑	$N = R_m$ $Z = \overline{R_m} \cdot \overline{R_{m-1}} \dots \overline{R_0}$ $V = \overline{S_m} \cdot D_m \cdot \overline{R_m} + S_m \cdot \overline{D_m} \cdot R_m$ $C = S_m \cdot D_m + \overline{D_m} \cdot R_m + S_m \cdot R_m$
DADD	—	↑	—	↑	$Z = Z \cdot \overline{R_m} \dots \overline{R_0}$ C = decimal carry
DIVXU	↑	↑	↑	0	$N = R_m$ $Z = \overline{R_m} \cdot \overline{R_{m-1}} \dots \overline{R_0}$ $V = \text{division overflow}$

* Z' is the Z bit before execution.

Table 2-7 Condition Code Changes (2)

Instruction	N	Z	V	C	Definitions
DSUB	—	↑	—	↑	$Z = Z \cdot \overline{Rm} \cdot \dots \cdot \overline{R0}$ C = decimal borrow
EXTS	↑	↑	0	0	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$
EXTU	0	↑	0	0	$Z = \overline{Rm} \cdot Rm-1 \cdot \dots \cdot R0$
JMP	—	—	—	—	
JSR	—	—	—	—	
LDC	Δ	Δ	Δ	Δ	If CR = SR (CCR), then N, Z, V, and C are loaded from the source operand. If CR ≠ SR (CCR), then N, Z, V, and C remain unchanged.
LDM	—	—	—	—	
LINK	—	—	—	—	
MOV	↑	↑	0	—	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$
MOVFPE	—	—	—	—	
MOVTPPE	—	—	—	—	
MULXU	↑	↑	0	0	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$
NEG	↑	↑	↑	↑	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$ $V = Dm \cdot Rm$ $C = Dm + Rm$
NOP	—	—	—	—	
NOT	↑	↑	0	—	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$
OR	↑	↑	0	—	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$
ORC	Δ	Δ	Δ	Δ	If CR = SR (CCR): N, Z, V, and C are ORed with source operand bits 3 to 0. If CR ≠ SR (CCR): $N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdot \dots \cdot \overline{R0}$ $V = 0$ $C = \text{remains unchanged.}$

Table 2-7 Condition Code Changes (3)

Instruction N Z V C Definitions

PJMP	— — — —	
PJSR	— — — —	
PRTS	— — — —	
PRTD	— — — —	
ROTL	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = Dm
ROTR	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = D0
ROTXL	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = Dm
ROTXR	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = D0
RTD	— — — —	
RTE	↑ ↓ ↑ ↓	Popped from the stack.
RTS	— — — —	
SCB	— — — —	
SHAL	↑ ↓ ↑ ↓	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ V = $D_m \cdot \overline{D_{m-1}} + \overline{D_m} \cdot D_{m-1}$ C = Dm
SHAR	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = D0
SHLL	↑ ↓ 0 ↑	N = Rm Z = $\overline{R_m} \cdot \overline{R_{m-1}} \dots \cdot \overline{R_0}$ C = Dm

Table 2-7 Condition Code Changes (4)

Instruction	N	Z	V	C	Definitions
SHLR	0	↑	0	↑	$Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$ $C = D0$
SLEEP	—	—	—	—	
STC	—	—	—	—	
STM	—	—	—	—	
SUB	↓	↑	↓	↑	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$ $V = \overline{Sm} \cdot Dm \cdot \overline{Rm} + Sm \cdot \overline{Dm} \cdot Rm$ $C = Sm \cdot \overline{Dm} + Dm \cdot Rm + Sm \cdot Rm$
SUBS	—	—	—	—	
SUBX	↓	↑	↓	↑	$N = Rm$ $Z = Z' \cdot \overline{Rm} \cdots \overline{R0}^*$ $V = \overline{Sm} \cdot Dm \cdot \overline{Rm} + Sm \cdot \overline{Dm} \cdot Rm$ $C = Sm \cdot \overline{Dm} + \overline{Dm} \cdot Rm + Sm \cdot Rm$
SWAP	↓	↑	0	—	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$
TAS	↓	↑	0	0	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$
TRAPA	—	—	—	—	
TRAP/V\$	—	—	—	—	
TST	↓	↑	0	0	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$
UNLK	—	—	—	—	
XCH	—	—	—	—	
XOR	↓	↑	0	—	$N = Rm$ $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$
XORC	Δ	Δ	Δ	Δ	If CR = SR (CCR): N, Z, V, and C are exclusive-ORed with source operand bits 3 to 0. If CR ≠ SR (CCR): N = Rm $Z = \overline{Rm} \cdot \overline{Rm-1} \cdots \overline{R0}$ $V = 0$ C = remains unchanged.

* Z' is the Z bit before execution.

2.6 Instruction Execution Cycles

Tables 2-8 (1) through (6) list the number of cycles required by the CPU to execute each instruction in each addressing mode.

The meaning of the symbols in the tables is explained below. The values of I, J, and K are used to calculate the number of execution cycles when off-chip memory is accessed for an instruction fetch or operand read/write. The formulas for these calculations are given next. Different formulas are used for the H8/532, H8/534, H8/536, H8/520 which have an 8-bit external bus, and the H8/510, H8/570 which have a 16-bit external bus.

2.6.1 Calculation of Instruction Execution States (H8/532, H8/534, H8/536, H8/520)

One state is one cycle of the system clock (\emptyset). If $\emptyset = 10\text{MHz}$, then one state = 100ns.

Instruction fetch	Operand read/write	Number of states
On-chip memory ^{*1}	On-chip memory, general register, or no operand	(Value in Table 2-8) + (Value in Table 2-9)
	On-chip supporting module or off-chip memory ^{*2}	Byte (Value in Table 2-8) + (Value in Table 2-9) + I Word (Value in Table 2-8) + (Value in Table 2-9) + 2 I
Off-chip memory ^{*2}	On-chip memory, general register, or no operand	(Value in Table 2-8) + 2(J + K)
	On-chip supporting module or off-chip memory ^{*2}	Byte (Value in Table 2-8) + I + 2(J + K) Word (Value in Table 2-8) + 2(I + J + K)

*1 When the instruction is fetched from on-chip memory (ROM or RAM), the number of execution states varies by 1 or 2 depending of whether the instruction is stored at an even or odd address. This difference must be noted when software is used for timing, and in other cases in which the exact number of states is important.

*2 If wait states are inserted in access to external memory, add the necessary number of cycles.

2.6.2 Tables of Instruction Execution Cycles

Tables 2-8 (1) through (6) should be read as shown below:

J + K: Number of instruction fetch cycles.

I: Total number of bytes written and read when operand is in memory.

Instruction	I	J	K	Addressing mode							
				Rn	@Rn	(d:8,Rn)	(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16
ADD.B	1	1		2	5	5	6	5	6	5	6
ADD.W	2	1		2	5	5	6	5	6	5	6
ADD:Q.B	2	1		2	7	7	8	7	8	7	8
ADD:Q.W	4	1		2	7	7	8	7	8	7	8
DADD				2	4						

Shading in the I column means the operand cannot be in memory.

Shading indicates addressing modes that cannot be used with this instruction.

2.6.3 Examples of Calculation of Number of States Required for Execution (H8/532, H8/534, H8/536, H8/520)

(Example 1) ADD:G.W @R0, R1: instruction fetch from on-chip memory

Operand Read/Write	Start addr.	Address	Assembler notation Code	Mnemonic	Table 2-8 + Table 2-9	Number of states
On-chip memory or general register	Even	H'0100	H'D821	ADD @R0, R1	5 + 1	6
	Odd	H'0101	H'D821	ADD @R0, R1	5 + 0	5

(Example 2) JSR @R0: instruction fetch from on-chip memory
(stack in external memory)

Branch addr.	Address	Assembler notation Code	Mnemonic	Table 2-8 + Table 2-9 + 2I	Number of states
Even	H'FC00	H'11D8	JSR @R0	9 + 0 + 2 × 2	13
Odd	H'FC01	H'11D8	JSR @R0	9 + 1 + 2 × 2	14

(Example 3) ADD:G.W @R0, R1: instruction fetch from external memory

Operand Read/Write	Address	Assembler notation Code	Mnemonic	Table 2-8 + 2(J + K)	Number of states
On-chip memory or general register	H'9002	H'D821	ADD:G.W @R0, R1	5 + 2 × (1 + 1)	9
On-chip supporting module or external memory	H'9002	H'D821	ADD:G.W @RD, R1	5 + 2 × (2 + 1 + 1)	13

2.6.4 Number of Execution States (H8/510, H8/570)

One state is one cycle of the system clock (\emptyset). If $\emptyset = 10\text{MHz}$ then one state = 100ns.

Instruction fetch	Operand access	Number of states
16-bit bus, 2-state access address space	16-bit bus and 2-state access address space, or general register	(Value in Table 2-8) + (Value in Table 2-9)
	16-bit bus and 3-state access address space	Byte (Value in Table 2-8) + (Value in Table 2-9) + I Word (Value in Table 2-8) + (Value in Table 2-9) + I/2
	8-bit bus and 2-state access address space	Byte (Value in Table 2-8) + (Value in Table 2-9) Word (Value in Table 2-8) + (Value in Table 2-9) + I
	8-bit bus and 3-state access address space, or on-chip register field	Byte (Value in Table 2-8) + (Value in Table 2-9) + I Word (Value in Table 2-8) + (Value in Table 2-9) + 2I
16-bit bus, 3-state access address space	16-bit bus and 2-state access address space, or general register	(Value in Table 2-8) + (Value in Table 2-9) + (J + K)/2
	16-bit bus and 3-state access address space	Byte (Value in Table 2-8) + (Value in Table 2-9) + I + (J + K)/2 Word (Value in Table 2-8) + (Value in Table 2-9) + (I + J + K)/2
	8-bit bus and 2-state access address space	Byte (Value in Table 2-8) + (Value in Table 2-9) + (J + K)/2 Word (Value in Table 2-8) + (Value in Table 2-9) + I + (J + K)/2
	8-bit bus and 3-state access address space, or on-chip register field	Byte (Value in Table 2-8) + (Value in Table 2-9) + I + (J + K)/2 Word (Value in Table 2-8) + (Value in Table 2-9) + 2I + (J + K)/2

Instruction fetch	Operand access	Number of states	
8-bit bus, 2-state access address space	16-bit bus and 2-state access address space, or general register	Byte	(Value in Table 2-8) + J + K
	16-bit bus and 3-state access address space	Word	(Value in Table 2-8) + I/2 + J + K
	8-bit bus and 2-state access address space	Byte	(Value in Table 2-8) + J + K
	Word	(Value in Table 2-8) + I + J + K	
	8-bit bus and 3-state access address space, or on-chip register field	Byte	(Value in Table 2-8) + I + J + K
		Word	(Value in Table 2-8) + 2I + J + K
8-bit bus, 3-state access address space	16-bit bus and 2-state access address space, or general register	Byte	(Value in Table 2-8) + 2(J + K)
	16-bit bus and 3-state access address space	Word	(Value in Table 2-8) + I/2 + 2(J + K)
	8-bit bus and 2-state access address space	Byte	(Value in Table 2-8) + 2(J + K)
	Word	(Value in Table 2-8) + I + 2(J + K)	
	8-bit bus and 3-state access address space, or on-chip register field	Byte	(Value in Table 2-8) + I + 2(J + K)
		Word	(Value in Table 2-8) + 2(I + J + K)

- Notes:
1. When an instruction is fetched from the 16-bit bus access address space, the number of states differs by 1 or 2 depending on whether the instruction is stored at an even or odd address. This point should be noted in software timing routines and other situations in which the precise number of states must be known.
 2. If wait states or T_p states are inserted in access to the 3-state access address space, add the necessary number of states.
 3. When an instruction is fetched from the 16-bit-bus, 3-state access address space, the term $(J + K)/2$ is rounded down to an integer.

2.6.5 Examples of Calculation of Number of States Required for Execution (H8/510, H8/570)

(Example 1) Instruction fetch from 16-bit-bus, 2-state access address space

Operand Read/Write	Start addr.	Assembler notation			Table 2-8 + Table 2-9	Number of states
16-bit-bus, 2-state access address space, or general register	Even	H'0100	D821	ADD @R0, R1	5 + 1	6
	Odd	H'0101	D821	ADD @R0, R1	5 + 0	5

(Example 2) Instruction fetch from 16-bit-bus, 2-state access address space (stack in 8-bit-bus, 3-state access address space)

Branch addr.	Assembler notation			Table 2-8 + Table 2-9 + 2I	Number of states
	Address	Code	Mnemonic		
Even	H'FC00	11D8	JSR @R0	9 + 0 + 2 × 2	13
Odd	H'FC01	11D8	JSR @R0	9 + 1 + 2 × 2	14

(Example 3) Instruction fetch from 8-bit-bus, 3-state access address space

Operand Read/Write	Assembler notation			Table 2-8 + 2(J + K)	Number of states
	Address	Code	Mnemonic		
16-bit-bus, 2-state access address space, or general register	H'9002	D821	ADD @R0, R1	5 + 2 × (1 + 1)	9

(Example 4) Instruction fetch from 16-bit-bus, 2-state access address space

Operand Read/Write	Start addr.	Assembler notation			Table 2-8 + Table 2-9 + (J + K)/2	Number of states
		Address	Code	Mnemonic		
16-bit-bus, 2-state access address space, or general register	Even	H'0100	D821	ADD @R0, R1	5 + 1 + (1 + 1)/2	7
	Odd	H'0101	D821	ADD @R0, R1	5 + 0 + (1 + 1)/2	6

Table 2-8 Instruction Execution Cycles (1)

Instruction	I	J	K	Addressing mode									
				Rn	@Rn	(@d:8,Rn)	(@d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16
ADD:G.B	1	1	2	5	5	6	5	6	5	6	3		
ADD:G.W	2	1	2	5	5	6	5	6	5	6			4
ADD:Q.B	2	1	2	7	7	8	7	8	7	8			
ADD:Q.W	4	1	2	7	7	8	7	8	7	8			
ADDS.B	1	1	3	5	5	6	5	6	5	6	3		
ADDS.W	2	1	3	5	5	6	5	6	5	6			4
ADDX.B	1	1	2	5	5	6	5	6	5	6	3		
ADDX.W	2	1	2	5	5	6	5	6	5	6			4
AND.B	1	1	2	5	5	6	5	6	5	6	3		
AND.W	2	1	2	5	5	6	5	6	5	6			4
ANDC			1										5 9
BCLR.B	2	1	4	7	7	8	7	8	7	8			
BCLR.W	4	1	4	7	7	8	7	8	7	8			
BNOT.B	2	1	4	7	7	8	7	8	7	8			
BNOT.W	4	1	4	7	7	8	7	8	7	8			
BSET.B	2	1	4	7	7	8	7	8	7	8			
BSET.W	4	1	4	7	7	8	7	8	7	8			
BTST.B	1	1	3	5	5	6	5	6	5	6			
BTST.W	2	1	3	5	5	6	5	6	5	6			
CLR.B	1	1	2	5	5	6	5	6	5	6			
CLR.W	2	1	2	5	5	6	5	6	5	6			
CMP:G.B	1	1	2	5	5	6	5	6	5	6	3		
CMP:G.W	2	1	2	5	5	6	5	6	5	6			4
CMP:G.B #xx:8,<EA>	1	2		6	6	7	6	7	6	7			
CMP:G.B #xx:16,<EA>	2	3		7	7	8	7	8	7	8			

Table 2-8 Instruction Execution Cycles (2)

Instruction	I	J	K	Addressing mode									
				Rn	@Rn	(d:8,Rn)	(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16
CMP:E #xx:8,Rd			0									2	
CMP:I #xx:16,Rd			0									3	
DADD			2	4									
DIVXU.B	1	1	20	23	23	24	23	24	23	24	23	24	21
DIVXU.W	2	1	26	29	29	30	29	30	29	30	29	30	28
DSUB			2	4									
EXTS			1	3									
EXTU			1	3									
LDC.B	1	1	3	6	6	7	6	7	6	7	4		
LDC.W	2	1	4	7	7	8	7	8	7	8		6	
MOV.B	1	1	2	5	5	6	5	6	5	6	5	6	3
MOV.W	2	1	2	5	5	6	5	6	5	6	5	6	4
MOV.B #xx:8,<EA>	1	2		7	7	8	7	8	7	8			
MOV.W #xx:16,<EA>	2	3		8	8	9	8	9	8	9			
MOV:E #xx:8,Rd			0									2	
MOV:I #xx:16,Rd			0									3	
MOV:L.B @aa:8,Rd	1	0									5		
MOV:L.W @aa:8,Rd	2	0									5		
MOV:S.B Rs,@aa:8	1	0									5		
MOV:S.W Rs,@aa:8	2	0									5		
MOV:F.B @(d:8, R6), Rd	1	0			5								
MOV:F.W @(d:8, R6), Rd	2	0			5								
MOV:F.B Rs, @(d:8, R6)	1	0			5								
MOV:F.W Rs, @(d:8, R6)	2	0			5								

Table 2-8 Instruction Execution Cycles (3)

Instruction	I	J	K	Addressing mode												
				Rn	@Rn	@(d:8,Rn)	@(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16			
MOVFPE ^{*1} * ₂	0	2		13 20	13 20	14 21	13 20	14 21	13 20	14 21	13 20	14 21				
MOVTPE ^{*1} * ₂	0	2		13 20	13 20	14 21	13 20	14 21	13 20	14 21	13 20	14 21				
MULXU.B	1	1	16	19	19	20	19	20	19	20	19	20	18			
MULXU.W	2	1	23	25	25	26	25	26	25	26	25	26	25			25
NEG.B	2	1	2	7	7	8	7	8	7	8	7	8				
NEG.W	4	1	2	7	7	8	7	8	7	8	7	8				
NOT.B	2	1	2	7	7	8	7	8	7	8	7	8				
NOT.W	4	1	2	7	7	8	7	8	7	8	7	8				
OR.B	1	1	2	5	5	6	5	6	5	6	5	6	3			
OR.W	2	1	2	5	5	6	5	6	5	6	5	6	4			
ORC			1										5	9		
ROTL.B	2	1	2	7	7	8	7	8	7	8	7	8				
ROTL.W	4	1	2	7	7	8	7	8	7	8	7	8				
ROTR.B	2	1	2	7	7	8	7	8	7	8	7	8				
ROTR.W	4	1	2	7	7	8	7	8	7	8	7	8				
ROTXL.B	2	1	2	7	7	8	7	8	7	8	7	8				
ROTXL.W	4	1	2	7	7	8	7	8	7	8	7	8				
ROTXR.B	2	1	2	7	7	8	7	8	7	8	7	8				
ROTXR.W	4	1	2	7	7	8	7	8	7	8	7	8				
SHAL.B	2	1	2	7	7	8	7	8	7	8	7	8				
SHAL.W	4	1	2	7	7	8	7	8	7	8	7	8				
SHAR.B	2	1	2	7	7	8	7	8	7	8	7	8				
SHAR.W	4	1	2	7	7	8	7	8	7	8	7	8				
SHLL.B	2	1	2	7	7	8	7	8	7	8	7	8				
SHLL.W	4	1	2	7	7	8	7	8	7	8	7	8				

*₁ These instructions are not available on H8/520.

*₂ MOVFPE and MOVTPE are executed synchronous with the E-clock, so the number of execution states will change depending on timing of the execution.

Table 2-8 Instruction Execution Cycles (4)

Instruction	I	J	K	Addressing mode											
				Rn	@Rn	@(d:8,Rn)	@(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16		
SHLR.B	2	1	2	7	7	8	7	8	7	8	7	8			
SHLR.W	4	1	2	7	7	8	7	8	7	8	7	8			
STC.B	1	1	4	7	7	8	7	8	7	8	7	8			
STC.W	2	1	4	7	7	8	7	8	7	8	7	8			
SUB.B	1	1	2	5	5	6	5	6	5	6	5	6	3		
SUB.W	2	1	2	5	5	6	5	6	5	6	5	6	4		
SUBS.B	1	1	3	5	5	6	5	6	5	6	5	6	3		
SUBS.W	2	1	3	5	5	6	5	6	5	6	5	6	4		
SUBX.B	1	1	2	5	5	6	5	6	5	6	5	6	3		
SUBX.W	2	1	2	5	5	6	5	6	5	6	5	6	4		
SWAP			1	3											
TAS	2	1	4	7	7	8	7	8	7	8	7	8			
TST.B	1	1	2	5	5	6	5	6	5	6	5	6			
TST.W	2	1	2	5	5	6	5	6	5	6	5	6			
XCH			1	4											
XOR.B	1	1	2	5	5	6	5	6	5	6	5	6	3		
XOR.W	2	1	2	5	5	6	5	6	5	6	5	6	4		
XORC			1										5	9	

*

DIVXU.B Zero divide, minimum mode	6 7	1	20	23	23	24	23	24	23	24	21				
DIVXU.B Zero divide, maximum mode	10 11	1	25	28	28	29	28	29	28	29	21				
DIVXU.W Zero divide, minimum mode	6 8	1	20	23	23	24	23	24	23	24	27				
DIVXU.W Zero divide, maximum mode	10 12	1	25	28	28	29	28	29	28	29	27				
DIVXU.B Overflow	1	1	8	11	11	12	11	12	11	12	9				
DIVXU.W Overflow	2	1	8	11	11	12	11	12	11	12	10				

* For register and immediate operands



For memory operand

Table 2-8 Instruction Execution Cycles (5)

Instruction	(Condition)	Execution cycles	I	J + K
BCC d:8	Condition false, branch not taken	3	2	2
	Condition true, branch taken	7		5
BCC d:16	Condition false, branch not taken	3	3	3
	Condition true, branch taken	7		6
BSR	d:8	9	2	4
	d:16	9		2
JMP	@aa:16	7	5	5
	@Rn	6		5
	@(d:8, Rn)	7		5
	@(d:16, Rn)	8		6
JSR	@aa:16	9	2	5
	@Rn	9		2
	@(d:8, Rn)	9		2
	@(d:16, Rn)	10		6
LDM		6+4n*	2n	2
LINK	#xx:8	6	2	2
	#xx:16	7	2	3
NOP		2		1
RTD	#xx:8	9	2	4
	#xx:16	9		5
RTE	Minimum mode	13	4	4
	Maximum mode	15		6
RTS		8	2	4
SCB	Condition false, branch not taken	3	3	3
	Count = -1, branch not taken	4		3
	Other than the above, branch taken	8		6
SLEEP	Cycles preceding transition to power-down mode	2		0
STM		6+3n*	2n	2

* n is the number of registers specified in the register list.

Table 2-8 Instruction Execution Cycles (6)

Instruction	(Condition)	Execution cycles	I	J + K
TRAPA	Minimum mode	17	6	4
	Maximum mode	22	10	4
TRAP/VIS	V = 0, trap not taken	3		1
	V = 1, trap taken, minimum mode	18	6	4
	V = 1, trap taken, maximum mode	23	10	4
UNLK		5	2	1
PJMP	@aa:24	9		6
	@Rn	8		5
PJSR	@aa:24	15	4	6
	@Rn	13	4	5
PRTS		12	4	5
PRTD	#xx:8	13	4	5
	#xx:16	13	4	6

Table 2-9 (a) Adjusted value (branch instructions)

Instruction	Address	Adjusted value
BSR, JMP, JSR, RTS, RTD, RTE	even	0
TRAPA, PJMP, PJSR, PRTS, PRTD	odd	1
Bcc, SCB, TRAP/VIS (When branches)	even	0
	odd	1

Table 2-9 (b) Adjusted value (Other instructions by addressing modes)

Instructor	Start address	Rn	@Rn	@(t:8,Rn)	@(d:16,Rn)	@-Rn	@Rn+	@aa:8	@aa:16	#xx:8	#xx:16
MOV.B #xx:8, <EA>	even		1	1	1	1	1	1	1		
MOVTPE, MOVFPE	odd		1	1	1	1	1	1	1		
MOV.W #xx:16, <EA>	even		2	0	2	2	2	0	2		
	odd		0	2	0	0	0	2	0		
Instructions other than above	even	0	1	0	1	1	1	0	1	0	0
	odd	0	0	1	0	0	0	1	0	0	0

2.7 Invalid Instruction Exception Handling

Handling of Undefined Instruction Codes: When an attempt is made to execute an instruction with an undefined bit pattern (undefined operation code or addressing mode), the H8/500 initiates invalid instruction exception handling. "Undefined" means that the corresponding entry in the operation code map is blank.

Table 2-10 lists the invalid instruction codes. In addition to the instruction codes listed, there are invalid combinations of addressing modes. These do not cause an invalid instruction exception, so proper handling is not assured.

Table 2-10 Instruction Codes Causing Invalid Instruction Exceptions (a)

Effective address		Operation code
	H'0B	
	H'16	
	H'1B	
Register		H'01 to H'07
	Rn	H'0A, H'0B
		H'0E, H'0F
Memory	@Rn	H'01 to H'03
	@(d:8, Rn) @(d:16, Rn)	H'0A, H'0B
	@-Rn	H'0E, H'0F
	@aa:8	H'10 to H'12
Immediate	#xx:8	H'00 to H'0F
		H'10 to H'1F
		H'78 to H'7F
		H'90 to H'9F
		H'C0 to H'CF
		H'D0 to H'DF
		H'E0 to H'EF
		H'F0 to H'FF

Table 2-10 Instruction Codes Causing Invalid Instruction Exceptions (b)

Operation code	Effective address
H'01	H'00 to H'0F
H'06	H'10 to H'13
H'07	H'15 to H'18
H'11	H'1A, H'1B H'1D to H'1F H'20 to H'7F H'88 to H'8F H'98 to H'9F H'A8 to H'AF

Table 2-10 Instruction Codes Causing Invalid Instruction Exceptions (c)

	Effective address	Prefix code	Operation code
Register or memory	Rn	H'00	H'00 to H'0F
	@Rn		H'10 to H'13
	@(d:8, Rn), @(d:16, Rn)		H'15 to H'18
	@-Rn, @Rn+		H'1A, H'1B
	@aa:8, @aa:16		H'1D to H'1F H'20 to H'7F H'88 to H'8F H'98 to H'9F H'A8 to H'AF

The following additional instruction codes are invalid in minimum mode.

Table 2-10 Instruction Codes Causing Invalid Instruction Exceptions (d)

Operation code	Effective address
H'03	
H'13	
H'11	H'14, H'19 H'1C H'C0 to H'CF

Section 3 State Transitions

The CPU operates in five main states: the program execution state, exception handling state, bus-released state, reset state, and power-down state. Figure 3-1 shows the transitions among these states.

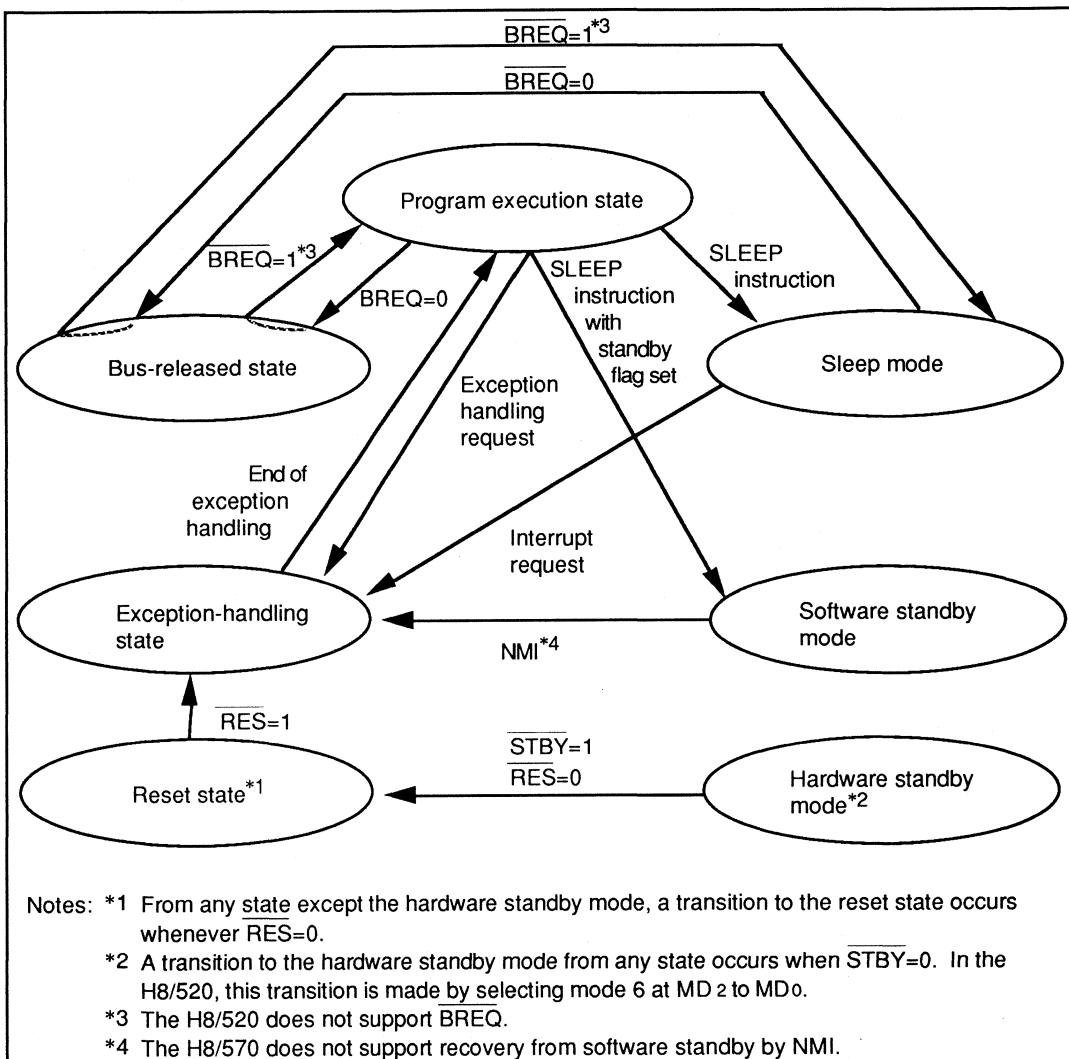


Figure 3-1 State Transitions

3.1 Program Execution State

In this state the CPU executes program instructions in normal sequence.

3.2 Exception Handling State

3.2.1 Types of Exception Handling and Their Priorities

As indicated in Table 3-1 (a) and (b), exception handling can be initiated by a reset, address error, trace, interrupt, or instruction. An instruction initiates exception handling if the instruction is an invalid instruction, a trap instruction, or a DIVXU instruction with zero divisor. Exception handling begins with a hardware exception-handling sequence which prepares for the execution of a user-coded software exception-handling routine.

There is a priority order among the different types of exceptions, as shown in Table 3-1 (a). If two or more exceptions occur simultaneously, they are handled in their order of priority. An instruction exception cannot occur simultaneously with other types of exceptions.

Table 3-1 (a) Exceptions and Their Priority

Priority	Exception type	Source	Detection timing	Start of exception-handling sequence
High	Reset	External, internal	\overline{RES} Low-to-High transition	Immediately
	Address error	Internal	Instruction fetch or data read/write bus cycle	End of instruction execution
	Trace	Internal	End of instruction execution, if T = "1" in status register	End of instruction execution
Low	Interrupt	External, internal	End of instruction execution or end of exception-handling sequence	End of instruction execution

Table 3-1 (b) Instruction Exceptions

Exception type	Start of exception-handling sequence
Invalid instruction	Attempted execution of instruction with undefined code
Trap instruction	Started by execution of trap instruction
Zero divide	Attempted execution of DIVXU instruction with zero divisor

3.2.2 Exception Handling Sources and Vector Table

Figure 3-2 classifies the sources of exception handling. Each source has a different vector address, as listed in Table 3-2. The vector addresses differ between the minimum and maximum modes.

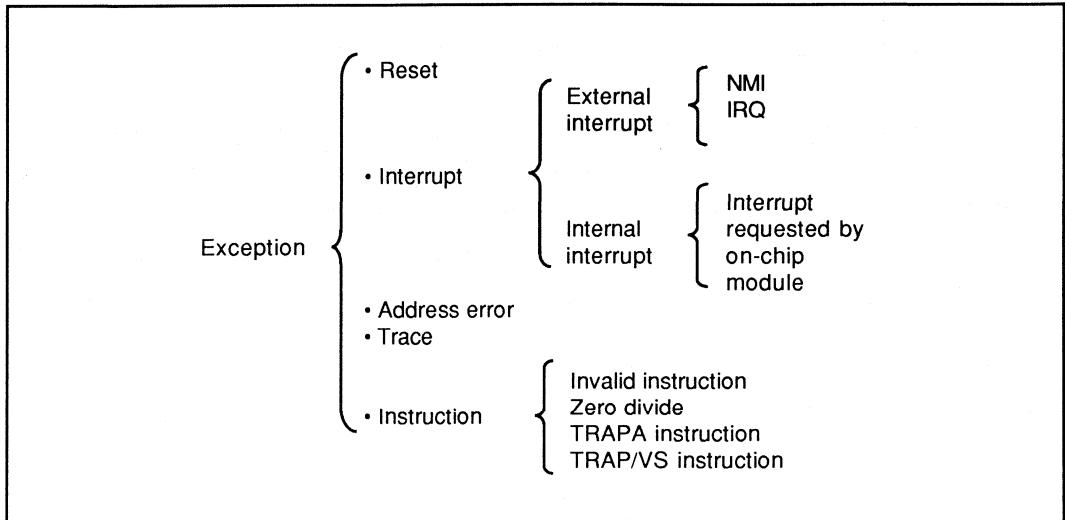


Figure 3-2 Sources of Exception Handling

Table 3-2 Exception Vector Table

Type of exception	Minimum mode	Maximum mode
Reset (initialize PC)	H'0000 to H'0001	H'0000 to H'0003
— (reserved for system)	H'0002 to H'0003	H'0004 to H'0007
Invalid instruction	H'0004 to H'0005	H'0008 to H'000B
DIVXU instruction (zero divide)	H'0006 to H'0007	H'000C to H'000F
TRAP/VС instruction	H'0008 to H'0009	H'0010 to H'0013
—	H'000A to H'000B	H'0014 to H'0017
— (reserved for system)	H'000C to H'000D	H'0018 to H'001B
—	H'000E to H'000F	H'001C to H'001F
Address error	H'0010 to H'0011	H'0020 to H'0023
Trace	H'0012 to H'0013	H'0024 to H'0027
— (reserved for system)	H'0014 to H'0015	H'0028 to H'002B
Nonmaskable external interrupt (NMI)	H'0016 to H'0017	H'002C to H'002F
	H'0018 to H'0019	H'0030 to H'0033
— (reserved for system)	to H'001E to H'001F*	to H'003C to H'003F*
TRAPA instruction (16 factors)	H'0020 to H'0021	H'0040 to H'0043
	to H'003E to H'003F	to H'007C to H'007F
External and	H'0040 to H'0041	H'0080 to H'0083
Internal interrupt	to H'009E to H'009F	to H'013C to H'013F

Note: 1. In maximum mode the exception vector table is located in page 0.

2. Each products have different vector table. See the *H8 Hardware Manual* for details.

* Assigned to ISP address error in the H8/570.

3.2.3 Exception Handling Operation

When exception handling is started by a source other than a reset, in the minimum mode the program counter (PC) and status register (SR) are pushed onto the stack; in the maximum mode the code page register (CP), PC, and SR are pushed onto the stack. Then the trace (T) bit in the status register is cleared to "0," the address of the pertinent exception handling routine is read from the exception vector table, and execution branches to that address.

A reset is handled as follows. When the RES pin goes Low, the CPU waits for the RES pin to go High, then latches the value at the mode input pins in the mode select bits (MDS0 to MDS2) of the mode control register (MDCR). Next the CPU reads the address of the reset handling routine from the exception vector table and executes the program at that address.

3.3 Bus-Released State

When it receives a bus request (BREQ) signal* from an external device, the CPU waits until the end of a machine cycle, then releases the bus.

To notify the external device that it has released the bus, the CPU responds to the BREQ signal by asserting a Low BACK signal. When it receives the BACK signal, the device that requested the bus becomes the bus master and can use the address bus, data bus, and control bus.

* The H8/520 does not support the BREQ signal.

3.4 Reset State

A reset has the highest exception handling priority. A reset provides a way to initialize the system at power-up or when recovering from a fatal error.

When the RES pin goes Low, whatever process is being executed is halted and the microcomputer unit enters the reset state.

A reset clears the T bit (bit 15) of the status register (SR) to "0" to disable the trace mode, and sets the interrupt mask level in I₂ to I₀ (SR bits 10 to 8) to 7, the highest level. In the reset state all interrupts are disabled, including the nonmaskable interrupt (NMI).

When the RES pin returns from Low to High, the microcomputer unit comes out of the reset state and begins executing the reset exception routine.

3.5 Power-Down State

In the power-down state some or all of the clock signals are stopped to conserve power. There are three power-down modes. Table 3-1 describes the state of the CPU and the on-chip supporting functions in each mode.

Table 3-3 Power-Down Modes

Mode	Clock	Supporting CPU functions and on-chip RAM			Recovery methods
Sleep	Runs	Halts	Run	Held	Interrupt—Interrupt is accepted and interrupt handling begins. <u>RES</u> —Transition to reset state <u>STBY</u> ^{*2} —Transition to hardware standby mode
Software standby	Halts	Halts	Halt and initialized	Held	NMI—NMI starts clock; NMI exception handling starts automatically after time set in watchdog timer <u>RES</u> —Clock starts, followed by transition to reset state. <u>STBY</u> ^{*2} —Hardware standby mode.
Hardware standby	Halts	Halts	Halt and initialized	Held ^{*1}	High input at <u>STBY</u> pin ^{*3} and Low input at <u>RES</u> pin followed, after clock settling time, by High input at <u>RES</u> pin initiates reset exception handling routine.

- Notes:
1. Only on-chip RAM contents are held.
 2. In the H8/520, select mode 6 at MD2 to MD0.
 3. In the H8/520, select mode 1, 2, 3, 4, or 7 at MD2 to MD0.

3.5.1 Sleep Mode

Execution of the SLEEP instruction normally causes a transition to the sleep mode. CPU operation halts immediately after execution of the SLEEP instruction, but the CPU register contents remain unchanged. The on-chip supporting functions, in particular the clock, continue to operate.

The CPU "wakes up" from the sleep mode when it receives an exception handling request such as a reset or an interrupt of an acceptable level. The CPU then returns via the exception-handling state to the program execution state.

3.5.2 Software Standby Mode

When the software standby (SSBY) bit in the standby control register (SBYCR)* is set to "1," execution of a SLEEP instruction causes a transition to the software standby mode.

In this mode the CPU, the clock, and the other on-chip supporting functions all stop operating. The on-chip supporting modules are reset, but as long as a minimum voltage level is maintained the contents of CPU registers and on-chip RAM remains unchanged. The status of I/O ports also remains unchanged.

A reset or nonmaskable interrupt is required to recover from the software standby mode. The CPU returns via the exception-handling state to the program execution state. (The H8/570 recovers from software standby mode by reset only. Program execution restarts after the reset exception-handling sequence.)

If a Low STBY signal is received in the software standby mode, the mode changes to the hardware standby mode.

* See the *H8/500 Hardware Manual*.

3.5.3 Hardware Standby Mode

Input of a Low STBY signal causes a transition to the hardware standby mode.

In this mode, as in the software standby mode, all operations halt.

All clock signals stop and the on-chip supporting modules are reset, but as long as a minimum voltage level is maintained the contents of on-chip RAM remains unchanged. I/O ports are set to the high-impedance state.

A reset is required to recover from the software standby mode. The CPU returns via the exception-handling state to the program execution state.

Section 4 Basic Operation Timing

The CPU operates on the \emptyset clock, which is created by dividing the clock oscillator output by 2.

One cycle of the \emptyset clock is called a "state". The following sections describe the timing of access to on-chip memory, on-chip supporting modules, and off-chip devices.

4.1 On-Chip Memory Access Timing (H8/532, H8/534, H8/536, H8/520, H8/570)

For high-speed execution, access to on-chip memory (RAM and ROM) is performed in two states. The data width is 16 bits.

Figure 4-1 is a timing chart for access to on-chip memory.

No wait state (T_w) is inserted.

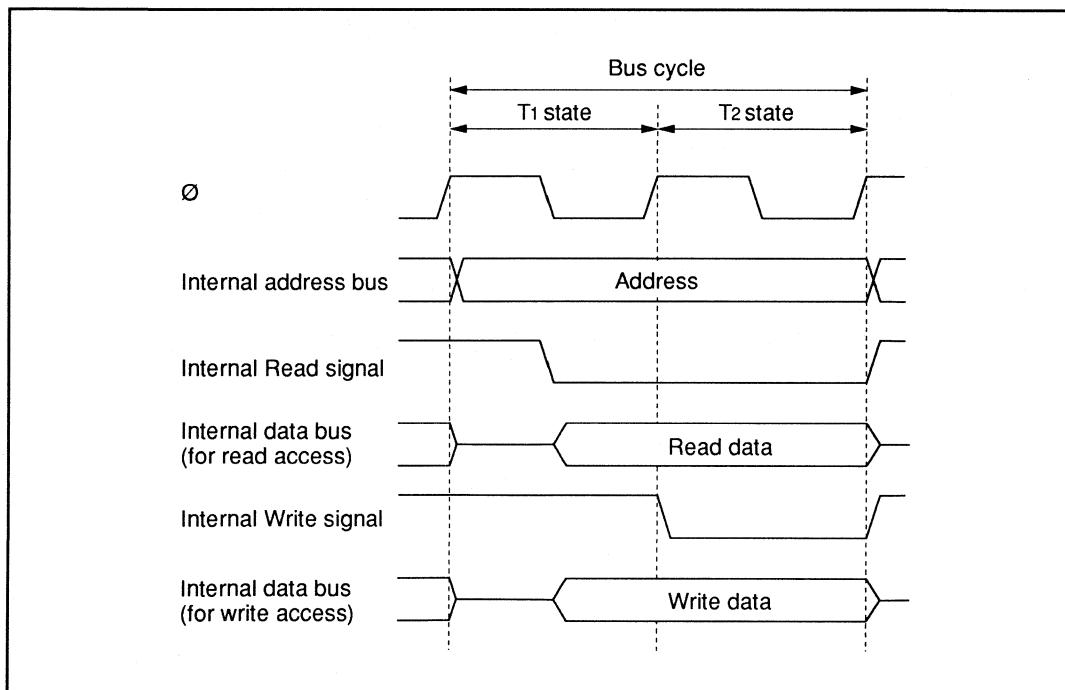


Figure 4-1 On-Chip Memory Access Timing

4.2 On-Chip Supporting Module Access Timing

On-chip supporting modules are accessed in three states as shown in Figure 4-2. The data width is 8 bits.

No wait state (T_w) is inserted.

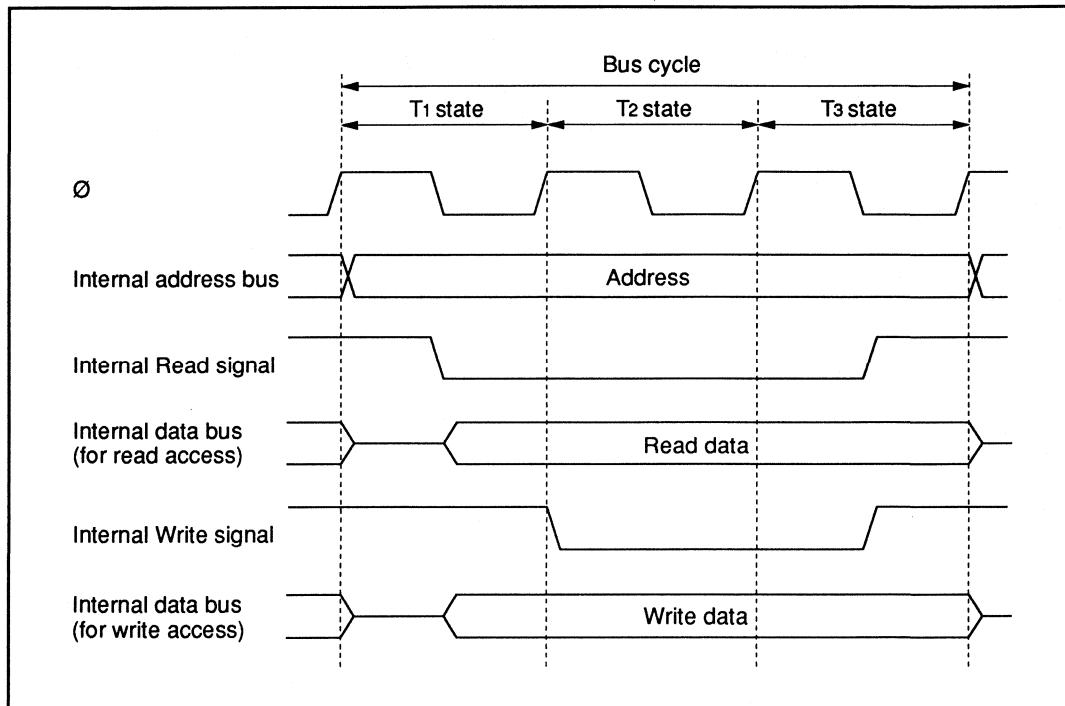


Figure 4-2 On-Chip Supporting Module Access Timing

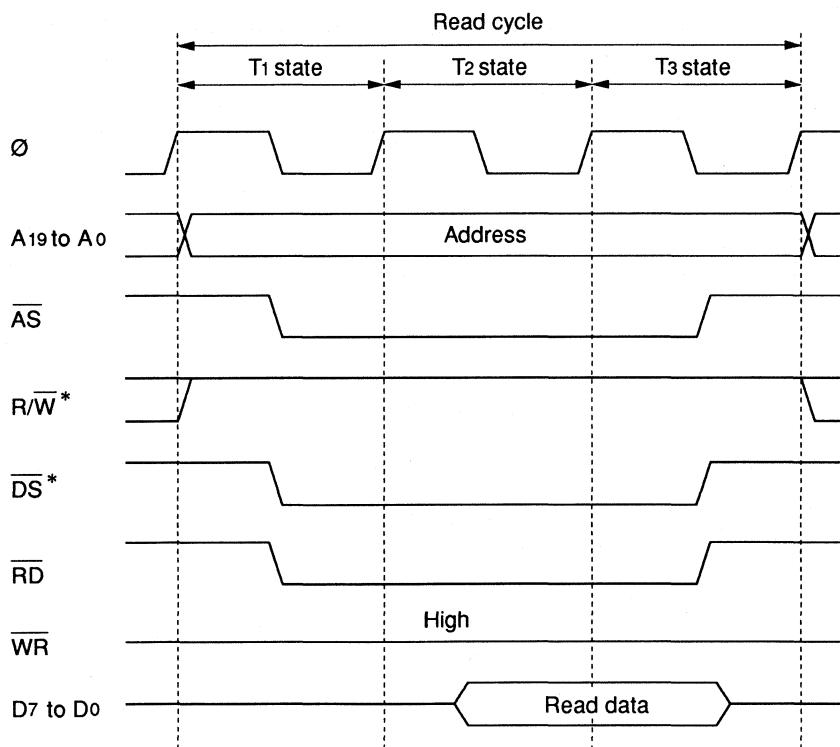
4.3 External Device Access Timing

Off-chip devices are accessed in two or three states as shown in Figures 4-3 and 4-4.

The access timing depends on the particular off-chip device. A wait-state controller can insert additional wait states (T_w) as necessary. (Wait states cannot be inserted in access to the two-state access address space, however, because of the high processing speed.)

For details about the insertion of wait states, see the *H8 Hardware Manual*.

a. Read

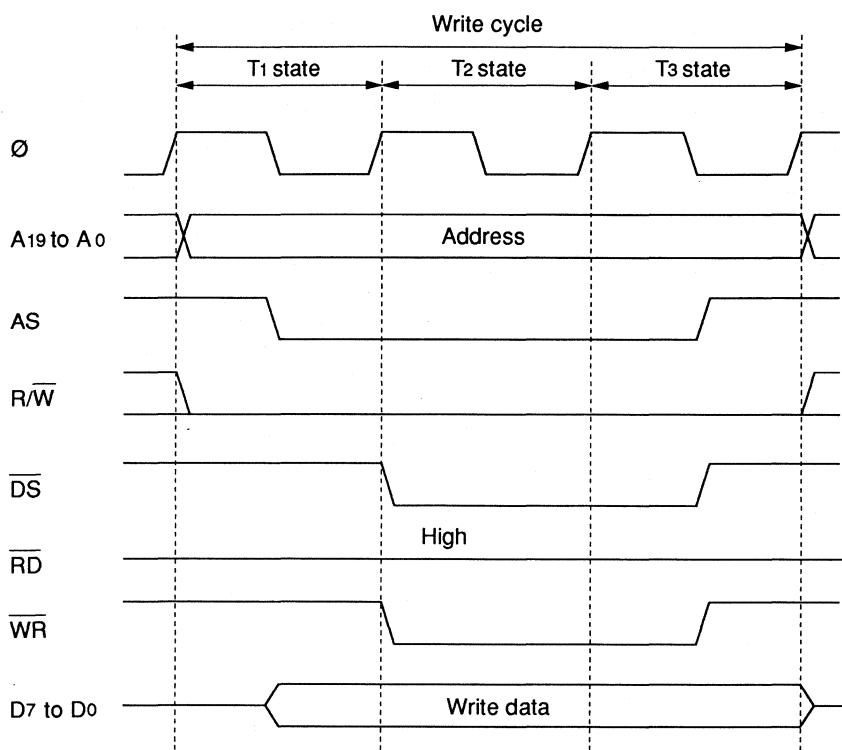


(H8/532, H8/534, H8/536, H8/520)

* The H8/520 does not output R/W and DS bus control signals.

Figure 4-3 (a) External Access Cycle (Read Access)

b. Write



(H8/532, H8/534, H8/536, H8/520)

Figure 4-3 (b) External Access Cycle (Write Access)

a. Two-State-Access Address Space Access Cycle

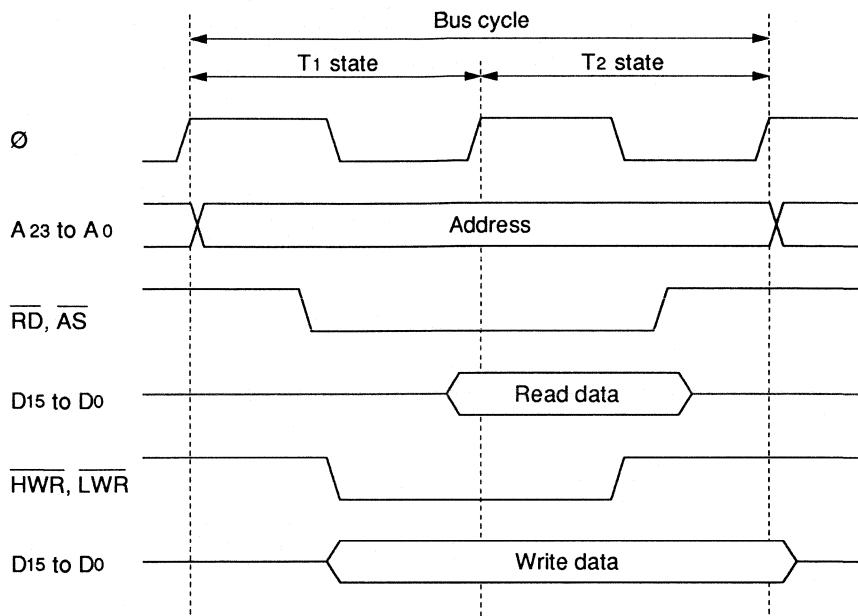


Figure 4-4 External Access Cycle (H8/510, H8/570)

b. Three-State-Access Address Space Access Cycle

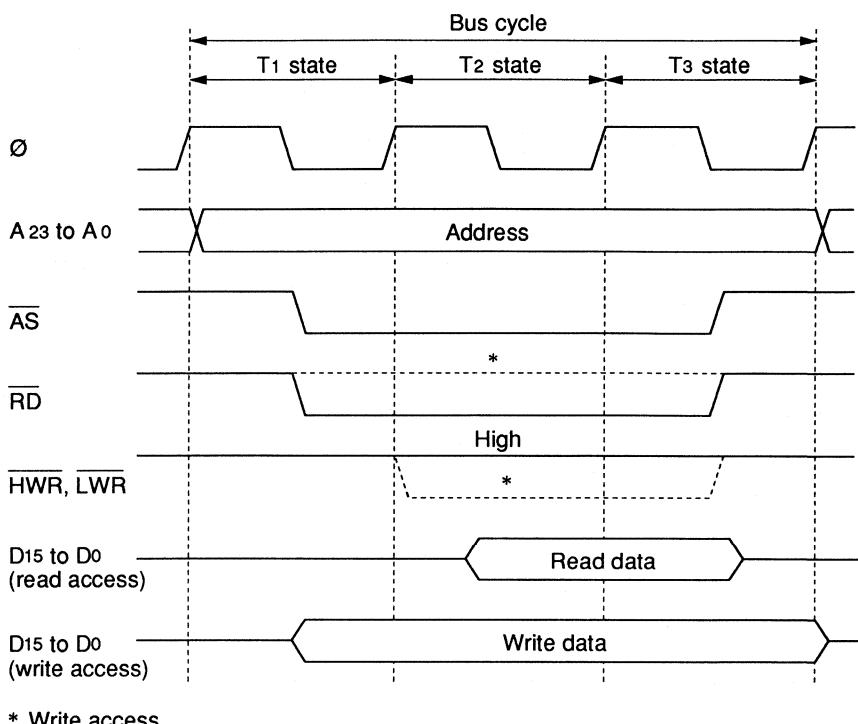


Figure 4-4 External Access Cycle (H8/510, H8/570) (cont)

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